

DATA SHEET

29 AUGUST 2003

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REV 1-03

REPLACEMENT
of UC384x

MIK384x Series • CURRENT-MODE PWM CONTROLLERS



MIK384x series

CURRENT MODE PWM CONTROLLER

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GENERAL DESCRIPTION

The MIK3842A(AM)(BW)/43A(AM)(BW)/44A(AM)(BW)/45A(AM)(BW) are fixed frequency current mode PWM controller. They are specially designed for OFF-Line and DC to DC converter applications with a minimal external components. Internally implemented circuits include a trimmed oscillator for precise duty cycle control, a temperature compensated reference, high gain error amplifier, current sensing comparator, and a high current totempole output ideally suited for driving a power MOSFET. Protection circuitry includes built undervoltage lockout and current limiting.

The MIK3842A(AM)(BW) and MIK3844A(AM)(BW) have UVLO thresholds of 16V (ON) and 10V (OFF). The corresponding thresholds for the MIK3843A(AM)(BW)/45A(AM)(BW) are 8.4V (ON) and 7.6V (OFF). The MIK3842A(AM)(BW) and MIK3843A(AM)(BW) can operate within 100% duty cycle. The MIK3844A(AM)(BW) and MIK3845A(AM)(BW) can operate within 50% duty cycle.

The MIK384xA(AM)(BW) has Start-Up Current 0.17mA (typ).

The MIK384xA-BW are revised UC384xAM and differ by higher Unity Gain bandwidth of Error Amplifier.

FEATURES

- Low Start-Up and Operating Current
- High Current Totem Pole Output
- Undervoltage Lockout With Hysteresis
- Operating Frequency Up To
 - 300kHz for 384xA
 - 500kHz for 384xAM, 384xBW

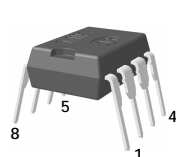


PIN CONNECTION AND DESCRIPTION

PIN		SYMBOL	DESCRIPTION
8-PIN	14-PIN		
1	1	COMP	This pin is the Error Amplifier output and is made for loop compensation.
2	3	V _{FB}	This is the inverting input of the Error Amplifier. It is normally connected to the switching power supply output through a resistor divider.
3	5	V _{SENSE}	A voltage proportional to inductor current is connected to this input. The PWM uses this information to terminate the output switch conduction.
4	7	R _T /C _T	The oscillator frequency and maximum output duty cycle are programmed by connecting resistor R _T to V _{ref} and capacitor C _T to ground.
5	—	GND	This pin is the combined control circuitry and power ground.
6	10	OUT	This output directly drives the gate of a power MOSFET. Peak currents up to 1A are sourced and sink by this pin.
7	12	V _{CC}	This pin is the positive supply of the integrated circuit.
8	14	V _{REF}	This is the reference output. It provides charging current for capacitor C _T through resistor R _T .
—	8	P_GND	This pin is a separate power ground return (14-pin package only) that is connected back to the power source. It is used to reduce the effects of switching transient noise on the control circuitry.
—	11	P_V _C	The output high state (V _{OH}) is set by the voltage applied to this pin (14-pin package only). With a separate power source connection, it can reduce the effects of switching transient noise on the control circuitry.
—	9	GND	This pin is the control circuitry ground return (14-pin package only) and is connected back to the power source ground.
—	2, 4, 6, 13	NC	No connection (14-pin package only). These pins are not internally connected.

MIK384xN, MIK384x-BWN

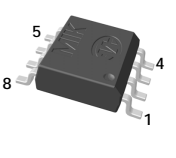
DIP-8



- 1 — COMP
- 2 — V_{FB}
- 3 — V_{SENSE}
- 4 — R_T/C_T
- 5 — GND
- 6 — OUT
- 7 — V_{CC}
- 8 — V_{REF}

MIK384xD1, MIK384x-BWD1

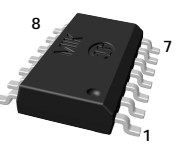
SOP-8



- 1 — COMP
- 2 — V_{FB}
- 3 — V_{SENSE}
- 4 — R_T/C_T
- 5 — GND
- 6 — OUT
- 7 — V_{CC}
- 8 — V_{REF}

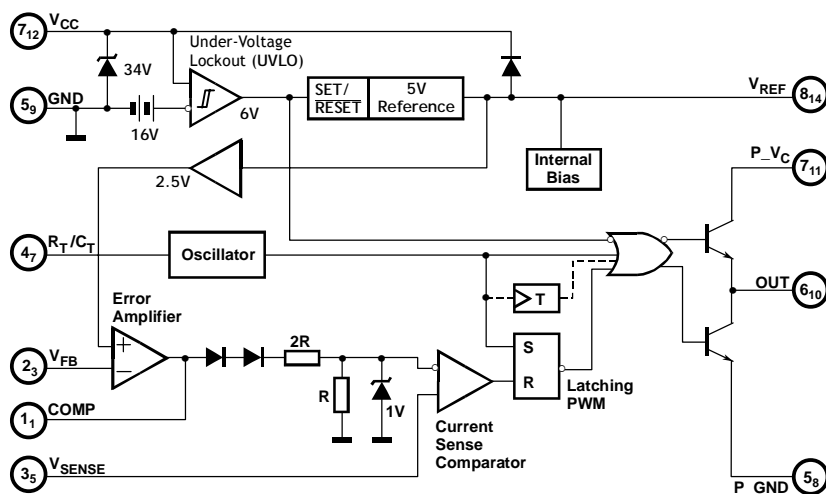
MIK384xD, MIK384x-BWD

SOP-14



- 1 — COMP
- 2 — NC
- 3 — V_{FB}
- 4 — NC
- 5 — V_{SENSE}
- 6 — NC
- 7 — R_T/C_T
- 8 — P_GND
- 9 — GND
- 10 — OUT
- 11 — V_{CC}
- 12 — V_{CC}
- 13 — NC
- 14 — V_{REF}

BLOCK DIAGRAM



NOTES:



A = DIP-8 and SOP-8 Pin Number.
 B = SOP-14 Pin Number.

Toggle flip flop used only in MIK3844 and MIK3845.



ABSOLUTE MAXIMUM RATINGS

SYMBOL	CHARACTERISTIC	VALUE	UNIT
V_{CC}	Supply Voltage (low impedance source)	30	V
I_O	Output Current	± 1	A
V_I	Input Voltage (Analog Inputs pins 2,3)	-0.3 to 5.5	V
$I_{SINK (E.A)}$	Error Amp Output Sink Current	10	mA
P_O	Power Dissipation ($T_A = 25^\circ\text{C}$)	1	W
Tstg	Storage Temperature Range	-65 to 150	$^\circ\text{C}$
T_L	Lead Temperature (soldering 5 sec.)	260	$^\circ\text{C}$

ELECTRICAL CHARACTERISTICS

(* $V_{CC}=15\text{V}$, $R_T = 10\text{k}\Omega$, $C_T = 3.3\text{nF}$, $T_A = 0^\circ\text{C}$ TO $+70^\circ\text{C}$, unless otherwise specified)

SYMBOL	CHARACTERISTICS	TEST CONDITION	MIN	TYP	MAX	UNIT
REFERENCE SECTION						
V_{REF}	Reference Output Voltage	$T_J = 25^\circ\text{C}$, $I_{REF} = 1\text{ mA}$	4.9	5.0	5.1	V
ΔV_{REF}	Line Regulation	$12\text{V} \leq V_{CC} \leq 25\text{V}$	—	6.0	20	mV
I_{REF}	Load Regulation	$1\text{ mA} \leq I_{REF} \leq 20\text{mA}$	—	6.0	25	mV
I_{SC}	Short Circuit Output Current	$T_A = 25^\circ\text{C}$	—	-100	-180	mA
OSCILLATOR SECTION						
f	Oscillation Frequency	$T_J = 25^\circ\text{C}$ (MIK384x-A)	47	50	57	kHz
		$T_J = 25^\circ\text{C}$ (MIK384x-AM, MIK384x-BW)	47	52	57	kHz
$\Delta f/\Delta V_{CC}$	Frequency Change with Voltage	$12\text{V} \leq V_{CC} \leq 25\text{V}$	—	0.05	1.0	%
$V_{(OSC)}$	Oscillator Amplitude	(peak to peak)	—	1.6	—	V
ERROR AMPLIFIER SECTION						
I_{BIAS}	Input Bias Current	$V_{FB}=3\text{V}$	—	-0.1	-2	μA
$V_{I(E.A)}$	Input Voltage	$V_{PIN 1} = 2.5\text{V}$	2.42	2.5	2.58	V
A_{VOL}	Open Loop Voltage Gain	$2\text{V} \leq V_O \leq 4\text{V}$	65	90	—	dB
UGBW	Unity Gain Bandwidth (only for MIK384xA-BW)	$T_J=25^\circ\text{C}$, Note 3	0.5	0.6	—	MHz
PSRR	Power Supply Rejection Ratio	$12\text{V} \leq V_{CC} \leq 25\text{V}$	60	70	—	dB
I_{SINK}	Output Sink Current	$V_{PIN 2} = 2.7\text{V}$, $V_{PIN 1} = 1.1\text{V}$	2	7	—	mA
I_{SOURCE}	Output Source Current	$V_{PIN 2} = 2.3\text{V}$, $V_{PIN 1} = 5\text{V}$	-0.5	-1.0	—	mA
V_{OH}	High Output Voltage	$V_{PIN 2} = 2.3\text{V}$, $R_L = 15\text{k}\Omega$ to GND	5.0	6.0	—	V
V_{OL}	Low Output Voltage	$V_{PIN 2} = 2.7\text{V}$, $R_L = 15\text{k}\Omega$ to Pin8	—	0.8	1.1	V
CURRENT SENSE SECTION						
G_V	Gain	(Notes 1, 2)	2.85	3.0	3.15	V/V
$V_{I(MAX)}$	Maximum Input Signal	$V_{PIN 1} = 5\text{V}$ (Note1)	0.9	1.0	1.1	V
SVR	Supply Voltage Rejection	$12\text{V} \leq V_{CC} \leq 25\text{V}$ (Note 1)	—	70	—	dB
I_{BIAS}	Input Bias Current	$V_{PIN 3} = 3\text{V}$	—	-3.0	-10	μA
OUTPUT SECTION						
V_{OL}	Low Output Voltage	$I_{SINK} = 20\text{ mA}$	—	0.08	0.4	V
		$I_{SINK} = 200\text{ mA}$	—	1.4	2.2	
V_{OH}	High Output Voltage	$I_{SINK} = 20\text{ mA}$	13	13.5	—	V
		$I_{SINK} = 200\text{ mA}$	12	13.0	—	
t_R	Rise Time	$T_J = 25^\circ\text{C}$, $C_L = 1\text{nF}$ (Note 3)	—	45	150	ns
t_F	Fall Time	$T_J = 25^\circ\text{C}$, $C_L = 1\text{nF}$ (Note 3)	—	35	150	

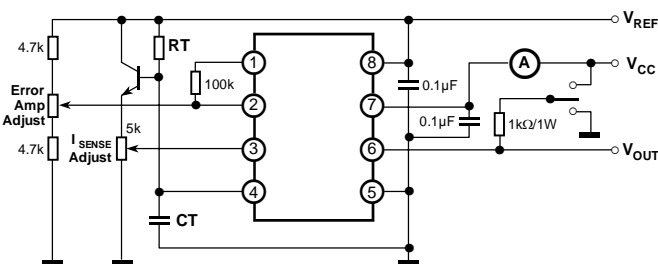
* Adjust V_{CC} above the start threshold before setting it to 15V.

**ELECTRICAL CHARACTERISTICS (CONTINUED)**(* $V_{CC} = 15V$, $R_T = 10K\Omega$, $C_T = 3.3nF$, $T_A = 0^\circ C$ TO $+70^\circ C$, unless otherwise specified)

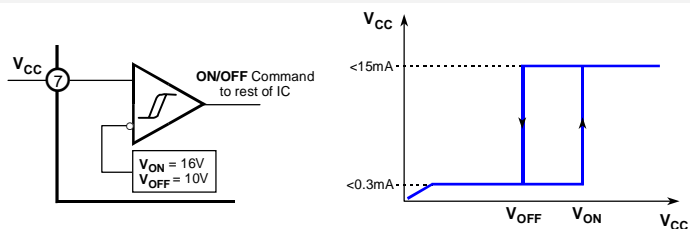
SYMBOL	CHARACTERISTICS	TEST CONDITION	MIN	TYP	MAX	UNIT
UNDERVOLTAGE LOCKOUT SECTION						
$V_{TH(ST)}$	Start Threshold	MIK3842A(AM), MIK3842A-BW	14.5	16.0	17.5	V
		MIK3844A(AM), MIK3844A-BW				
		MIK3843A(AM), MIK3843A-BW	7.8	8.4	9.0	V
		MIK3845A(AM), MIK3845A-BW				
$V_{OPR(min)}$	Min. Operating Voltage (After Turn On)	MIK3842A(AM), MIK3842A-BW	8.5	10	11.5	V
		MIK3844A(AM), MIK3844A-BW				
		MIK3843A(AM), MIK3843A-BW	7.0	7.6	8.2	V
		MIK3845A(AM), MIK3845A-BW				
PWM SECTION						
$D_{(MAX)}$	Max. Duty Cycle	MIK3842A(AM), MIK3842A-BW	95	97	100	%
		MIK3843A(AM), MIK3843A-BW				
		MIK3844A(AM), MIK3844A-BW	47	48	50	%
		MIK3845A(AM), MIK3845A-BW				
$D_{(MIN)}$	Min. Duty Cycle	—	—	0	%	
TOTAL STANDBY CURRENT						
I_{ST}	Start-Up Current	MIK384xA(AM), MIK384xA-BW		0.17	0.3	mA
$I_{CC(OPR)}$	Operating Supply Current	$V_{pin3} = V_{pin2} = 0V$		13	17	
V_Z	Zener Voltage	$I_{CC} = 25\text{ mA}$	30	38		V

* Adjust V_{CC} above the Startup threshold before setting it to 15V.Note 1: Parameter measured at trip point of latch with $V_{pin2} = 0$.Note 2: Gain defined as $A = \Delta V_{pin1} / \Delta V_{pin3}$; $0 \leq V_{pin3} \leq 0.8V$.

Note 3: These parameters, although guaranteed, are not 100% tested in production.

APPLICATION INFORMATION**OPEN-LOOP LABORATORY TEST FIXTURE**

High peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected close to pin 5 in a single point ground. The transistor and 5kΩ potentiometer are used to sample the oscillator waveform and apply an adjustable ramp to pin 3.

UNDERVOLTAGE LOCKOUT (UVLO)

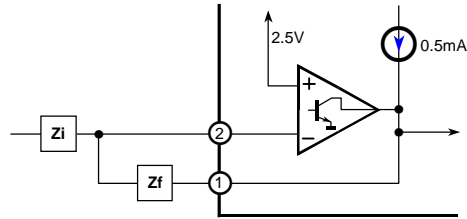
During Under-Voltage Lock-Out, the output driver is biased to a high impedance state. Pin 6 should be shunted to ground with a bleeder resistor to prevent activating the power switch with output leakage current.



APPLICATION INFORMATION (CONTINUED)

ERROR AMPLIFIER CONFIGURATION

Error amplifier can source or sink up to 0.5A.

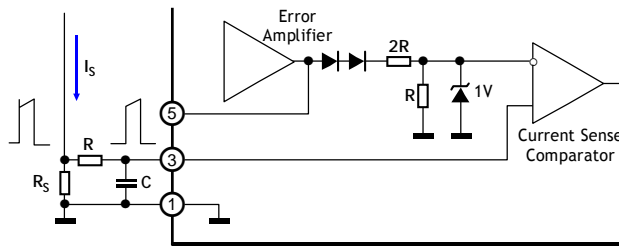


CURRENT SENSE CIRCUIT

Peak current (I_S) is determined by the formula:

$$I_S (\text{MAX}) = 1V / R_S$$

A small RC filter may be required to suppress switch transients.



OSCILLATOR WAVEFORMS AND MAXIMUM DUTY CYCLE

Oscillator timing capacitor, C_T , is charged by V_{REF} through R_T and discharged by an internal current source. During the discharge time, the internal clock signal blanks the output to the low state. Selection of R_T and C_T therefore determines both oscillator frequency and maximum duty cycle. Charge and discharge times are determined by the formulas:

$$t_c = 0.55 R_T C_T$$

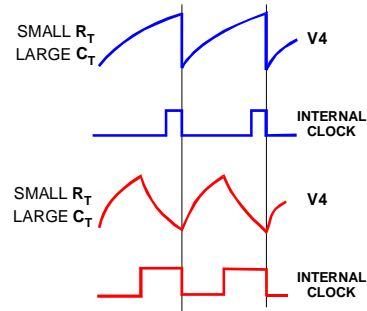
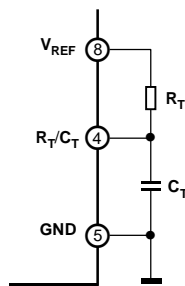
$$t_d \approx R_T C_T \times \ln \left(\frac{0.0063 R_T - 2.7}{0.0063 R_T - 4} \right)$$

Frequency, then, is

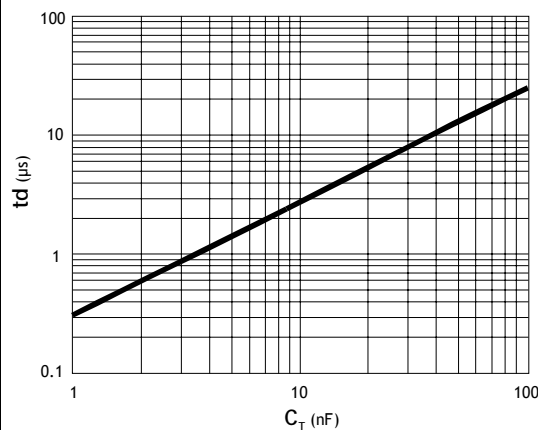
$$f = (t_c + t_d)^{-1}$$

For $R_T > 5k\Omega$

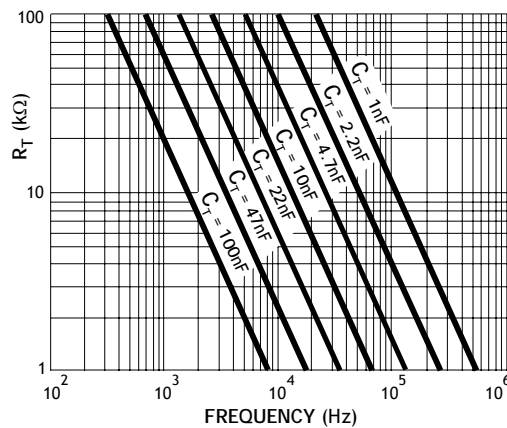
$$f \approx 1.8 / R_T C_T$$



OSCILLATOR DEAD TIME vs. C_T ($R_T > 5K$)



TIMING RESISTANCE vs. FREQUENCY



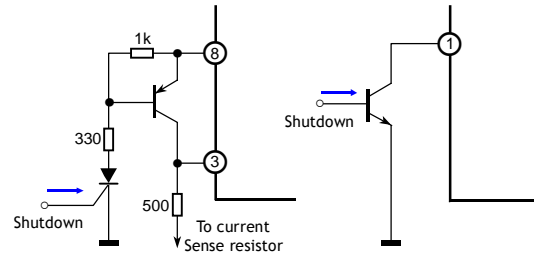


APPLICATION INFORMATION (CONTINUED)

SHUTDOWN TECHNIQUES

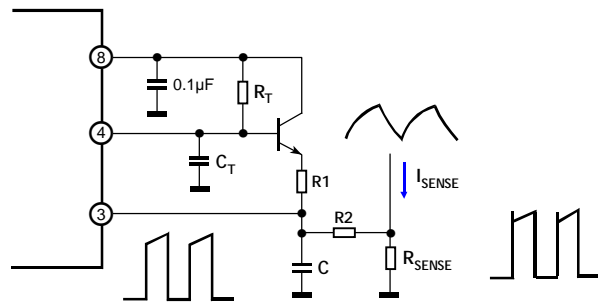
Shutdown of the MIK384xx can be accomplished by two methods; either raise Pin 3 above 1V or pull Pin 1 below a voltage two diode drops above ground. Either method caused the output of PWM comparator to be high (refer to block diagram). The PWM latch is reset dominant so that the output will remain low until the next clock cycle after the shutdown condition at pins 1 and/or 3 is removed. In one example, an externally latched shutdown may be accomplished by adding an SCR which be reset by cycling V_{CC} below the lower UVLO threshold.

At this point the reference turns off allowing the SCR to reset.



SLOPE COMPENSATION

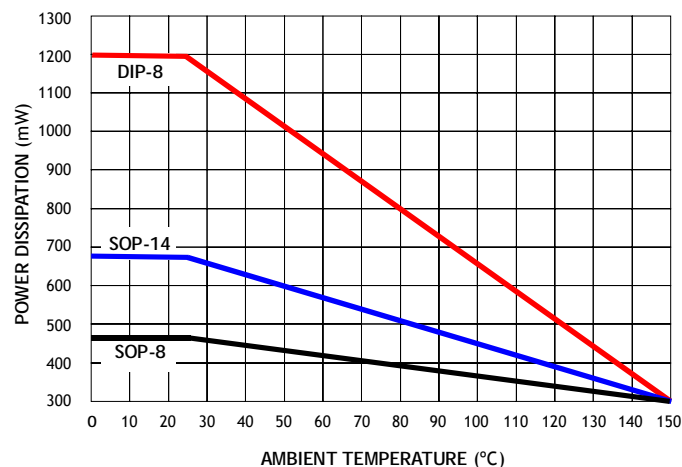
A fraction of the oscillator ramp can be resistively summed with the current sense signal to provide slope compensation for converts requiring duty cycles over 50%. Note that capacitor C_T forms a filter with R_2 to suppress the leading edge switch spikes.



THERMAL DATA

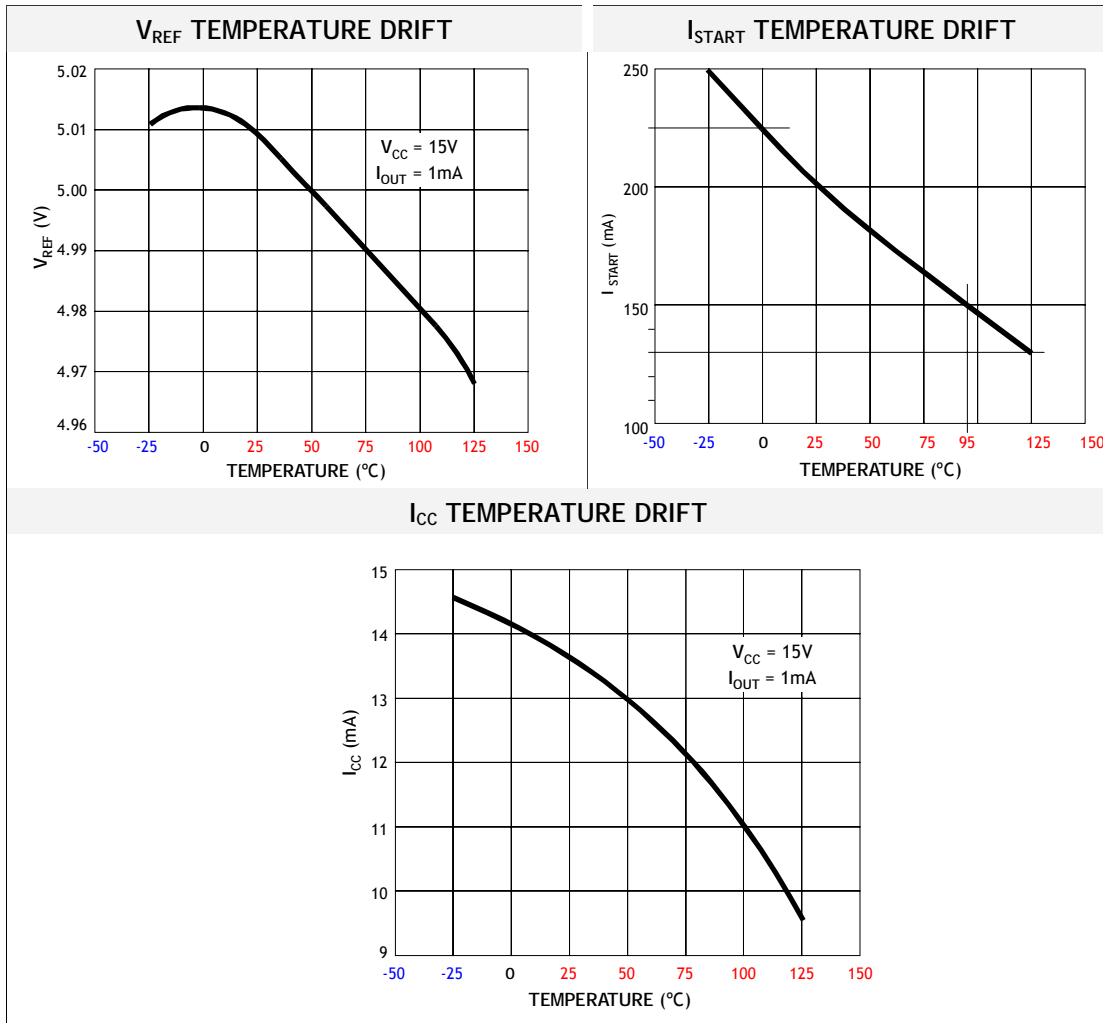
SYMBOL	CHARACTERISTIC	DIP-8	SOP-8	SOP-14	UNIT
$R_{THJ-AMB}(MAX)$	Thermal Resistance Junction-ambient	100	265	180	$^{\circ}C/W$

POWER DISSIPATION CURVE





TYPICAL PERFORMANCE CHARACTERISTICS





PHYSICAL DIMENSIONS AND MARKING DIAGRAMS

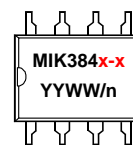
MIKRON_JSC • http://www.mikron.ru • 29 August 2003

DIP-8 PACKAGE

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9,35	9,45	0,368	0,372
B	6.30	6.40	0,248	0,252
C	0,84	0,94	0,033	0,037
D		1,82		0,072
E	0,41	0,51	0,016	0,020
F	3,75	4,35	0,148	0,171
G	0,94	1,04	0,037	0,041
H	2,49	2,59	0,098	0,102
J	3,00	3,50	0,118	0,138
K	0,50	1,10	0,020	0,043
L	0,20	0,30	0,008	0,012
M	7,57	7,67	0,298	0,302
N		10°		10°

DIP-8

MARKING DIAGRAM



X-X – see page 4, table «ELECTRICAL CHARACTERISTICS»

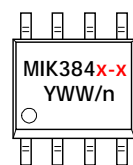
YY – Year
WW – Work Week
n – assembly location

SOP-8 PACKAGE

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	4.78	4.91	0.188	0.193
B	5.96	6.12	0.235	0.241
C	3.89	3.99	0.153	0.157
D		0.406		0.016
E	1.40	1.50	0.055	0.059
F	0.49	0.55	0.019	0.022
G		1.27		0.050
H	0.10	0.25	0.004	0.010
J	0.50	0.25	0.020	0.010
K	0.17	0.23	0.007	0.009
L	0.40	1.25	0.016	0.049
M	0°	7°	0°	7°

SOP-8

MARKING DIAGRAM



X-X – see page 4, table «ELECTRICAL CHARACTERISTICS»

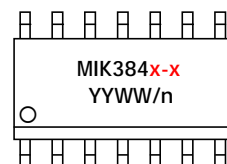
Y – Year
WW – Work Week
n – assembly location

SOP-14 PACKAGE

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	8.55	8.75	0.340	0.350
B	5.80	6.20	0.228	0.244
C	3.80	4.00	0.150	0.160
D	0.36	0.49	0.014	0.019
E	1.25	1.75	0.049	0.069
F	0.49	0.55	0.019	0.022
G		1.27		0.050
H	0.10	0.25	0.004	0.010
J	0.50	0.25	0.020	0.010
K	0.17	0.23	0.007	0.009
L	0.40	1.25	0.016	0.049
M	0°	7°	0°	7°

SOP-14

MARKING DIAGRAM



X-X – see page 4, table «ELECTRICAL CHARACTERISTICS»

YY – Year
WW – Work Week
n – assembly location



ORDERING INFORMATION

(THE FORM OF PACKING IS STIPULATED IN THE CONTRACT)





ORDERING NUMBER	OPERATING TEMPERATURE RANGE	PACKAGE	SHIPPING	
MIK3842A N	T _A = 0°C to +70°C	DIP-8	50 Units/Rail	
MIK3843A N		DIP-8	50 Units/Rail	
MIK3844A N		DIP-8	50 Units/Rail	
MIK3845A N		DIP-8	50 Units/Rail	
MIK3842AM N		DIP-8	50 Units/Rail	
MIK3843AM N		DIP-8	50 Units/Rail	
MIK3844AM N		DIP-8	50 Units/Rail	
MIK3845AM N		DIP-8	50 Units/Rail	
MIK3842A-BW N		DIP-8	50 Units/Rail	
MIK3843A-BW N		DIP-8	50 Units/Rail	
MIK3844A-BW N		DIP-8	50 Units/Rail	
MIK3845A-BW N		DIP-8	50 Units/Rail	
MIK3842A D1		T _A = 0°C to +70°C	SOP-8	98 Units/Rail
MIK3843A D1			SOP-8	98 Units/Rail
MIK3844A D1			SOP-8	98 Units/Rail
MIK3845A D1	SOP-8		98 Units/Rail	
MIK3842AM D1	SOP-8		98 Units/Rail	
MIK3843AM D1	SOP-8		98 Units/Rail	
MIK3844AM D1	SOP-8		98 Units/Rail	
MIK3845AM D1	SOP-8		98 Units/Rail	
MIK3842A-BW D1	SOP-8		98 Units/Rail	
MIK3843A-BW D1	SOP-8		98 Units/Rail	
MIK3844A-BW D1	SOP-8		98 Units/Rail	
MIK3845A-BW D1	SOP-8		98 Units/Rail	
MIK3842A D	T _A = 0°C to +70°C		SOP-14	55 Units/Rail _ 2500 Tape & Reel
MIK3843A D			SOP-14	55 Units/Rail _ 2500 Tape & Reel
MIK3844A D			SOP-14	55 Units/Rail _ 2500 Tape & Reel
MIK3845A D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3842AM D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3843AM D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3844AM D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3845AM D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3842A-BW D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3843A-BW D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3844A-BW D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	
MIK3845A-BW D		SOP-14	55 Units/Rail _ 2500 Tape & Reel	






The information presented in this Data sheet is believed to be accurate and reliable. However, MIKRON can assume no responsibility for its use as well as for use of the circuits or devices described herein.

In the interest of product improvement, MIKRON reserves the right to change specifications and data without notice.

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