



ICM532B
CIF Color CMOS Image Sensor
With USB Output

Data Sheet
V1.1
November, 2002

IC Media Corporation

545 East Brokaw Road
San Jose, CA 95112, U.S.A.
Phone: (408) 451-8838
Fax: (408) 451-8839
Email: Sales@IC-Media.Com
Web Site: www.ic-media.com

IC Media Technology Corporation

6F, No. 61, ChowTze Street., NeiHu District
Taipei, Taiwan, R.O.C.
Phone: 886-2-2657-7898
Fax: 886-2-2657-8751
Email: Ap.Sales@IC-Media.Com.tw
Web Site: www.ic-media.com.tw

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Features

- CIF format (352x288) pixels, used with 1/7" optical system.
- QVGA format (320x240) pixels, used with 1/7" optical system
- QCIF format (176x144) pixels, cropped or subsampled, up to 37.5 fps.
- Progressive readout
- Output data format: compressed 8-bit raw data
- Image processing and decompression supported with proprietary software. Image processing functions include color interpolation, color correction, auto white balance, auto exposure, auto anti-flickering, and sharpening.
- Proprietary data compression
- Input/Output interface: USB 1.1 Full Speed
- Electronic exposure control
- On-chip 9-bit ADC
- Correlated double sampling
- Dead pixel and dead column removal
- Power down/Suspend mode
- 8 User Programmable GPIO pins
- Optional 3.3V Serial EEPROM register loading during power-up (24C02/04/08/16)
- Automatic optical black compensation
- Mirror image
- Single 3.3 V power supply

Key Parameters

- Number of Active Pixels: up to 352x288
- Number of Physical Pixels: 362x298
- Frame Rate: up to 30 fps (35 fps QCIF)
- Pixel Size: 6.0 μm x 6.0 μm
- Sensor Area: 2.2 mm x 1.8 mm
- Single Crystal Frequency: 6 MHz
- Exposure Time: 125 μs (@ 25 fps, 1 line) ~ 8 s (@ 12 fps)
- Sensitivity: 1.0 V/lux-sec (555 nm)
- Quantum Efficiency: 38 % (555 nm)
- Dynamic Range: 53 dB (analog), 48 dB (digital)
- Fill Factor: 36%
- S/N Ratio: 45 dB @ 75% full signal level
- Sensitive to infrared illumination source
- Digital Gain: 1 ~ 64 x @ 2^N for all pixels
- RGB Gain: 1/256 ~ 64 x for individual Bayer pattern pixels
- Power Supply: 3.3 V
- Power consumption: 130mW typ.
- Packages: SPLCC48

General Description

ICM-532B is a single-chip, CIF resolution, digital color PC camera with integrated data compression, line buffer and Full Speed USB 1.1 interface. All the image processing functions (color interpolation, color correction, auto white balance, auto exposure, auto anti-flickering, sharpening) are performed by software in the host computer. It incorporates a 352x288 sensor array operating at 6 ~ 30 frames per second in progressive manner. Each pixel is covered by a color filter, which forms a "Bayer pattern." Correlated double sampling is performed by the internal ADC and timing circuitry. The raw data can be adjusted with digital gain. The raw data is compressed using a proprietary compression scheme. The compression allows video out in 8-bit compressed data format through USB 1.1 with 30 frames per second video capability. For higher frame-rates, sub-sampled or cropped QCIF (176x144) modes are available that support 35 frames per second.

8 Pins are supplied that can be programmed by the driver as general purpose I/O pins, with individually selectable output enables. During power-up, the internal control registers can be loaded from an external serial EEPROM. This allows customization of Vendor ID and Product ID, as well as initialization of other device parameters.

The 48 MHz clock required for the ICM-532B is provided by an on-chip phase-lock loop that is driven by an external 6 MHz crystal oscillator. Using a PLL reduces power dissipation, electrical noise and the cost of the crystal. It also reduces the need for EMI shielding that would be required if a 48 MHz oscillator were used. The highest frequency external signal is the 12Mbps on the differential USB data pins.

Software Support

- Computer & OS requirements: 750 MHz, 64M memory for 30 fps; 300 MHz, 64M memory for 12 fps. Windows 98, Windows ME, Windows 2000 Macintosh OS 9.
- Driver support
 - WDM USB driver
 - TWAIN
 - DirectShow
 - VFW extension driver
 - Proprietary DirectShow decoder
 - Installation software

Applications

- PC camera
- Embedded Solutions (Notebooks, LCD monitors)



1. Pin Assignments

| Pin # | Name | Class | Function |
|----------------------|----------|---------|---|
| 36 | DN | B,IO | USB D- connection |
| 37 | DP | B,IO | USB D+ connection |
| 40 | XIN | A,I | 6 MHz Crystal Input |
| 39 | XOUT | A,O | 6 MHz Crystal Output |
| 3,5,34 | Reserved | D,O | Leave Unconnected |
| 44 | Test | D, I, N | Leave Unconnected |
| 2 | Clock_S | D, IO | Serial clock, for external serial EEPROM |
| 1 | Data_S | D, IO | Serial data, for external serial EEPROM |
| | | | |
| 16 | RSET | A,I | Resistor to Ground = 75 K Ω |
| 8 | RSTN | D,SI,U | Chip Reset, active low |
| 15 | RAMP | A,O | Analog Test Output |
| | | | |
| 46 | GPIO 0 | D,IO | User Programmable I/O, Requires External Pull-up |
| 47 | GPIO 1 | D,IO | User Programmable I/O, Requires External Resistor |
| 48 | GPIO 2 | D,IO | User Programmable I/O, Requires External Pull-up |
| 10 | GPIO 3 | D,IO | User Programmable I/O |
| 11 | GPIO 4 | D,IO | User Programmable I/O |
| 12 | GPIO 5 | D,IO | User Programmable I/O |
| 13 | GPIO 6 | D,IO | User Programmable I/O |
| 14 | GPIO 7 | D,IO | User Programmable I/O |
| | | | |
| 7,27,31 | VDDA | P | Sensor & PLL Analog Power |
| 9,28,30 | GNDA | P | Sensor & PLL Analog Ground |
| 19 | VDDD | P | Sensor Digital Power |
| 17 | GNDD | P | Sensor Digital Ground |
| 4,26,33, 38,41,43 | VDDK | P | Digital Power |
| 6,29,32, 35,42,45 | GNDK | P | Digital Ground |
| 18 | GNDS | P | Substrate Ground |

Class Code: A – Analog signal, D – Digital signal, I – Input, SI – Schmitt Input, O – Output, IO – Bidirectional, P – Power or ground, U – Internal pull-up, N – Internal pull-down, B – USB Pad

2. Functional Description

ICM-532B is a single-chip USB digital color imaging device. It includes a 352x288 sensor array, 352 column-level ADC, and correlated double sampling circuitry. All the programmable parameters are set by writing through the USB interface which can address the register file consisting of 8-bit registers. The internal CIF image sensor is based upon the ICM-102B. The output format is USB 1.1 compatible compressed video data using a single ISOCHRONOUS channel. Dead pixels and dead columns are



removed, to generate a high quality image.

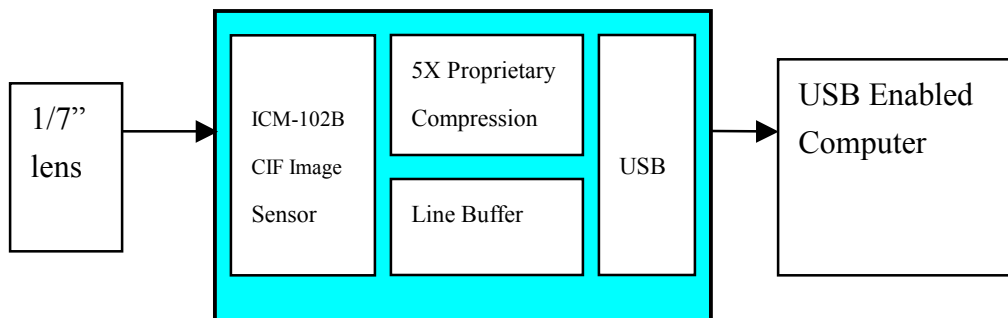


Figure 1. Block Diagram

2.1. Image Array

The image array consists of 352x288 pixels. Each pixel has a light sensitive photo diode and a set of control and transfer transistors. At the beginning of the cycle, a row of pixels is pre-charged to its maximum value. Then they are exposed to light for several lines worth of time and sampled by the ADC. Correlated double sampling (CDS) is performed by subtracting the reset value (sampled right before sampling the signal) from the signal value. The purpose of CDS is to eliminate the point-wise fixed pattern noise (FPN). The output of CDS is approximately proportional to the amount of received light, ranging from 0 to 255.

2.2. Color Filter

Each pixel is covered by a color filter. They form the Bayer Pattern as shown in Figure 2. (Row 0, Column 0) is covered by a Red filter, (Row 0, Column 1) and (Row 1, Column 0) by Green filters, and (Row 1, Column 1) by a Blue filter. Since each pixel only gets part of the frequency band, the data needs further processing (i.e., color interpolation and color correction) in order to approximate the full visible spectrum.

| | | | | | | | |
|---|---|---|---|---|---|---|---|
| R | G | R | G | R | G | R | G |
| G | B | G | B | G | B | G | B |
| R | G | R | G | R | G | R | G |
| G | B | G | B | G | B | G | B |

Figure 2. Color filter Bayer pattern

2.3. Exposure and Gain Control

The brightness of the scene may change by a great amount that renders the captured image either



over-exposed or under-exposed. To accommodate for different brightness, the user may change the exposure time or digital gain by adjusting the AD_EXPOSE_TIMEH and AD_EXPOSE_TIMEL. The exposure time is measured in terms of the time to read out one line of data, which is equal to 125 us (assuming the line length is 500). If the number of lines per frame is set at 320 (the default), the exposure time can vary from 1 to 319 lines. In addition, the user can adjust bit 7 to 5 of register AD_EXPOSE_TIMEH to digitally boost the output value by 1 to 64 times @ 2N for all pixels. Furthermore, users can adjust registers AD_M1_L, AD_M1_H, AD_M2_L, AD_M2_H, AD_M3_L, AD_M3_H, AD_M4_L, AD_M4_H, to optimize the RGB gain (from 1/256 to 64) of the 4 Bayer pattern pixels separately.

2.4. Output Format

During normal operation, the output format is 8-bit compressed data that ranges from 0 to 255. This data is transmitted with a USB Transceiver using Isochronous packets. The video quality is related to the size of the packets, with 1023 bytes/packet generating the highest quality image. The packets are received, decompressed, and color processed by a host PC. A typical configuration is to connect ICM-532B to a USB enabled PC. When operated at 24 fps CIF, the USB clock is 48 MHz and the Video data clock is 4MHz. When operated at 30 fp, the Video data clock is 6MHz. The line and frame timing can be adjusted through registers AD_WIDTH and AD_HEIGHT.

3. Control Registers

Registers may be configured using either the USB Command/Control Channel, or the Serial interface. The result is unpredictable if both interfaces are used simultaneously. USB access should be made using a Standard Vendor Type Device Request. For a write, if the Length field value is 0, the two bytes in the Value field are written into two registers starting at the Index field value. For all other Length field values, the data stage transfers the requested number of bytes starting from the Index field value. The data transfer Length must not be larger than 8 bytes.

The 7-bit Serial ICM-532B device address is 0x21. ICM-532B can operate in either Serial master mode or slave mode right after power up, depending on the pull-up or pull-down of the GPIO[1] pin. When GPIO[1] is pulled low during power-up, ICM-102B's Serial interface is operated as a slave device, waiting to be controlled by an external master such as a microprocessor. When GPIO[1] is pulled high

during power-up, the Serial interface will first act as a master device, trying to read from an external EEPROM (24C02/04/08/16). The first word read will indicate the number of bytes to transfer from the external EEPROM. After transferring these bytes, or failing to access an external device, the ICM-532B will behave like a slave device. The external EEPROM is addressed at address 0x50, and must be 3.3v compatible.

| Address | Name | Default | Description |
|------------------|---|---------------|--|
| 0:00h | PART_CONTROL | 0 | Processing control [0] 0: normal mode [1] Slope adjustment enable [2] Exposure time control, writing a 1 will activate the new value set in AD_EXPOSE_TIME, when read back from it, 0 means the exposure time change is finished, 1 means the exposure time change is still in progress. [6:3] Reserved [7] Latent change, writing a 1 means the changed latent registers now starts taking effect, when the entire operation is done, the read back value of this bit will change from 1 to 0. |
| 1:01h 2:02h | TIMING_CONTROL_LOW TIMING_CONTROL_HIGH | 17 0x0011 | Timing control [0] Column count enable, set to 0 when filling wave table, set to 1 when normal operation [3] Auto dark correction enable [4] Timing select, 0: wave table timing, 1: default timing [8] IRST select, 0: from wave table, 1: from IRST_NUMBER register [11] Dead column removal mode, 0: color, 1: black-and-white [12] Out-of-array exposure pointer control, 0: point to row 295, 1: point to row 298 (a non-existent row) [13] Column stop, 0: sensor column counter stop at 361 when exceeding real array, 1: sensor column counter keeps counting |
| 7:07h | TABLE_LEN | 0 | Reserved |
| 12:0Ch 13:0Dh | AD_WIDTHL AD_WIDTHH | 500 0x01F4 | [9:0] Frame width |
| 14:0Eh 15:0Fh | AD_HEIGHTL AD_HEIGHTH | 400 0x0190 | [15:0] Frame height, should not be less than AD_ROW_BEGIN + 298 |
| 16:10h 17:11h | AD_COL_BEGINL AD_COL_BEGINH | 180 0x00B4 | [9:0] Beginning of active line in terms of column position [10] Mirror image enable [15:13] Digital gain 0: 1 1: 2 2: 4 3: 8 4: 16 5: 32 |



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| | | | |
|--------------------|------------------------------------|-----------------|---|
| | | | 6: 64 |
| 20:14h 21:15h | AD_ROW_BEGINL AD_ROW_BEGINH | 10 0x000A | [15:0] Beginning of active frame in terms of row position |
| 24:18h 25:19h | AD_HSYNC_ENDL AD_HSYNC_ENDH | 64 0x0040 | [9:0] End of horizontal sync in terms of column position |
| 26:1Ah 27:1Bh | AD_VSYNC_ENDL AD_VSYNC_ENDH | 3 0x0003 | [15:0] End of vertical sync in terms of row position |
| 28:1Ch 29:1Dh | AD_EXPOSE_TIMEL AD_EXPOSE_TIMEH | 524 0x020C | [15:0] Exposure time in terms of number of rows |
| 32:20h 33:21h | AD_M1_L AD_M1_H | 256 0x100 | [10:0] Gain coefficient (G1), in unsigned 3.8 ~ 6.5 format (Selected by register 52) |
| 34:22h 35:23h | AD_M2_L AD_M2_H | 256 0x100 | [10:0] Gain coefficient (R), in unsigned 3.8 ~ 6.5 format (Selected by register 52) |
| 36:24h 37:25h | AD_M3_L AD_M3_H | 256 0x100 | [10:0] Gain coefficient (B), in unsigned 3.8 ~ 6.5 format (Selected by register 52) |
| 38:26h 39:27h | AD_M4_L AD_M4_H | 256 0x100 | [10:0] Gain coefficient (G2), in unsigned 3.8 ~ 6.5 format (Selected by register 52) |
| 82:52h | AD_INOUTSEL | 0 | [4:0] Output format 0-7, 12-31: 8-bit raw data, with 0: RGB gain format = 3.8 1: RGB gain format = 4.7 2: RGB gain format = 5.6 3-7, 12-31: RGB gain format = 6.5 8: control signals 9: row address 10: column address 11: sensor raw data |
| 110:6Eh 111:6Fh | AD_DEAD0L AD_DEAD0H | 1023 0x03FF | [9:0] Dead column #0 in terms of real sensor array |
| 112:70h 113:71h | AD_DEAD1L AD_DEAD1H | 1023 0x03FF | [9:0] Dead column #1 in terms of real sensor array |
| 114:72h 115:73h | AD_DEAD2L AD_DEAD2H | 1023 0x03FF | [9:0] Dead column #2 in terms of real sensor array |
| 116:74h 117:75h | AD_DEAD3L AD_DEAD3H | 1023 0x03FF | [9:0] Dead column #3 in terms of real sensor array |
| 118:76h 119:77h | AD_DEAD4L AD_DEAD4H | 1023 0x03FF | [9:0] Dead column #4 in terms of real sensor array |
| 120:78h 121:79h | AD_DEAD5L AD_DEAD5H | 1023 0x03FF | [9:0] Dead column #5 in terms of real sensor array |
| 122:7Ah 123:7Bh | AD_DEAD6L AD_DEAD6H | 1023 0x03FF | [9:0] Dead column #6 in terms of real sensor array |
| 124:7Ch 125:7Dh | AD_DEAD7L AD_DEAD7H | 1023 0x03FF | [9:0] Dead column #7 in terms of real sensor array |
| 126:7Eh 127:7Fh | AD_DEAD8L AD_DEAD8H | 1023 0x03FF | [9:0] Dead column #8 in terms of real sensor array |
| 128:80h 129:81h | AD_DEAD9L AD_DEAD9H | 1023 0x03FF | [9:0] Dead column #9 in terms of real sensor array |
| 130:82h 131:83h | AD_IDL AD_IDH | 54048 0xD320 | [15:4] Device ID, can be programmed |
| 144:90h | AD_DARK_DATA | 0 | [7:0] When auto dark correction is disabled, serve as the subtrahend for dark correction |
| 149:95h | AD_SLOPE_END_TIMEL | 341 | [9:0] When auto slope adjustment is turned on, if |



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| | | | |
|--------------------|------------------------------------|----------------|--|
| 150:96h | AD_SLOPE_END_TIMEH | 0x0155 | the slope counter exceeds this value, the ramp will become steeper |
| 151:97h 152:98h | AD_WT_BEGINL AD_WT_BEGINH | 0 | Reserved |
| 153:99h 154:9Ah | AD_WT_ENDL AD_WT_ENDH | 1020 0x03FC | Reserved |
| 155:9Bh 156:9Ch | AD_SUB_EN_TIMEL AD_SUB_EN_TIMEH | 474 0x01DA | [9:0] Column position where the CDS subtraction pulse is applied |
| 161:A1h 162:A2h | AD_WIDTHL_C AD_WIDTHH_C | 500 0x01F4 | Reserved |
| 163:A3h 164:A4h | AD_HEIGHTL_C AD_HEIGHTH_C | 400 0x0190 | Reserved |
| 165:A5h 166:A6h | AD_COL_BEGINL_C AD_COL_BEGINH_C | 100 0x0064 | Reserved |
| 167:A7h 168:A8h | AD_ROW_BEGINL_C AD_ROW_BEGINH_C | 10 0x000A | Reserved |
| 169:A9h 170:AAh | AD_HSYNC_ENDL_C AD_HSYNC_ENDH_C | 64 0x0040 | Reserved |
| 171:ABh 172:ACH | AD_VSYNC_ENDL_C AD_VSYNC_ENDH_C | 3 0x0003 | Reserved |
| 173:ADh | AD_PART_CONTROL_C | 6 0x06 | Reserved |
| 174:AEh 175:AFh | AD_WT_BEGINL_C AD_WT_BEGINH_C | 0 | Reserved |
| 176:B0h 177:B1h | AD_WT_ENDL_C AD_WT_ENDH_C | 1020 0x03FC | Reserved |

- *These registers are updated at the next falling edge of VSYNC after register UPD is set. The occurrence of the update is marked in the video output by clearing bit 7 of the packet header. i.e. 80 => 00. This bit remains set until register UPD is cleared.

4. GPIO

4.1. General Purpose I/O pins

There are 8 pins that can be programmed by the user as general purpose Input/Output pins. Three of the pins are required to have pull-up or pull-down resistors attached to select device functionality at the rising edge of NRST.

1. Special Purpose:

GPIO[0] Pull-up.

It is possible to configure this output as an active low power-down pin, driven by the USB controller Suspend signal. When so configured, all external power except pins 4, 33, and 43 may be removed while this pin is driven low.

It is also possible to configure this output as an active low power-on pin, connected to an external LED. When so configured, an external LED with 8ma current limiting resistor will be on



unless the device is in Suspend state.

GPIO[1] Pull-up.

To enable external Serial EEPROM for register loads, Pull-down to disable this feature.

GPIO[2] Pull-up.

To select crystal oscillator clock source. Required condition

2. General Purpose:

The other 5 GPIO pins have no Pull-up/Pull-down requirements. All of these pins default to inputs at device reset. If the pins are to remain unused, an external pull-up is recommended to prevent the inputs from floating.

To use an external switch, use a pull-up, and connect the switch between the GPIO pin and ground, and poll the selected pin in register 58. The pull-up will return a high value, and a switch event will return a low value.

5. Programming

5.1. Special considerations

There are several registers that need to be correctly programmed for device operation. If custom Vendor ID/Product ID values are required, these registers should be programmed by an external Serial EEPROM before the USB controller accesses the part[†]. It is recommended that the Vendor ID and Product ID registers be programmed first. This allows the correct values to be set before the USB configuration after power-up. After that, the driver can look for a specific register value to indicate the end of Serial programming. During the initialization phase, if an external EEPROM is used, care must be taken by the driver to not access registers while the EEPROM is transferring data. The driver software should delay an appropriate time before accessing the registers.

Expansion RAM:

To access the internal 256Byte expansion RAM, load the RAA register with the desired address, and read or write the RAD register.

Device Programming:

The maximum size of a USB data transfer is 8 bytes. Transfers larger than this will not read/write the correct data values.

6. Electrical Characteristics

6.1. DC Characteristics

[†] Customization of the VID/PID is available at a cost for large volume orders.



1. Absolute Maximum Ratings

| Symbol | Parameter | Rating | | | Units |
|------------|-------------------------|---------|---------|----------------|-------|
| | | Minimum | Typical | Maximum | |
| V_{CCA} | Absolute Power Supply | -0.3 | | 3.8 | V |
| V_{INA} | Absolute Input Voltage | -0.3 | | $V_{CC} + 0.3$ | V |
| V_{OUTA} | Absolute Output Voltage | -0.3 | | $V_{CC} + 0.3$ | V |
| T_{STG} | Storage Temperature | 0 | 25 | 65 | °C |

2. Recommended Operating Conditions

| Symbol | Parameter | Rating | | | Units |
|-----------|-------------------------|---------|---------|----------|-------|
| | | Minimum | Typical | Maximum | |
| V_{CC} | Operating Power Supply | 3.0 | 3.3 | 3.6 | V |
| V_{IN} | Operating Input Voltage | 0 | | V_{CC} | V |
| T_{OPR} | Operating Temperature | 0 | 25 | 55 | °C |

3. General DC Characteristics

| Symbol | Parameter | Rating | | | Units |
|-----------|---|---------|---------|---------|-------|
| | | Minimum | Typical | Maximum | |
| I_{DD} | Operating Current @ $V_{CC}=3.3$ V, 25 °C | | 40 | | mA |
| I_{DDS} | Suspend Current @ $V_{CC}=3.3$ V, 25 °C | | | 500 | uA |
| I_{IL} | Input Low Current | -1 | | 1 | μA |
| I_{IH} | Input High Current | -1 | | 1 | μA |
| I_{OZ} | Tri-state Leakage Current | -10 | | 10 | μA |
| C_{IN} | Input Capacitance | | 3 | | pF |
| C_{OUT} | Output Capacitance | | 3 | | pF |



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| | | | | | |
|------------------|-----------------------------------|---|----|----|----|
| C _{BID} | Bi-directional Buffer Capacitance | | 3 | | pF |
| R _O | USB Output Impedance | 6 | | 18 | Ω |
| R _L | Input Pull-up/down Resistance | | 50 | | KΩ |

4. Electrical DC Characteristics

| Symbol | Parameter | Rating | | | Units |
|-----------------|-------------------------|---------|---------|---------|-------|
| | | Minimum | Typical | Maximum | |
| V _{CC} | Operating Power Supply | 3.0 | 3.3 | 3.6 | V |
| V _{OH} | Output High Voltage | 2.4 | | | V |
| V _{UL} | USB Output Low Voltage | | | 0.3 | V |
| V _{UH} | USB Output High Voltage | 2.8 | | | V |

6.2. Clocking

The ICM-532B clock is generated from an external low cost 6MHz crystal. The on-board PLL generates the required USB clock and the Video Clock. The nominal Video Clock rate is 8MHz. This rate can be altered by setting either the Fastclock (*1.5) or Slowclock (/2.0) register bits.

Video Timing examples:

At 8MHz, the Video clock generates 1 pixel every 250ns, a line (500 pixels) every 125us, and 8 lines every 1ms. This produces 8 lines to be packed into 1 USB data transfer, to make a 24 fps QVGA (352 x288) transfer rate.

At 12MHz, the Video clock generates 1 pixel every 166.7ns, a line (600 pixels) every 100us, and 10 lines every 1 ms. This produces 10 lines to be packed into 1 USB data transfer, to make a 30 fps QVGA (320x240) transfer rate.

At 12MHz, the Video clock generates 1 pixel every 166.7ns, a line (500 pixels) every 83.3us, and 12 lines every 1 ms. This produces 6 lines to be packed into 1 USB data transfer, to make a 35 fps QCIF (176 x 144) transfer rate.



6.3. AC Characteristics

| Symbol | Parameter | Rating | | | Units |
|-----------------|---------------------|---------|---------|---------|-------|
| | | Minimum | Typical | Maximum | |
| $T_{RISE/FALL}$ | USB Switching Times | 4 | 10 | 20 | ns |
| V_{CR} | USB Cross Point | 1.3 | | 2.0 | V |

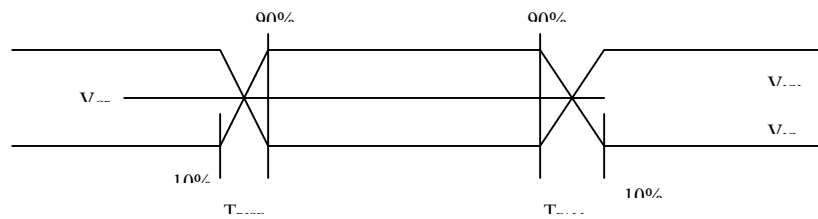


Figure 3. DP/DN Timing



7. Mechanical Information

ICM532B supports SPLCC (Plastic Shrink LCC48 Packaging) packaging. Note that pin 1 should point to the top of the camera when a lens and the default driver are used.

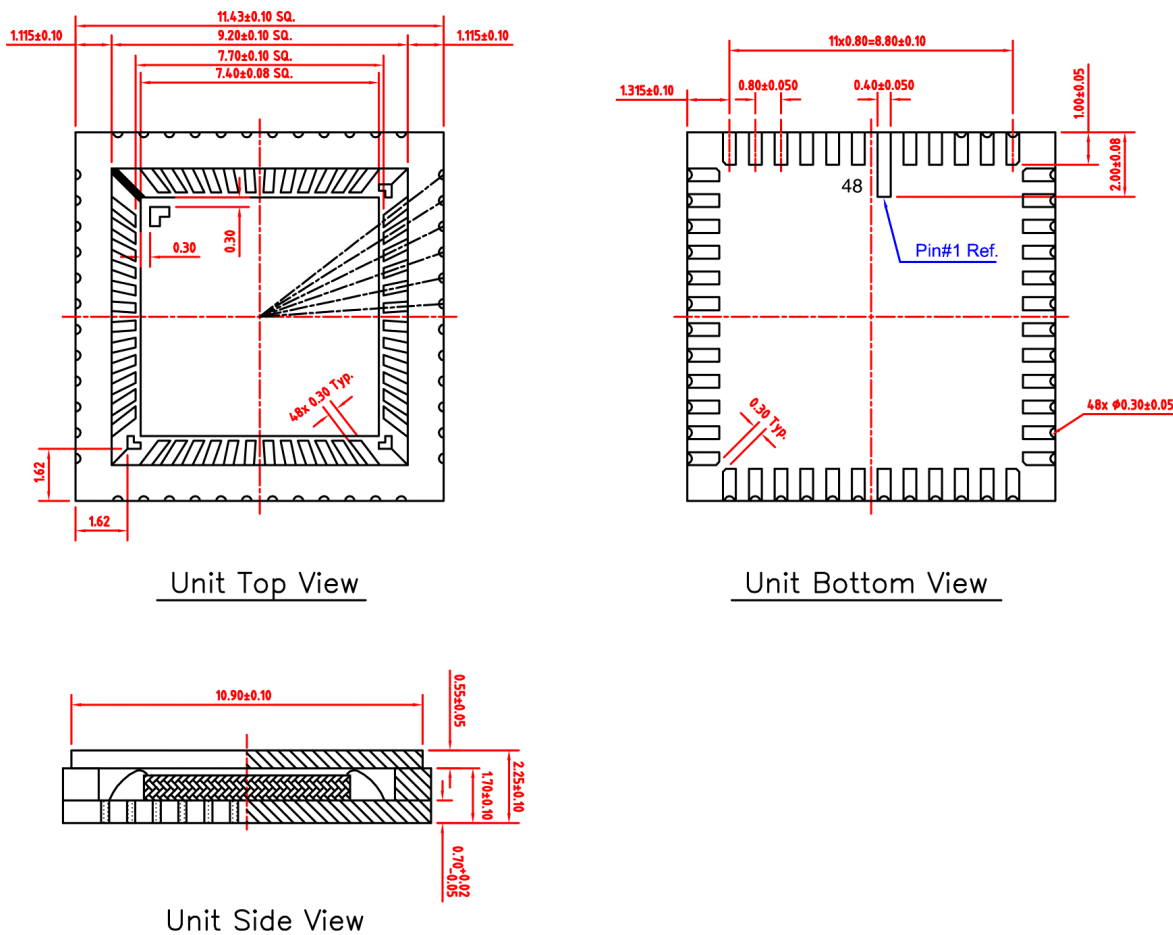


Figure 4. SPLCC48 Packaging

8. Board Design Information

Components:

- ICM-532B
- 6MHz Crystal
- RSET resistor
- USB connector or cable with 1.5kΩ pull-up on DP.
- 3.3v voltage regulator and associated components
- Power Supply filter capacitors
- Pull-up for SDA, SCL, GPIO0 GPIO1, and GPIO2
- If desired: Reset circuitry. A 0.1uF capacitor on RSTN is sufficient for power-on reset.



9. Ordering Information

Part number for different package:

| <i>Description</i> | <i>Part Number</i> |
|--|--------------------|
| Shrunk Plastic LCC48 package packaged, USB CIF resolution sensor (3.3 V) | ICM-532Bsa |

Contact Addresses:

IC Media Corporation

545 East Brokaw Road
San Jose, CA 95112, U.S.A.
Phone: (408) 451-8838
Fax: (408) 451-8839
Email: Sales@IC-Media.Com
Web Site: www.ic-media.com

IC Media Technology

6F, No. 61, ChowTze Street., NeiHu District
Taipei, Taiwan, R.O.C.
Phone: 886-2-2657-7898
Fax: 886-2-2657-8751
Email: Sales@IC-Media.Com
Web Site: www.ic-media.com