DUAL J-K MASTER SLAVE FLIP-FLOP

GENERAL DESCRIPTION

The MMC 4027 is a monolithic integrated circuit, available in 16-lead dual in-line plastic or ceramic package.

The MMC 4027 is a single monolithic chip integrated circuit containing two identical complementary-simmetry J-K master-slave flip-flops. Each flip-flop has provisions for individual J, K, Set, Reset and Clock input signals. Buffered Q and $\overline{Q}$ signals are provided as outputs. This input-output arrangement provides for compatible operation with the MMC 4013 dual D-type flip-flop.
The MMC 4027 is useful in performing control, register, and toggle functions. Logic levels present at the J and K inputs along with internal self-steering control the state of each flip-flop; changes in the flip-flop state are synchronous with the positive-going transition of the clock pulse. Set and reset functions are independent of the clock and are initiated when a high level signal is present at either the Set or Reset input.

FEATURES

- Set-Reset capability
- Static flip-flop operation-retains state indefinitely with clock level either „high" or „low"
- Medium speed operation-16 MHz (typ.) clock toggle rate at 10 V
- 100% tested for quiescent current

APPLICATIONS

- Registers, counters, control circuits

ABSOLUTE MAXIMUM RATINGS

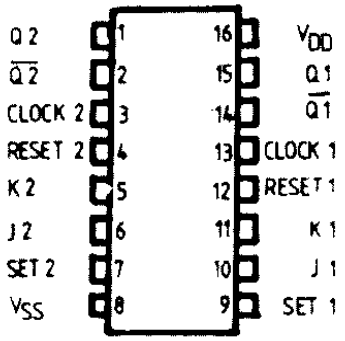
V_{DD}*	Supply voltage:	G and H types	-0.5 to	20	V
		E and F types	-0.5 to	18	V
V_I	Input voltage		-0.5 to	V_{DD}+0.5	V
I_I	DC input current (any one input)			± 10	mA
P_{tot}	Total power dissipation (per package)			200	mW
	Dissipation per output transistor for T_A = full package-temperature range			100	mW
T_A	Operating temperature	G and H types	-55 to	125	C
		E and F types	-40 to	85	C
T_{stg}	Storage temperature		-65 to	150	C

* All voltage values are referred to V_{SS} pin voltage

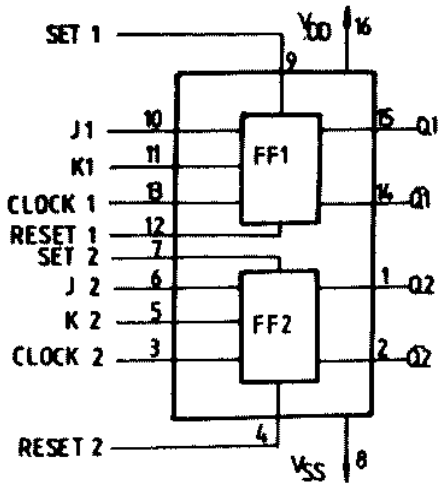
RECOMMENDED OPERATING CONDITIONS

V_{DD}*	Supply voltage:	G and H types	3 to	18	V
		E and F types	3 to	15	V
V_I	Input voltage		0 to	V_{DD}	V
T_A	Operating temperature	G and H types	-55 to	125	C
		E and F types	-40 to	85	C

CONNECTION DIAGRAM



FUNCTIONAL DIAGRAM

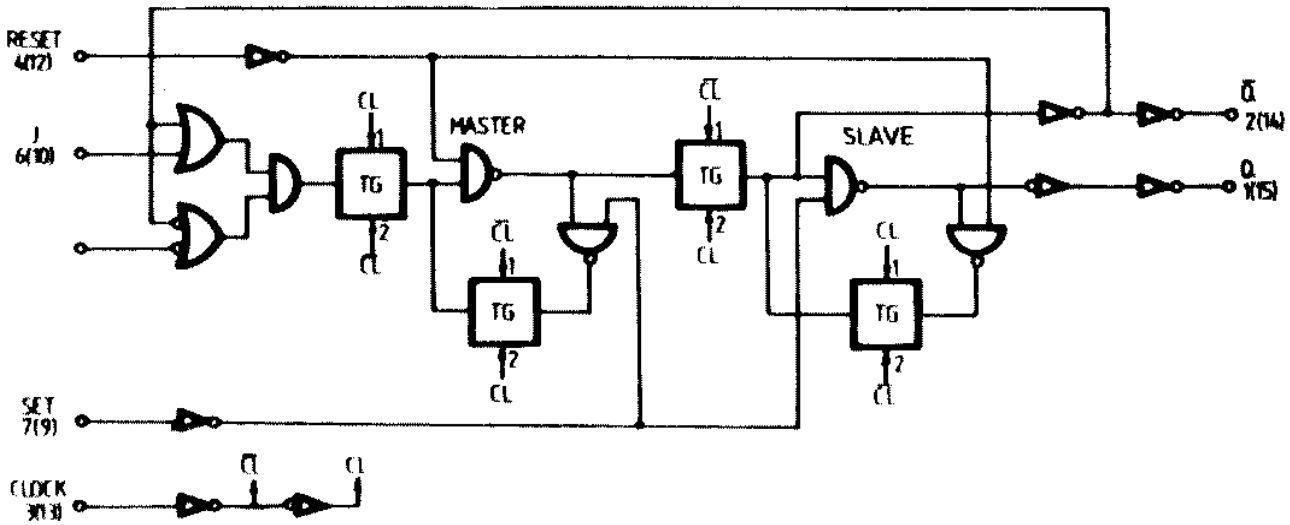


TRUTH TABLE

PRESENT STATE					CL●	NEXT STATE OUTPUTS		
INPUTS				OUTPUT				
J	K	S	R	Q		Q	Q	
1	X	0	0	0		1	0	
X	0	0	0	1		1	0	
0	X	0	0	0		0	1	
X	1	0	0	1		0	1	
X	X	0	0	X				· NO CHANGE
X	X	1	0	X	X	1	0	
X	X	0	1	X	X	0	1	
X	X	1	1	X	X	1	1	

● Level change
x Don't care

LOGIC DIAGRAM



STATIC ELECTRICAL CHARACTERISTICS

(over recommended operating conditions)

PARAMETER			TEST CONDITIONS				VALUES							UNIT
			V_I (V)	V_O (V)	$\|I_O\|$ (μA)	V_{DD} (V)	T^*_{LOW}		25°C			T^*_{HIGH}		
							min.	max.	min.	typ	max.	min.	max.	
I_L	Quiescent current	G, H types	0/ 5			5		1		0.02	1		30	μA
			0/10			10		2		0.02	2		60	
			0/15			15		4		0.02	4		120	
			0/20			20		20		0.04	20		600	
		E, F types	0/ 5			5		4		0.02	4		30	
			0/10			10		8		0.02	8		60	
			0/15			15		16		0.02	16		120	
V_{OH}	Output high voltage		0/ 5		< 1	5	4.95		4.95			4.95		V
			0/10		< 1	10	9.95		9.95			9.95		
			0/15		< 1	15	14.95		14.95			14.95		
V_{OL}	Output low voltage		5 /0		< 1	5		0.05			0.05		0.05	V
			10/0		< 1	10		0.05			0.05		0.05	
			15/0		< 1	15		0.05			0.05		0.05	
V_{IH}	Input high voltage			0.5/4.5	< 1	5	3.5		3.5			3.5		V
				1/9	< 1	10	7		7			7		
				1.5/13.5	< 1	15	11		11			11		
V_{IL}	Input low voltage			4.5/0.5	< 1	5		1.5			1.5		1.5	V
				9/1	< 1	10		3			3		3	
				13.5/1.5	< 1	15		4			4		4	
I_{OH}	Output drive current	G, H types	0/ 5	2.5		5	−2		−1.6	−3.2		−1.15		mA
			0/ 5	4.6		5	−0.64		−0.51	−1		−0.36		
			0/10	9.5		10	−1.6		−1.3	−2.6		−0.9		
			0/15	13.5		15	−4.2		−3.4	−6.8		−2.4		
		E, F types	0/ 5	2.5		5	−1.53		−1.36	−3.2		−1.1		
			0/ 5	4.6		5	−0.52		−0.44	−1		−0.36		
			0/10	9.5		10	−1.3		−1.1	−2.6		−0.9		
			0/15	13.5		15	−3.6		−3.0	−6.8		−2.4		
I_{OL}	Output sink current	G, H types	0/ 5	0.4		5	0.64		0.51	1		0.36		mA
			0/10	0.5		10	1.6		1.3	2.6		0.9		
			0/15	1.5		15	4.2		3.4	6.8		2.4		
		E, F types	0/ 5	0.4		5	0.52		0.44	1		0.36		
			0/10	0.5		10	1.3		1.1	2.6		0.9		
			0/15	1.5		15	3.6		3.0	6.8		2.4		
I_{IH}, I_{IL}	Input leakage current	G, H types	0/18	Any input		18		±0.1		$±10^{-5}$	±0.1		±1	μA
		E, F types	0/15			15		±0.3		$±10^{-5}$	±0.3		±1	
C_I	Input capacitance			Any input						5	7.5			pF

* T_{LOW} = −55°C for G, H devices; −40°C for E, F devices.

* T_{HIGH} = +125°C for G, H devices; +85°C for E, F devices.

The Noise Margin for both "1" and "0" level is:

1 V min. with V_{DD} = 5 V

2 V min. with V_{DD} = 10 V

2.5 V min. with V_{DD} = 15 V

DYNAMIC ELECTRICAL CHARACTERISTICS

(T_A = 25°C, C_L = 50 pF, R_L = 200 kΩ, typical temperature coefficient for all V_{DD} values is 0.3%/°C, all input rise and fall times = 20 ns)

PARAMETER			TEST CONDITIONS	VALUES			UNIT
			V_{DD}(V)	Min.	Typ.	Max.	
t_{PLH}, t_{PHL}	Propagation delay time	Clock to Q or $\overline{Q}$ outputs	5		150	300	ns
			10		65	130	
			15		45	190	
t_{PLH}	Propagation delay time	Set to Q or Reset to $\overline{Q}$	5		150	300	ns
			10		65	130	
			15		45	90	
t_{PHL}	Propagation delay time	Set to $\overline{Q}$ or Reset to Q	5		200	400	
			10		85	170	
			15		60	120	
t_{THL}, t_{TLH}	Transition time		5		100	200	ns
			10		50	100	
			15		40	80	
t_W	Pulse width	Clock	5	140	70		ns
			10	60	30		
			15	40	20		
t_W	Pulse width	Set or Reset	5	180	90		
			10	80	40		
			15	50	25		
t_r, t_f	Clock input rise or fall time		5			15	ns
			10			4	
			15			1	
t_{setup}	Setup time	Data	5	200	100		ns
			10	75	35		
			15	50	25		
f_{max}	Maximum clock input frequency*	Toggle mode	5	3.5	7		MHz
			10	8	16		
			15	12	24		

* Input t_r, t_f = 5 ns