

3802 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

DESCRIPTION

The 3802 group is the 8-bit microcomputer based on the 740 family core technology.

The 3802 group is designed for controlling systems that require analog signal processing and include two serial I/O functions, A-D converters, and D-A converters.

The various microcomputers in the 3802 group include variations of internal memory size and packaging. For details, refer to the section on part numbering.

For details on availability of microcomputers in the 3802 group, refer to the section on group expansion.

FEATURES

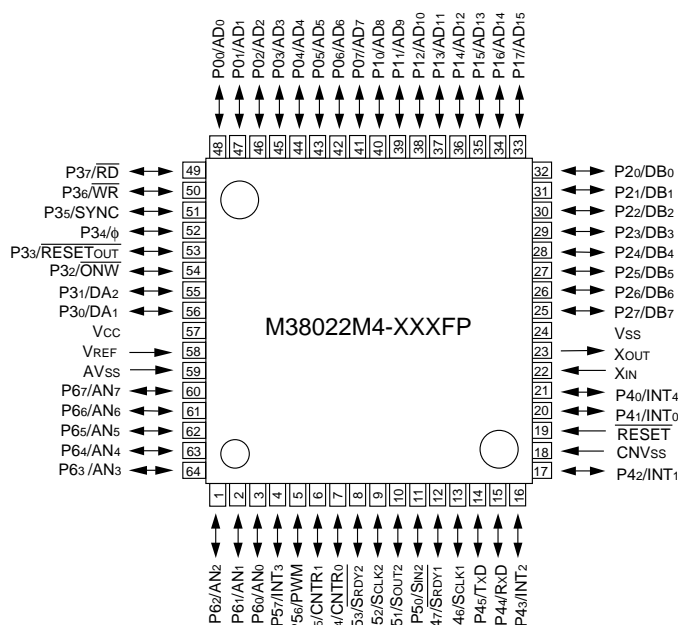
- Basic machine-language instructions 71
- The minimum instruction execution time 0.5 μ s
(at 8 MHz oscillation frequency)
- Memory size
 - ROM 8 K to 32 K bytes
 - RAM 384 to 1024 bytes

- Programmable input/output ports 56
- Interrupts 16 sources, 16 vectors
- Timers 8 bit X 4
- Serial I/O1 8-bit X 1 (UART or Clock-synchronized)
- Serial I/O2 8-bit X 1 (Clock-synchronized)
- PWM 8-bit X 1
- A-D converter 8-bit X 8 channels
- D-A converter 8-bit X 2 channels
- Clock generating circuit Internal feedback resistor
(connect to external ceramic resonator or quartz-crystal oscillator)
- Power source voltage 3.0 to 5.5 V
(Extended operating temperature version : 4.0 to 5.5 V)
- Power dissipation 32 mW
- Memory expansion possible
- Operating temperature range -20 to 85°C
(Extended operating temperature version : -40 to 85°C)

APPLICATIONS

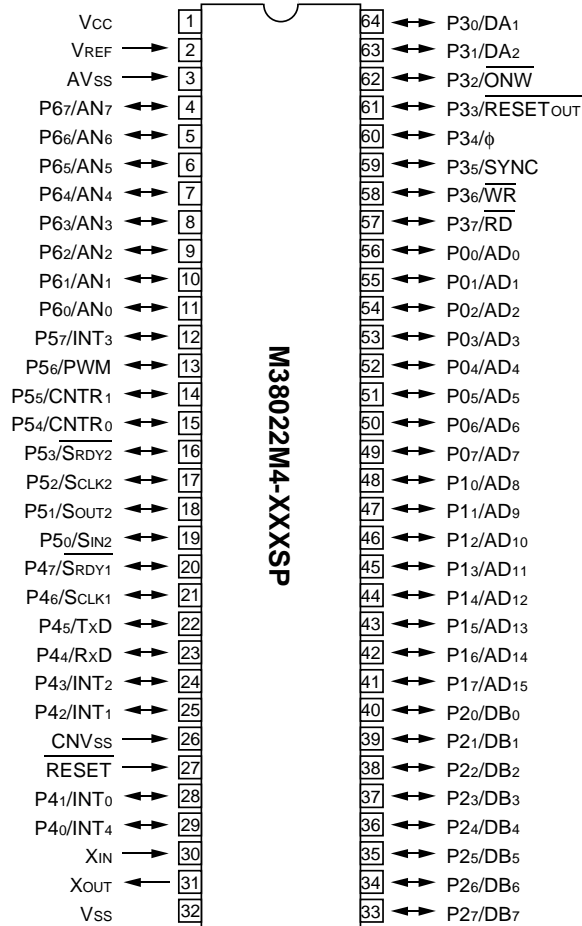
Office automation, VCRs, tuners, musical instruments, cameras, air conditioners, etc.

PIN CONFIGURATION (TOP VIEW)



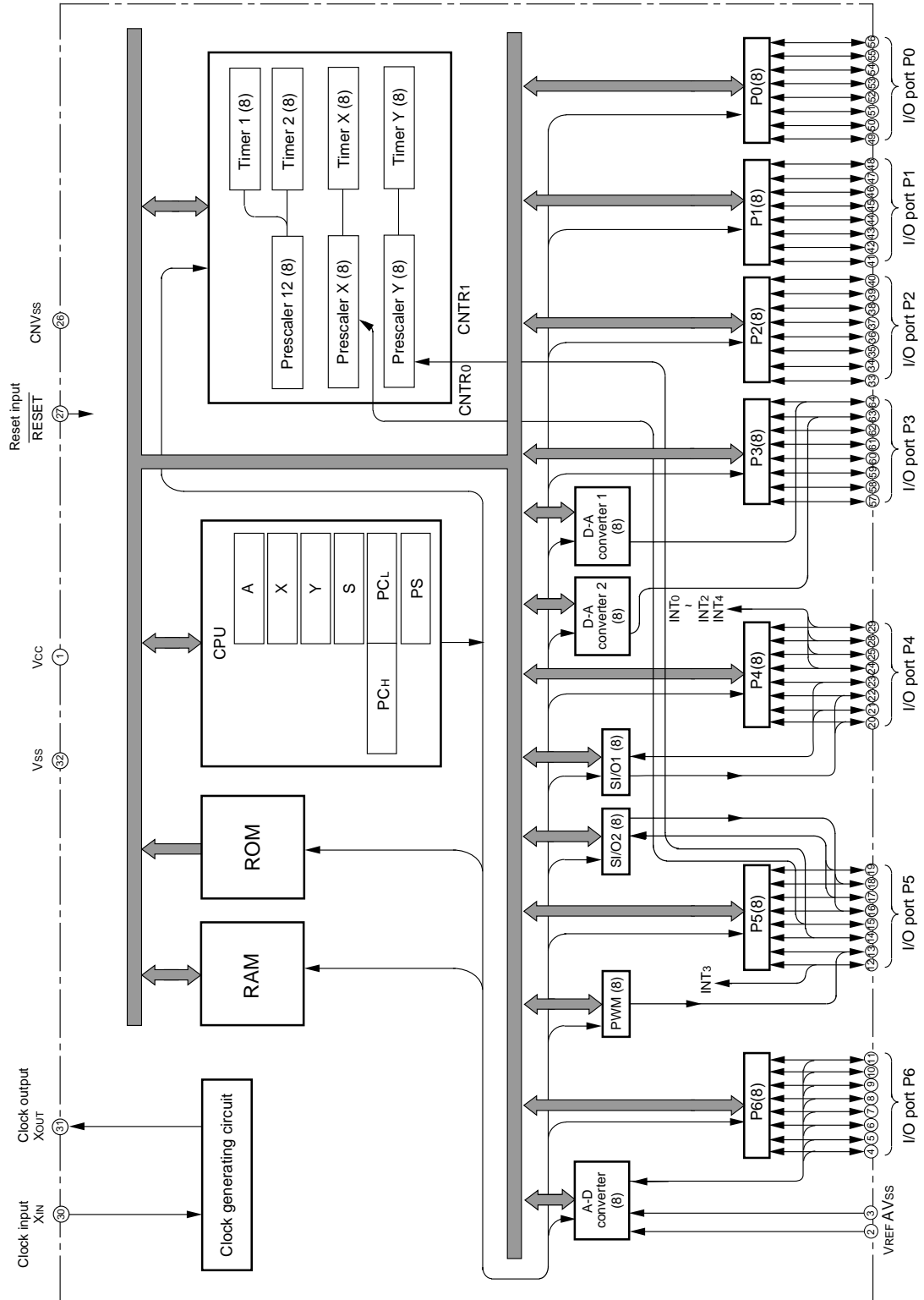
Package type : 64P6N-A
64-pin plastic-molded QFP

PIN CONFIGURATION (TOP VIEW)



Package type : 64P4B
64-pin shrink plastic-molded DIP

FUNCTIONAL BLOCK DIAGRAM (Package : 64P4B)



PIN DESCRIPTION

Pin	Name	Function		
			Function except a port function	
VCC, VSS	Power source	<ul style="list-style-type: none">• Apply voltage of 3.0 V–5.5 V to VCC, and 0 V to VSS. (Extended operating temperature version : 4.0 V to 5.5 V)		
CNVSS	CNVSS	<ul style="list-style-type: none">• This pin controls the operation mode of the chip.• Normally connected to VSS.• If this pin is connected to VCC, the internal ROM is inhibited and external memory is accessed.		
VREF	Analog reference voltage	<ul style="list-style-type: none">• Reference voltage input pin for A-D and D-A converters		
AVSS	Analog power source	<ul style="list-style-type: none">• GND input pin for A-D and D-A converters• Connect to VSS.		
$\overline{\text{RESET}}$	Reset input	<ul style="list-style-type: none">• Reset input pin for active “L”		
XIN	Clock input	<ul style="list-style-type: none">• Input and output signals for the clock generating circuit.• Connect a ceramic resonator or quartz-crystal oscillator between the XIN and XOUT pins to set the oscillation frequency.• If an external clock is used, connect the clock source to the XIN pin and leave the XOUT pin open.• The clock is used as the oscillating source of system clock.		
XOUT	Clock output			
P00–P07	I/O port P0	<ul style="list-style-type: none">• 8 bit CMOS I/O port• I/O direction register allows each pin to be individually programmed as either input or output.• At reset this port is set to input mode.• In modes other than single-chip, these pins are used as address, data, and control bus I/O pins.• CMOS compatible input level• CMOS 3-state output structure		
P10–P17	I/O port P1			
P20–P27	I/O port P2			
P30/DA1, P31/DA2	I/O port P3			<ul style="list-style-type: none">• D–A conversion output pins
P32–P37				
P40/INT4, P41/INT0, P42/INT1, P43/INT2	I/O port P4	<ul style="list-style-type: none">• 8-bit CMOS I/O port with the same function as port P0• CMOS compatible input level• CMOS 3-state output structure		
P44/RxD, P45/TxD, P46/SCLK1, P47/SDY1		<ul style="list-style-type: none">• External interrupt input pin• Serial I/O1 I/O pins		
P50/SIN2, P51/SOUT2, P52/SCLK2, P53/SDY2	I/O port P5	<ul style="list-style-type: none">• 8-bit CMOS I/O port with the same function as port P0• CMOS compatible input level• CMOS 3-state output structure		
P54/CNTR0, P55/CNTR1		<ul style="list-style-type: none">• Serial I/O2 I/O pins• Timer X and Timer Y I/O pins		
P56/PWM		<ul style="list-style-type: none">• PWM output pin		
P57/INT3		<ul style="list-style-type: none">• External interrupt input pin		
P60/AN0– P67/AN7	I/O port P6	<ul style="list-style-type: none">• 8-bit CMOS I/O port with the same function as port P0• CMOS compatible input level• CMOS 3-state output structure• A-D conversion input pins		

3802 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

GROUP EXPANSION

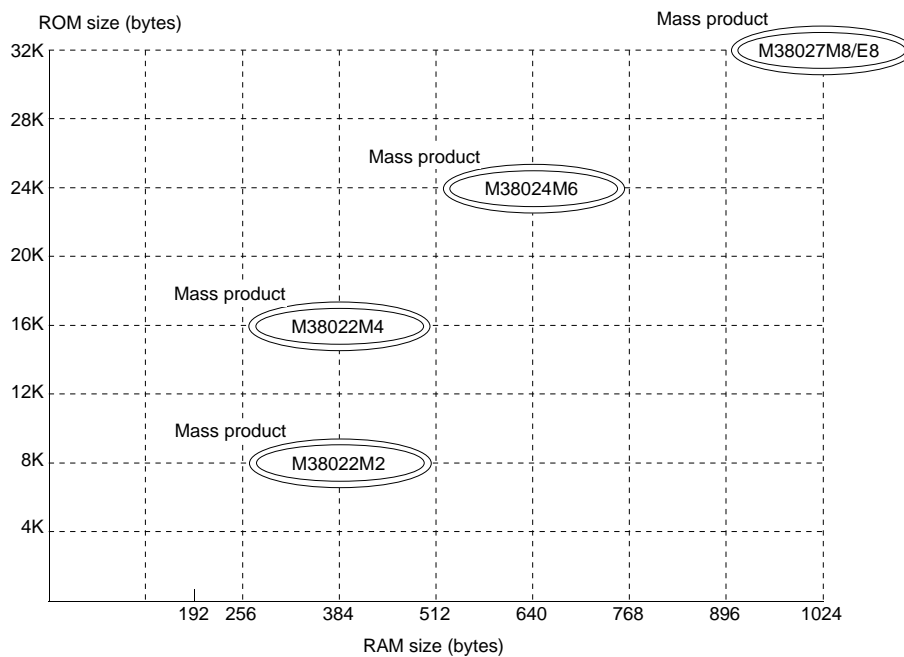
Mitsubishi plans to expand the 3802 group as follows:

- (1) Support for mask ROM, One Time PROM, and EPROM versions
 ROM/PROM capacity 8 K to 32 K bytes
 RAM capacity 384 to 1024 bytes

- (2) Packages

- 64P4B Shrink plastic molded DIP
 64P6N-A Plastic molded QFP
 64S1B-E Shrink ceramic DIP
 64D0 Ceramic LCC

Memory Expansion Plan



Currently supported products are listed below

As of May 1996

Product	(P) ROM size (bytes) ROM size for User in ()	RAM size (bytes)	Package	Remarks
M38022M2-XXXSP	8192 (8062)	384	64P4B	Mask ROM version
M38022M2-XXXFP			64P6N-A	Mask ROM version
M38022M4-XXXSP	16384 (16254)	384	64P4B	Mask ROM version
M38022M4-XXXFP			64P6N-A	Mask ROM version
M38024M6-XXXSP	24576 (24446)	640	64P4B	Mask ROM version
M38024M6-XXXFP			64P6N-A	Mask ROM version
M38027M8-XXXSP	32768 (32638)	1024	64P4B	Mask ROM version
M38027E8-XXXSP				One Time PROM version
M38027E8SP				One Time PROM version (blank)
M38027M8-XXXFP			64P6N-A	Mask ROM version
M38027E8-XXXFP				One Time PROM version
M38027E8FP				One Time PROM version (blank)
M38027E8SS			64S1B-E	EPROM version
M38027E8FS			64D0	EPROM version

3802 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

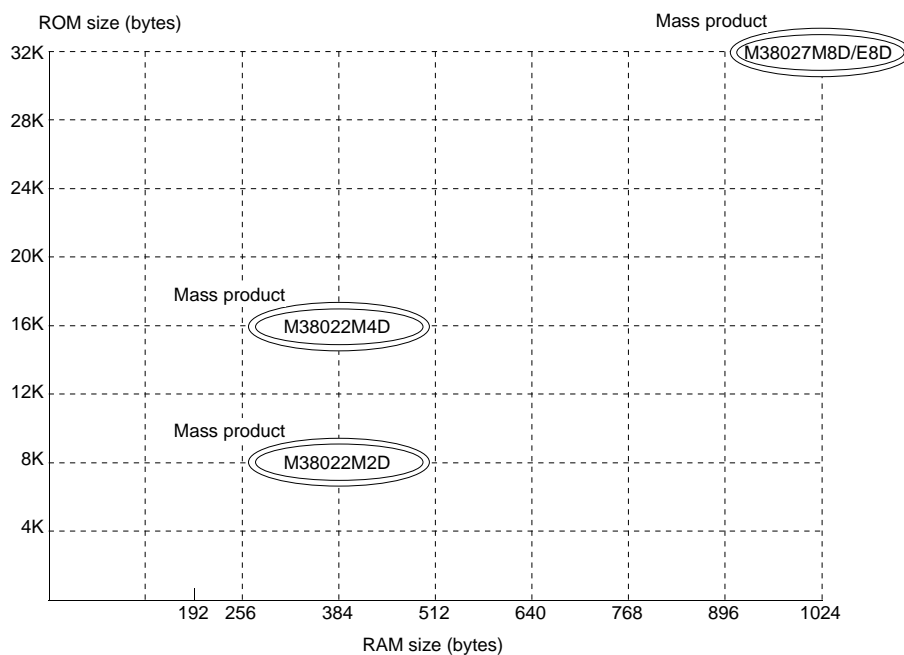
GROUP EXPANSION (Extended operating temperature version)

Mitsubishi plans to expand the 3802 group (extended operating temperature version) as follows:

- (1) Support for mask ROM One Time PROM, and EPROM versions
 ROM/PROM capacity 8 K to 32 K bytes
 RAM capacity 384 to 1024 bytes

- (2) Packages
 64P4B Shrink plastic molded DIP
 64P6N-A Plastic molded QFP

Memory Expansion Plan (Extended operating temperature version)



Currently supported products are listed below.

As of May 1996

Product	(P) ROM size (bytes)	RAM size (bytes)	Package	Remarks
M38022M2DXXXSP	8192	384	64P4B	Mask ROM version
M38022M2DXXXFP	(8062)		64P6N-A	Mask ROM version
M38022M4DXXXSP	16384	384	64P4B	Mask ROM version
M38022M4DXXXFP	(16254)		64P6N-A	Mask ROM version
M38027M8DXXXSP	32768 (32638)	1024	64P4B	Mask ROM version
M38027E8DXXXSP				One Time PROM version
M38027E8DSP				One Time PROM version (blank)
M38027M8DXXXFP			64P6N-A	Mask ROM version
M38027E8DXXXFP				One Time PROM version
M38027E8DFP				One Time PROM version (blank)

3802 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

PART NUMBERING

Product M3802 2 M 4 - XXX SP

Package type

SP : 64P4B package

FP : 64P6N-A package

SS : 64S1B-E package

FS : 64D0 package

ROM number

Omitted in some types.

Normally, using hyphen .

When electrical characteristic, or division of quality identification code using alphanumeric character

- : standard

D : Extended operating temperature version

ROM/PROM size

1 : 4096 bytes

2 : 8192 bytes

3 : 12288 bytes

4 : 16384 bytes

5 : 20480 bytes

6 : 24576 bytes

7 : 28672 bytes

8 : 32768 bytes

The first 128 bytes and the last 2 bytes of ROM are reserved areas ; they cannot be used.

Memory type

M : Mask ROM version

E : EPROM or One Time PROM version

RAM size

0 : 192 bytes

1 : 256 bytes

2 : 384 bytes

3 : 512 bytes

4 : 640 bytes

5 : 768 bytes

6 : 896 bytes

7 : 1024 bytes

FUNCTIONAL DESCRIPTION

Central Processing Unit (CPU)

The 3802 group uses the standard 740 family instruction set. Refer to the table of 740 family addressing modes and machine instructions or the SERIES 740 <Software> User's Manual for details on the instruction set.

Machine-resident 740 family instructions are as follows:

The FST and SLW instruction cannot be used.

The STP, WIT, MUL, and DIV instruction can be used.

CPU mode register

The CPU mode register is allocated at address 003B₁₆.

The CPU mode register contains the stack page selection bit.

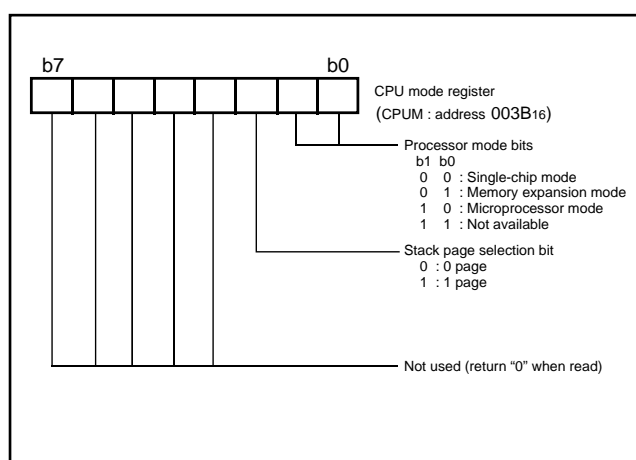


Fig. 1 Structure of CPU mode register

Memory

Special function register (SFR) area

The Special Function Register area in the zero page contains control registers such as I/O ports and timers.

RAM

RAM is used for data storage and for stack area of subroutine calls and interrupts.

ROM

The first 128 bytes and the last 2 bytes of ROM are reserved for device testing and the rest is user area for storing programs.

Interrupt vector area

The interrupt vector area contains reset and interrupt vectors.

Zero page

The 256 bytes from addresses 0000_{16} to $00FF_{16}$ are called the zero page area. The internal RAM and the special function registers (SFR) are allocated to this area.

The zero page addressing mode can be used to specify memory and register addresses in the zero page area. Access to this area with only 2 bytes is possible in the zero page addressing mode.

Special page

The 256 bytes from addresses $FF00_{16}$ to $FFFF_{16}$ are called the special page area. The special page addressing mode can be used to specify memory addresses in the special page area. Access to this area with only 2 bytes is possible in the special page addressing mode.

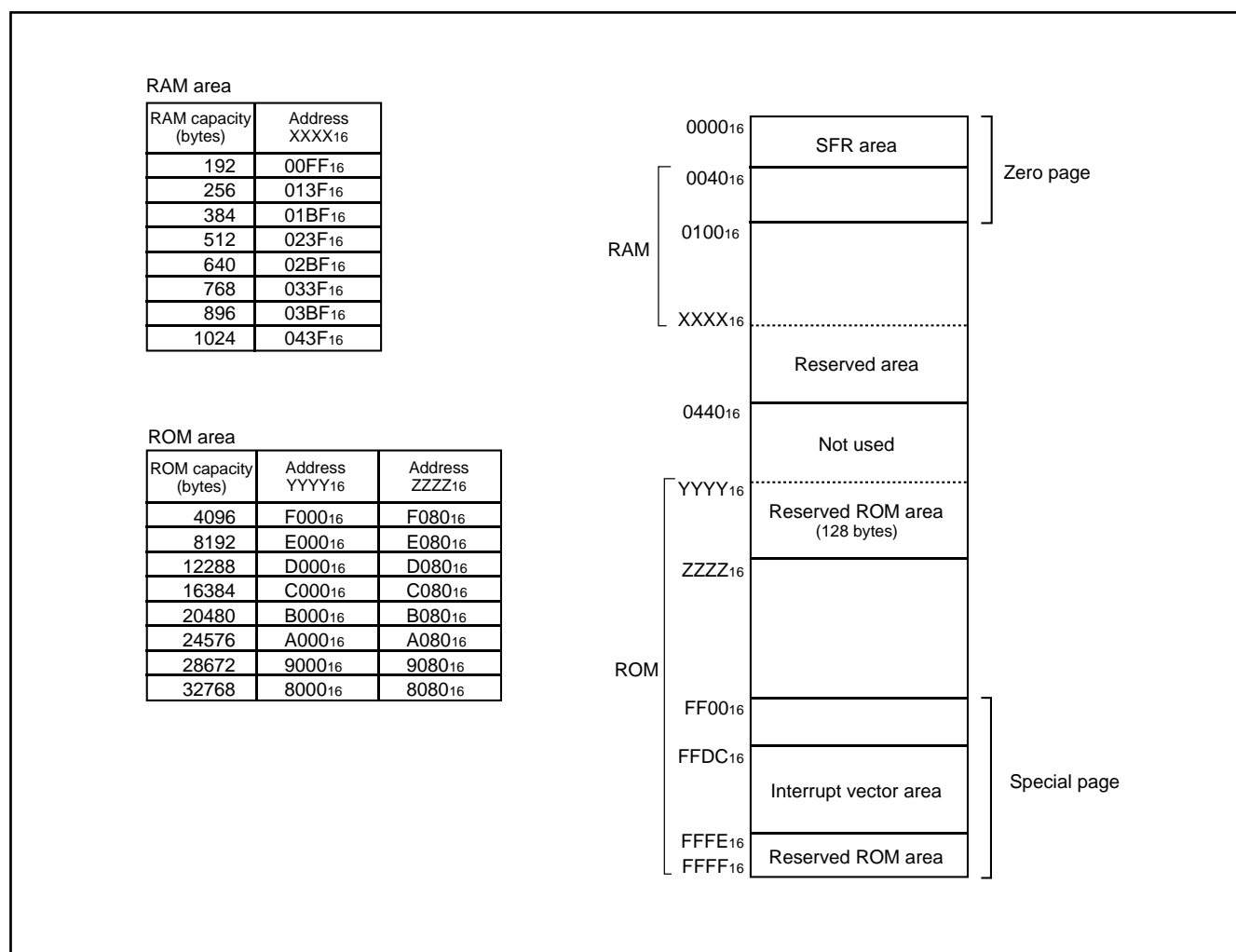


Fig. 2 Memory map diagram

0000 ₁₆	Port P0 (P0)	0020 ₁₆	Prescaler 12 (PRE12)
0001 ₁₆	Port P0 direction register (P0D)	0021 ₁₆	Timer 1 (T1)
0002 ₁₆	Port P1 (P1)	0022 ₁₆	Timer 2 (T2)
0003 ₁₆	Port P1 direction register (P1D)	0023 ₁₆	Timer XY mode register (TM)
0004 ₁₆	Port P2 (P2)	0024 ₁₆	Prescaler X (PREX)
0005 ₁₆	Port P2 direction register (P2D)	0025 ₁₆	Timer X (TX)
0006 ₁₆	Port P3 (P3)	0026 ₁₆	Prescaler Y (PREY)
0007 ₁₆	Port P3 direction register (P3D)	0027 ₁₆	Timer Y (TY)
0008 ₁₆	Port P4 (P4)	0028 ₁₆	
0009 ₁₆	Port P4 direction register (P4D)	0029 ₁₆	
000A ₁₆	Port P5 (P5)	002A ₁₆	
000B ₁₆	Port P5 direction register (P5D)	002B ₁₆	PWM control register (PWMCON)
000C ₁₆	Port P6 (P6)	002C ₁₆	PMW prescaler (PREPWM)
000D ₁₆	Port P6 direction register (P6D)	002D ₁₆	PWM register (PWM)
000E ₁₆		002E ₁₆	
000F ₁₆		002F ₁₆	
0010 ₁₆		0030 ₁₆	
0011 ₁₆		0031 ₁₆	
0012 ₁₆		0032 ₁₆	
0013 ₁₆		0033 ₁₆	
0014 ₁₆		0034 ₁₆	AD/DA control register (ADCON)
0015 ₁₆		0035 ₁₆	A-D conversion register (AD)
0016 ₁₆		0036 ₁₆	D-A1 conversion register (DA1)
0017 ₁₆		0037 ₁₆	D-A2 conversion register (DA2)
0018 ₁₆	Transmit/Receive buffer register (TB/RB)	0038 ₁₆	
0019 ₁₆	Serial I/O1 status register (SIO1STS)	0039 ₁₆	
001A ₁₆	Serial I/O1 control register (SIO1CON)	003A ₁₆	Interrupt edge selection register (INTEDGE)
001B ₁₆	UART control register (UARTCON)	003B ₁₆	CPU mode register (CPUM)
001C ₁₆	Baud rate generator (BRG)	003C ₁₆	Interrupt request register 1(IREQ1)
001D ₁₆	Serial I/O2 control register (SIO2CON)	003D ₁₆	Interrupt request register 2(IREQ2)
001E ₁₆		003E ₁₆	Interrupt control register 1(ICON1)
001F ₁₆	Serial I/O2 register (SIO2)	003F ₁₆	Interrupt control register 2(ICON2)

Fig. 3 Memory map of special function register (SFR)

3802 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

I/O Ports

Direction registers

The 3802 group has 56 programmable I/O pins arranged in seven I/O ports (ports P0 to P6). The I/O ports have direction registers which determine the input/output direction of each individual pin. Each bit in a direction register corresponds to one pin, each pin can be set to be input port or output port.

When "0" is written to the bit corresponding to a pin, that pin becomes an input pin. When "1" is written to that bit, that pin becomes an output pin.

If data is read from a pin which is set to output, the value of the port output latch is read, not the value of the pin itself. Pins set to input are floating. If a pin set to input is written to, only the port output latch is written to and the pin remains floating.

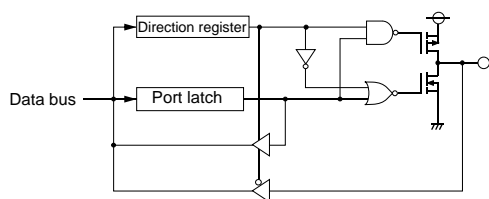
Pin	Name	Input/Output	I/O Format	Non-Port Function	Related SFRs	Ref.No.
P00–P07	Port P0	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	Address low-order byte output	CPU mode register	(1)
P10–P17	Port P1	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	Address high-order byte output	CPU mode register	
P20–P27	Port P2	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	Data bus I/O	CPU mode register	
P30/DA1 P31/DA2	Port P3	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	D-A conversion output	AD/DA control register CPU mode register	(2)
P32–P37				Control signal I/O	CPU mode register	(1)
P40/INT4, P41/INT0, P43/INT2	Port P4	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	External interrupt input	Interrupt edge selection register	(3)
P44/RxD, P45/TxD, P46/SCLK1, P47/SRDY1				Serial I/O1 function I/O	Serial I/O1 control register UART control register	(4)
						(5)
						(6)
						(7)
P50/SIN2, P51/SOUT2, P52/SCLK2, P53/SRDY2	Port P5	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	Serial I/O2 function I/O	Serial I/O2 control register	(8)
						(9)
						(10)
						(11)
P54/CNTR0, P55/CNTR1				Timer X and Timer Y function I/O	Timer XY mode register	(12)
P56/PWM				PWM output	PWM control register	(13)
P57/INT3				External interrupt input	Interrupt edge selection register	(3)
P60/AN0– P67/AN7	Port P6	Input/output, individual bits	CMOS 3-state output CMOS compatible input level	A-D conversion input		(14)

Note 1: For details of the functions of ports P0 to P3 in modes other than single-chip mode, and how to use double-function ports as function I/O ports, refer to the applicable sections.

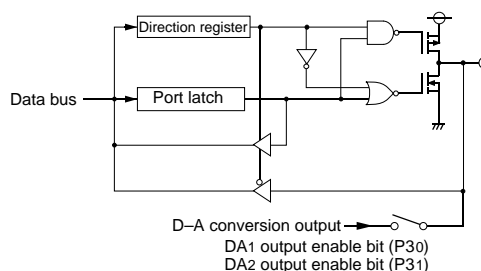
2: Make sure that the input level at each pin is either 0 V or V_{CC} during execution of the STP instruction.

When an input level is at an intermediate potential, a current will flow from V_{CC} to V_{SS} through the input-stage gate.

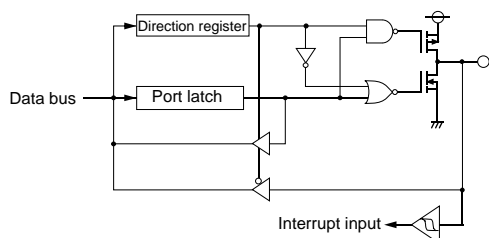
(1) Ports P0, P1, P2, P32-P37



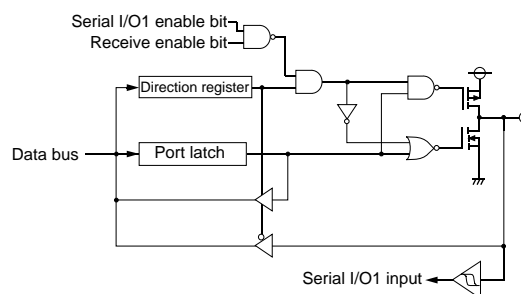
(2) Ports P30, P31



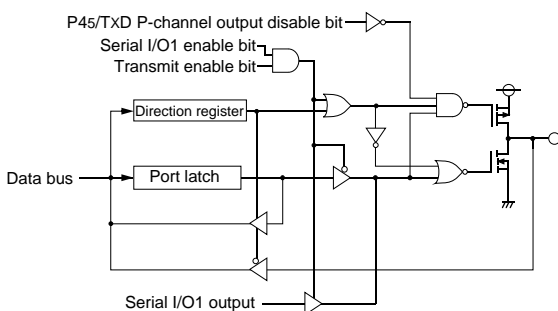
(3) Ports P40-P43, P57



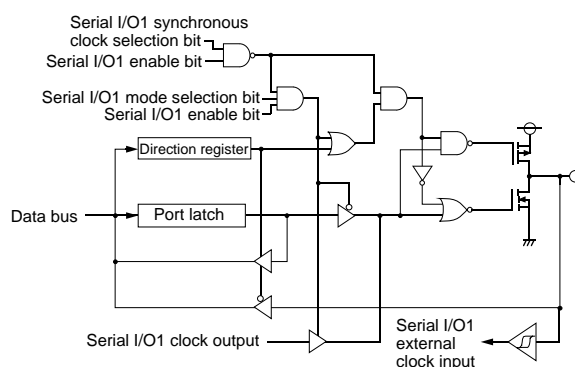
(4) Port P44



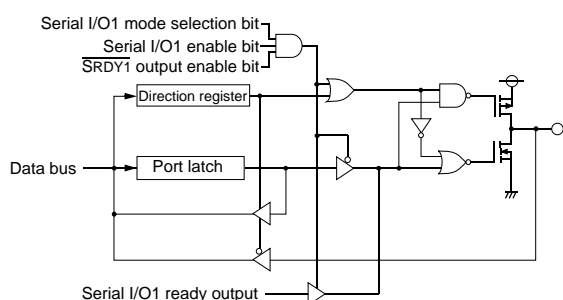
(5) Port P45



(6) Port P46



(7) Port P47



(8) Port P50

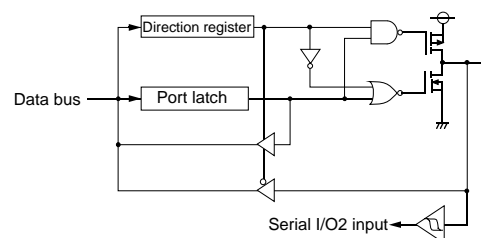
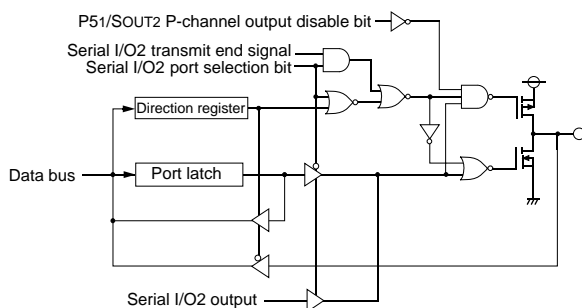
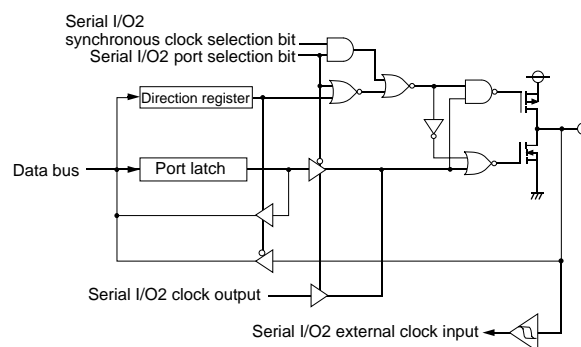


Fig. 4 Port block diagram (single-chip mode) (1)

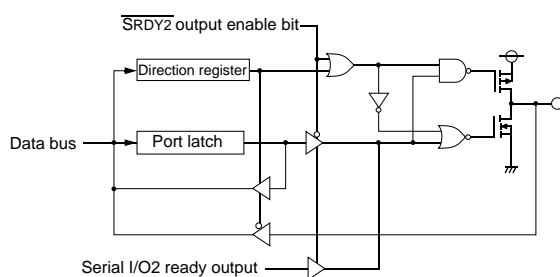
(9) Port P51



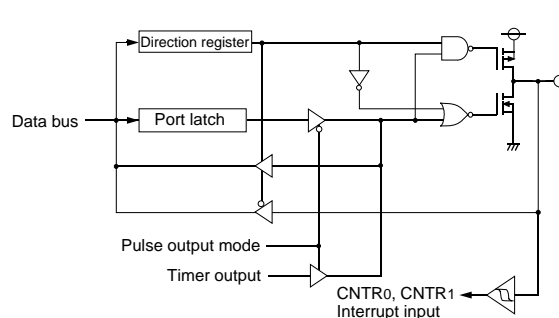
(10) Port P52



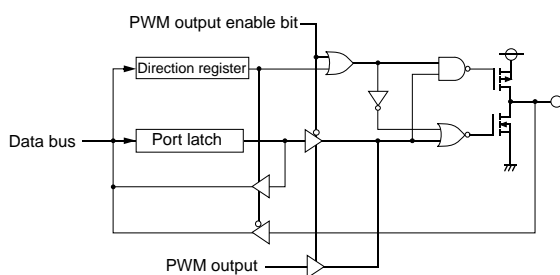
(11) Port P53



(12) Ports P54, 55



(13) Port P56



(14) Port P6

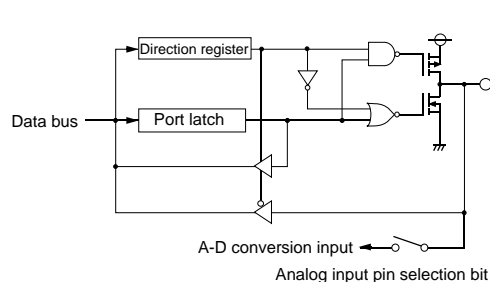


Fig. 5 Port block diagram (single-chip mode) (2)

INTERRUPTS

Interrupts occur by sixteen sources: seven external, eight internal, and one software.

Interrupt control

Each interrupt is controlled by an interrupt request bit, an interrupt enable bit, and the interrupt disable flag except for the software interrupt set by the BRK instruction. An interrupt occurs if the corresponding interrupt request and enable bits are "1" and the interrupt disable flag is "0".

Interrupt enable bits can be set or cleared by software.

Interrupt request bits can be cleared by software, but cannot be set by software.

The BRK instruction cannot be disabled with any flag or bit. The I (interrupt disable) flag disables all interrupts except the BRK instruction interrupt.

When several interrupts occur at the same time, the interrupts are received according to priority.

Interrupt operation

When an interrupt is received, the contents of the program counter and processor status register are automatically stored into the stack. The interrupt disable flag is set to inhibit other interrupts from interfering. The corresponding interrupt request bit is cleared and the interrupt jump destination address is read from the vector table into the program counter.

Notes on use

When the active edge of an external interrupt (INT₀ to INT₄, CNTR₀, or CNTR₁) is changed, the corresponding interrupt request bit may also be set. Therefore, please take following sequence;

- (1) Disable the external interrupt which is selected.
- (2) Change the active edge selection.
- (3) Clear the interrupt request bit which is selected to "0".
- (4) Enable the external interrupt which is selected.

Table 1. Interrupt vector addresses and priority

Interrupt Source	Priority	Vector Addresses (Note 1)		Interrupt Request Generating Conditions	Remarks
		High	Low		
Reset (Note 2)	1	FFFD ₁₆	FFFC ₁₆	At reset	Non-maskable
INT ₀	2	FFFB ₁₆	FFFA ₁₆	At detection of either rising or falling edge of INT ₀ input	External interrupt (active edge selectable)
INT ₁	3	FFF9 ₁₆	FFF8 ₁₆	At detection of either rising or falling edge of INT ₁ input	External interrupt (active edge selectable)
Serial I/O1 reception	4	FFF7 ₁₆	FFF6 ₁₆	At completion of serial I/O1 data reception	Valid when serial I/O1 is selected
Serial I/O1 transmission	5	FFF5 ₁₆	FFF4 ₁₆	At completion of serial I/O1 transfer shift or when transmission buffer is empty	Valid when serial I/O1 is selected
Timer X	6	FFF3 ₁₆	FFF2 ₁₆	At timer X underflow	
Timer Y	7	FFF1 ₁₆	FFF0 ₁₆	At timer Y underflow	
Timer 1	8	FFEF ₁₆	FFEE ₁₆	At timer 1 underflow	STP release timer underflow
Timer 2	9	FFED ₁₆	FFEC ₁₆	At timer 2 underflow	
CNTR ₀	10	FFEB ₁₆	FFEA ₁₆	At detection of either rising or falling edge of CNTR ₀ input	External interrupt (active edge selectable)
CNTR ₁	11	FFE9 ₁₆	FFE8 ₁₆	At detection of either rising or falling edge of CNTR ₁ input	External interrupt (active edge selectable)
Serial I/O2	12	FFE7 ₁₆	FFE6 ₁₆	At completion of serial I/O2 data transfer	Valid when serial I/O2 is selected
INT ₂	13	FFE5 ₁₆	FFE4 ₁₆	At detection of either rising or falling edge of INT ₂ input	External interrupt (active edge selectable)
INT ₃	14	FFE3 ₁₆	FFE2 ₁₆	At detection of either rising or falling edge of INT ₃ input	External interrupt (active edge selectable)
INT ₄	15	FFE1 ₁₆	FFE0 ₁₆	At detection of either rising or falling edge of INT ₄ input	External interrupt (active edge selectable)
A-D converter	16	FFDF ₁₆	FFDE ₁₆	At completion of A-D conversion	
BRK instruction	17	FFDD ₁₆	FFDC ₁₆	At BRK instruction execution	Non-maskable software interrupt

Note 1: Vector addresses contain interrupt jump destination addresses.

Note 2: Reset function in the same way as an interrupt with the highest priority.

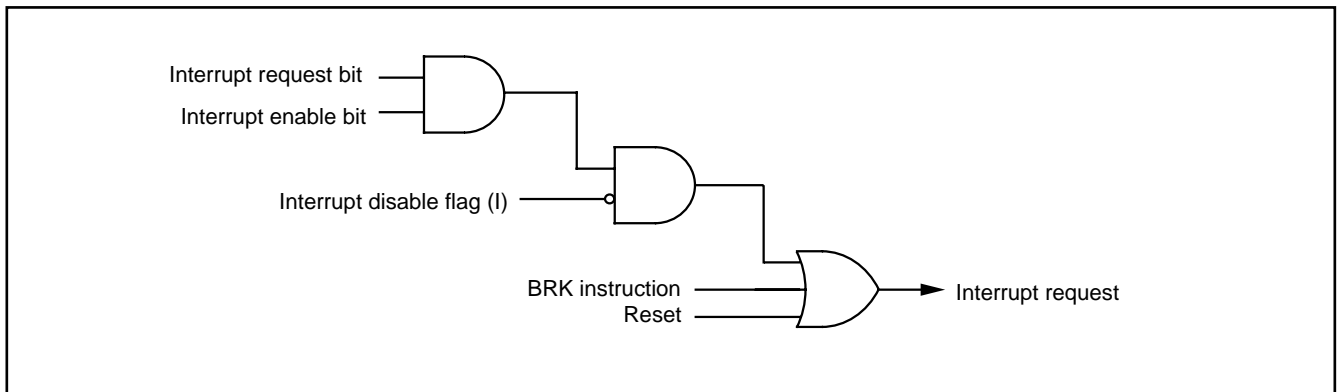


Fig. 6 Interrupt control

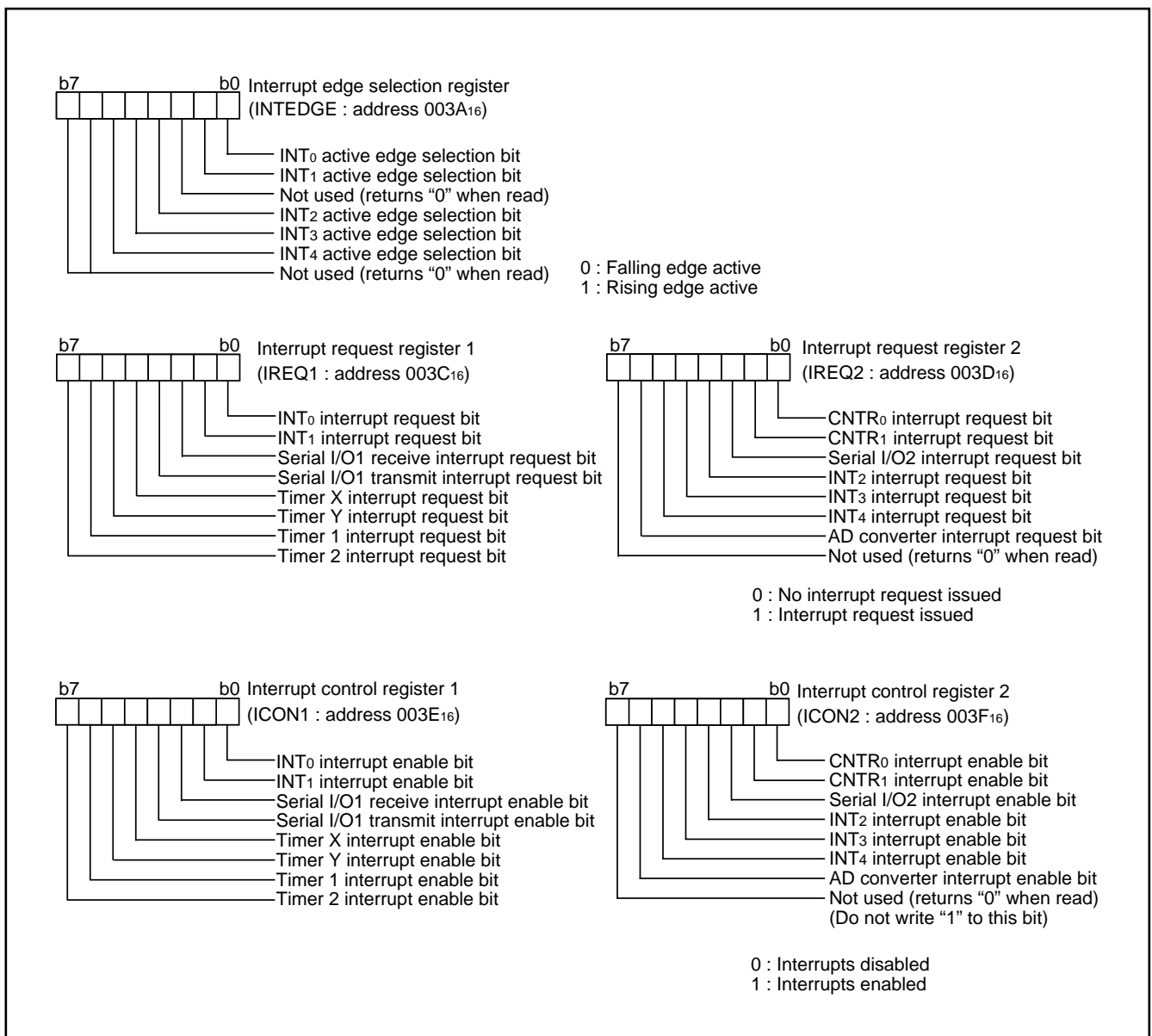


Fig. 7 Structure of interrupt-related registers

Timers

The 3802 group has four timers: timer X, timer Y, timer 1, and timer 2.

All timers are count down. When the timer reaches "0016", an underflow occurs at the next count pulse and the corresponding timer latch is reloaded into the timer and the count is continued. When a timer underflows, the interrupt request bit corresponding to that timer is set to "1".

The division ratio of each timer or prescaler is given by $1/(n + 1)$, where n is the value in the corresponding timer or prescaler latch.

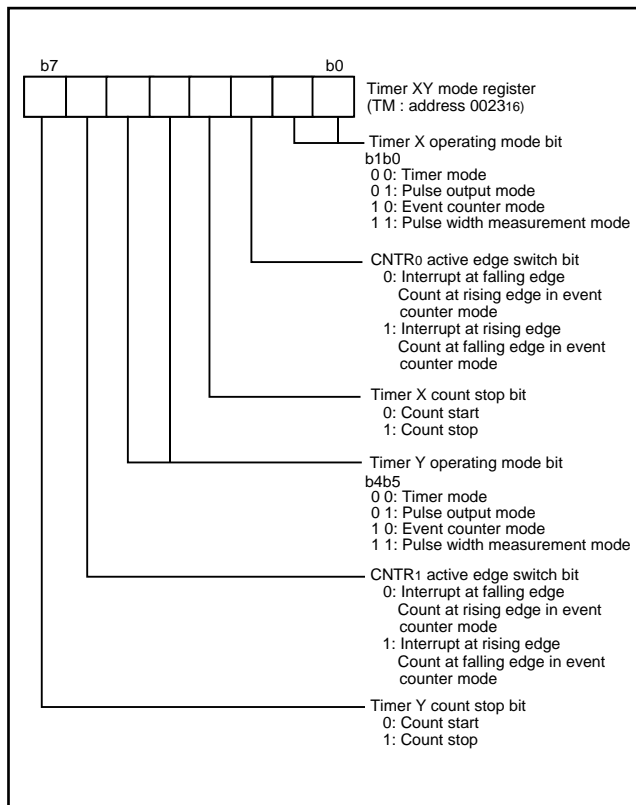


Fig. 8 Structure of timer XY register

Timer 1 and Timer 2

The count source of prescaler 12 is the oscillation frequency divided by 16. The output of prescaler 12 is counted by timer 1 and timer 2, and a timer underflow sets the interrupt request bit.

Timer X and Timer Y

Timer X and Timer Y can each be selected in one of four operating modes by setting the timer XY mode register.

Timer Mode

The timer counts $f(XIN)/16$ in timer mode.

Pulse Output Mode

Timer X (or timer Y) counts $f(XIN)/16$. Whenever the contents of the timer reach "0016", the signal output from the CNTR0 (or CNTR1) pin is inverted. If the CNTR0 (or CNTR1) active edge switch bit is "0", output begins at "H".

If it is "1", output starts at "L". When using a timer in this mode, set the corresponding port P54 (or port P55) direction register to output mode.

Event Counter Mode

Operation in event counter mode is the same as in timer mode, except the timer counts signals input through the CNTR0 or CNTR1 pin.

Pulse Width Measurement Mode

If the CNTR0 (or CNTR1) active edge selection bit is "0", the timer counts at the oscillation frequency divided by 16 while the CNTR0 (or CNTR1) pin is at "H". If the CNTR0 (or CNTR1) active edge switch bit is "1", the count continues during the time that the CNTR0 (or CNTR1) pin is at "L".

In all of these modes, the count can be stopped by setting the timer X (timer Y) count stop bit to "1". Every time a timer underflows, the corresponding interrupt request bit is set.

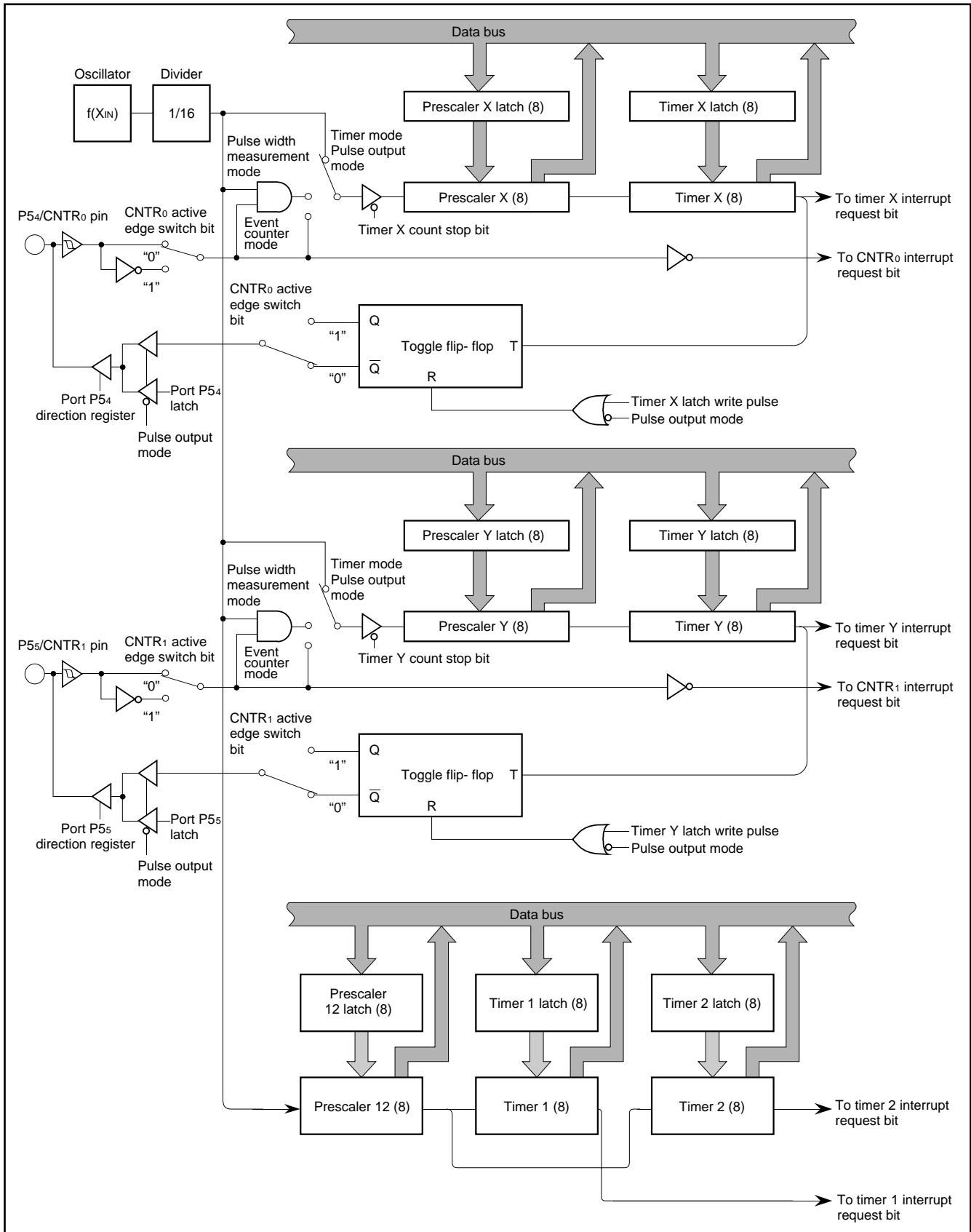


Fig. 9 Block diagram of timer X, timer Y, timer 1, and timer 2

Asynchronous serial I/O (UART) mode

Clock asynchronous serial I/O mode (UART) can be selected by clearing the serial I/O mode selection bit of the serial I/O control register to "0".

Eight serial data transfer formats can be selected, and the transfer formats used by a transmitter and receiver must be identical.

The transmit and receive shift registers each have a buffer, but the

two buffers have the same address in memory. Since the shift register cannot be written to or read from directly, transmit data is written to the transmit buffer, and receive data is read from the receive buffer.

The transmit buffer can also hold the next data to be transmitted, and the receive buffer can hold a character while the next character is being received.

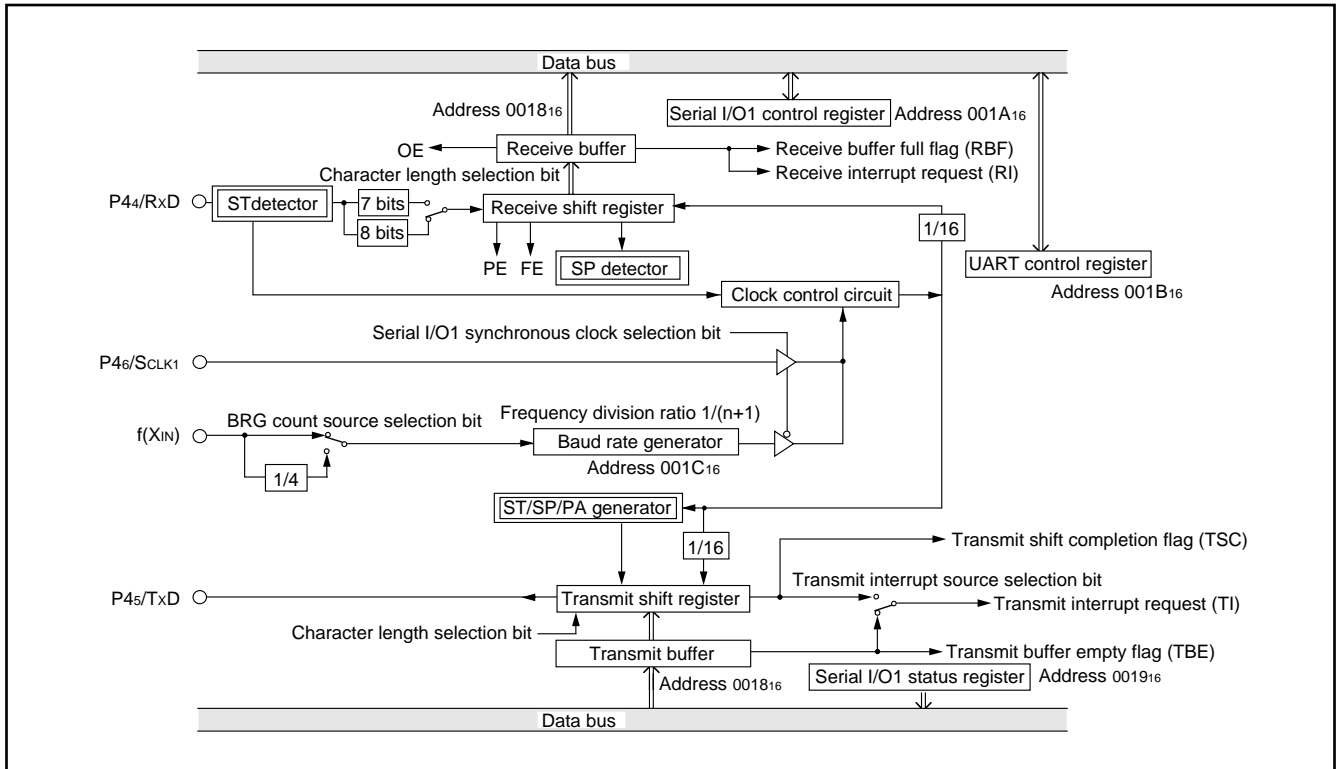


Fig. 12 Block diagram of UART serial I/O

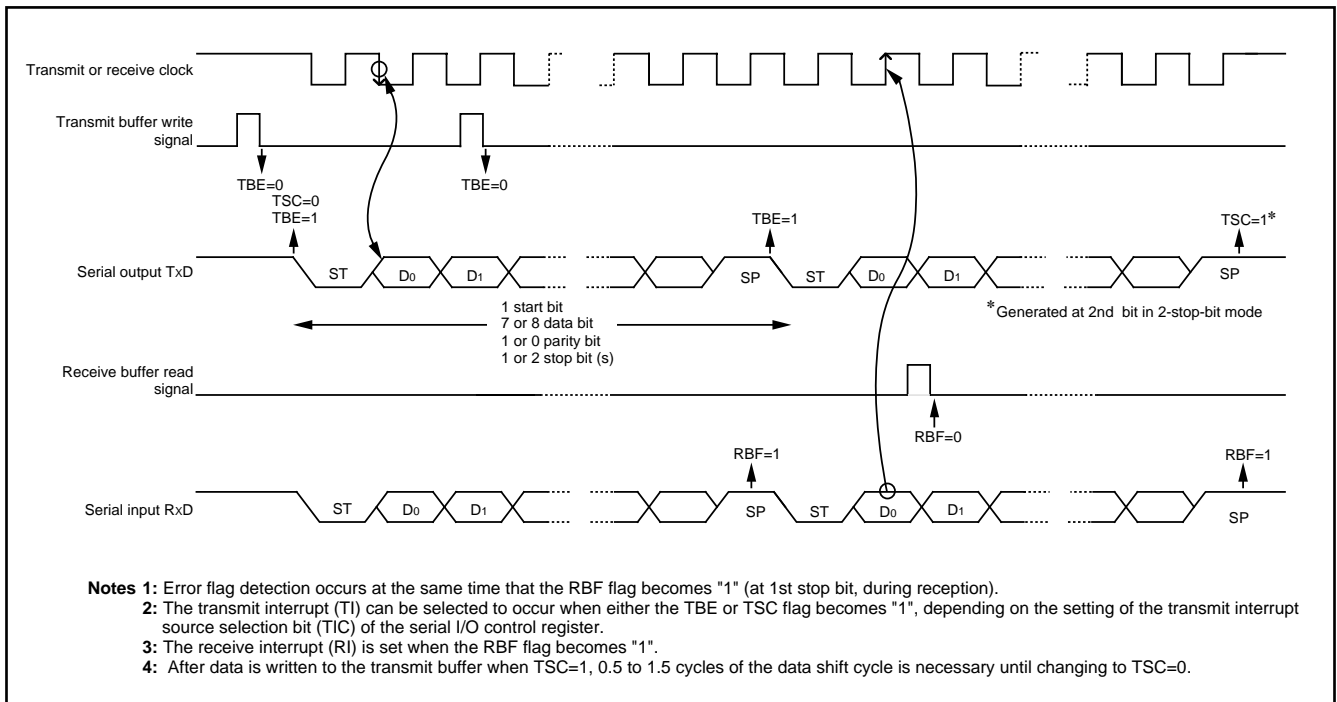


Fig. 13 Operation of UART serial I/O function

Serial I/O1 control register (SIO1CON) 001A16

The serial I/O control register consists of eight control bits for the serial I/O function.

UART control register (UARTCON) 001B16

The UART control register consists of four control bits (bits 0 to 3) which are valid when asynchronous serial I/O is selected and set the data format of an data transfer. One bit in this register (bit 4) is always valid and sets the output structure of the P45/TxD pin.

Serial I/O1 status register (SIO1STS) 001916

The read-only serial I/O1 status register consists of seven flags (bits 0 to 6) which indicate the operating status of the serial I/O function and various errors.

Three of the flags (bits 4 to 6) are valid only in UART mode.

The receive buffer full flag (bit 1) is cleared to "0" when the receive buffer is read.

If there is an error, it is detected at the same time that data is transferred from the receive shift register to the receive buffer, and the receive buffer full flag is set. A write to the serial I/O status register clears all the error flags OE, PE, FE, and SE (bit 3 to bit 6, re-

spectively). Writing "0" to the serial I/O enable bit SIOE (bit 7 of the Serial I/O Control Register) also clears all the status flags, including the error flags.

All bits of the serial I/O1 status register are initialized to "0" at reset, but if the transmit enable bit (bit 4) of the serial I/O control register has been set to "1", the transmit shift completion flag (bit 2) and the transmit buffer empty flag (bit 0) become "1".

Transmit buffer/Receive buffer register (TB/RB) 001816

The transmit buffer and the receive buffer are located at the same address. The transmit buffer is write-only and the receive buffer is read-only. If a character bit length is 7 bits, the MSB of data stored in the receive buffer is "0".

Baud rate generator (BRG) 001C16

The baud rate generator determines the baud rate for serial transfer.

The baud rate generator divides the frequency of the count source by $1/(n + 1)$, where n is the value written to the baud rate generator.

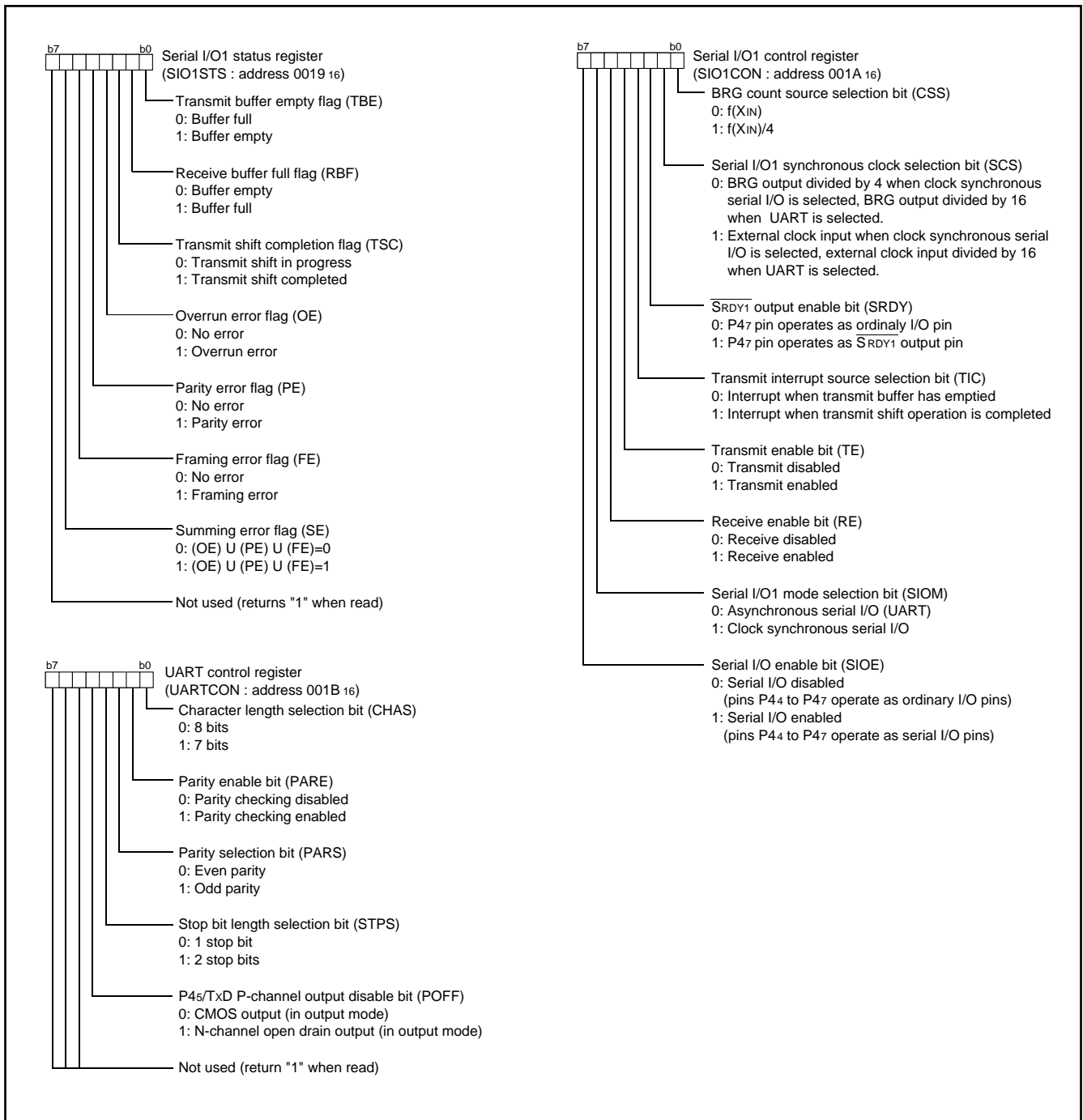


Fig. 14 Structure of serial I/O control registers

Serial I/O2

The serial I/O2 function can be used only for clock synchronous serial I/O.

For clock synchronous serial I/O the transmitter and the receiver must use the same clock. If the internal clock is used, transfer is started by a write signal to the serial I/O2 register.

Serial I/O2 control register (SIO2CON) 001D16

The serial I/O2 control register contains seven bits which control various serial I/O functions.

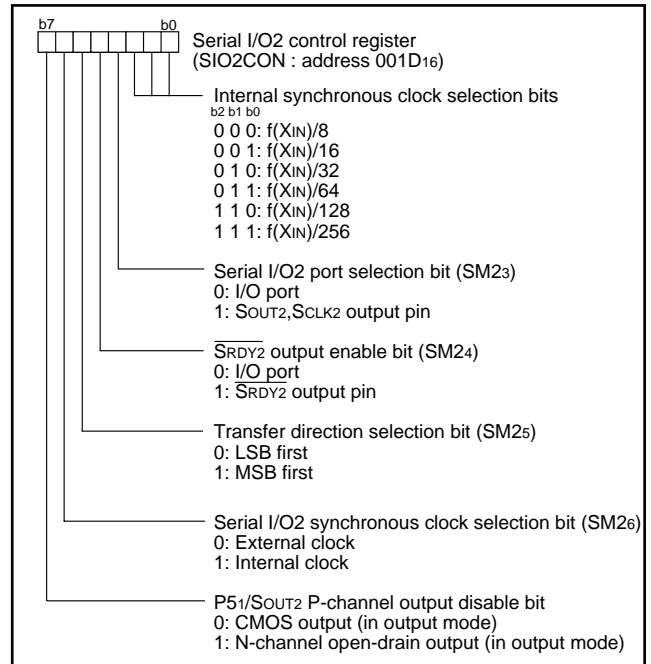


Fig. 15 Structure of serial I/O2 control register

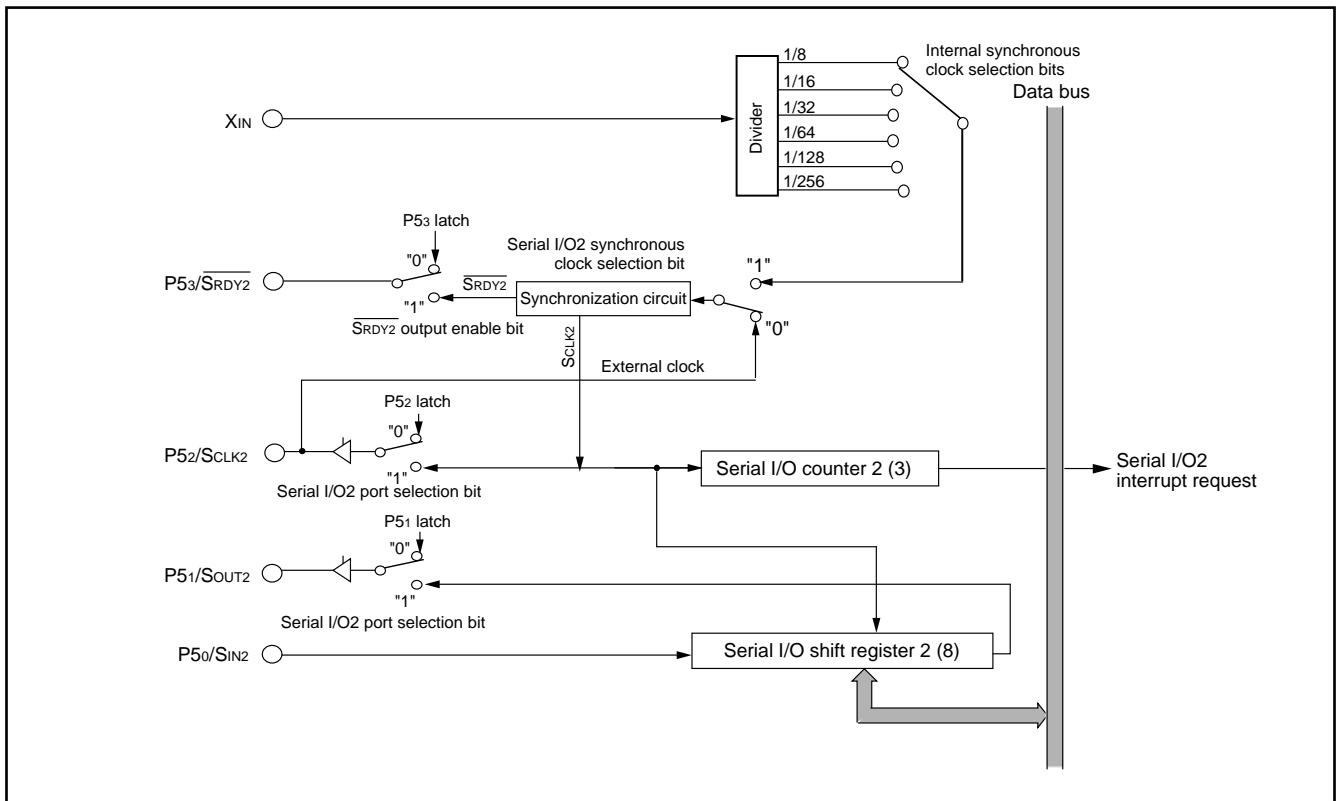


Fig. 16 Block diagram of serial I/O2 function

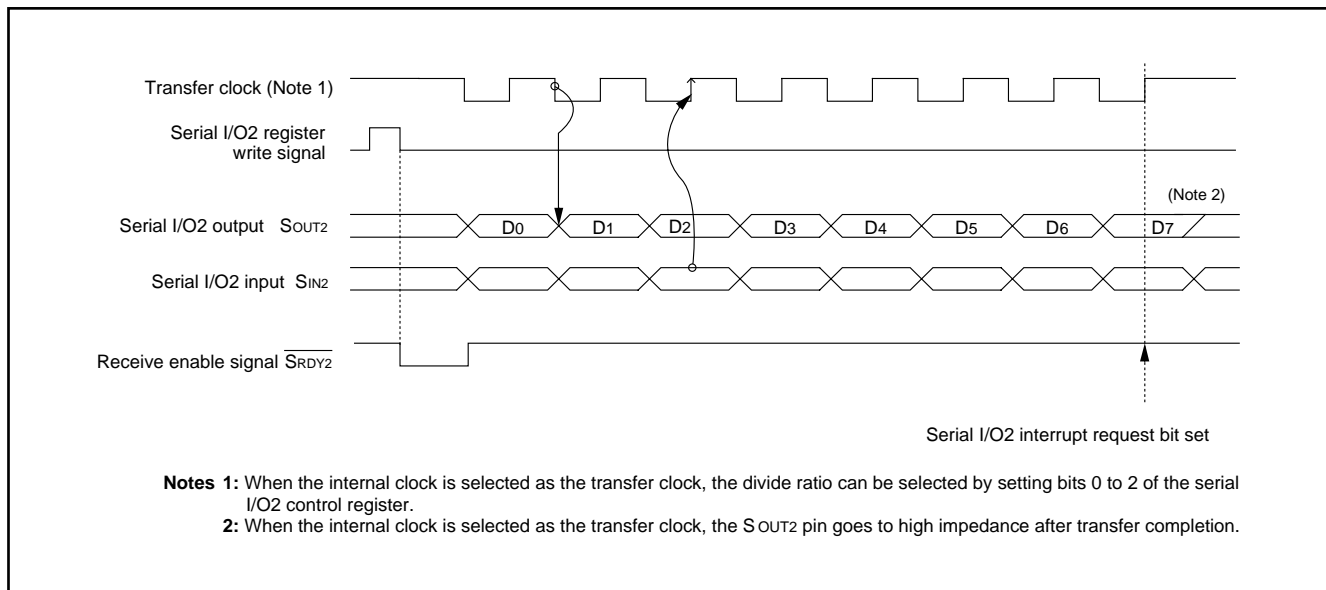


Fig. 17 Timing of serial I/O2 function

PULSE WIDTH MODULATION (PWM)

The 3802 group has a PWM function with an 8-bit resolution, based on a signal that is the clock input X_{IN} or that clock input divided by 2.

Data Setting

The PWM output pin also functions as port P5₆. Set the PWM period by the PWM prescaler, and set the period during which the output pulse is an "H" by the PWM register.

If the value in the PWM prescaler is n and the value in the PWM register is m (where $n = 0$ to 255 and $m = 0$ to 255) :

$$\begin{aligned} \text{PWM period} &= 255 \times (n+1) / f(X_{IN}) \\ &= 51 \times (n+1) \mu s \text{ (when } X_{IN} = 5 \text{ MHz)} \end{aligned}$$

$$\begin{aligned} \text{Output pulse "H" period} &= \text{PWM period} \times m / 255 \\ &= 0.2 \times (n+1) \times m \mu s \\ &\text{(when } X_{IN} = 5 \text{ MHz)} \end{aligned}$$

PWM Operation

When bit 0 (PWM enable bit) of the PWM control register is set to "1", operation starts by initializing the PWM output circuit, and pulses are output starting at an "H".

If the PWM register or PWM prescaler is updated during PWM output, the pulses will change in the cycle after the one in which the change was made.

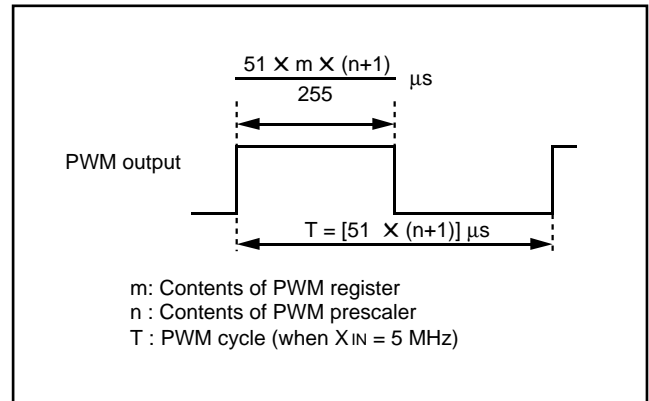


Fig. 18 Timing of PWM cycle

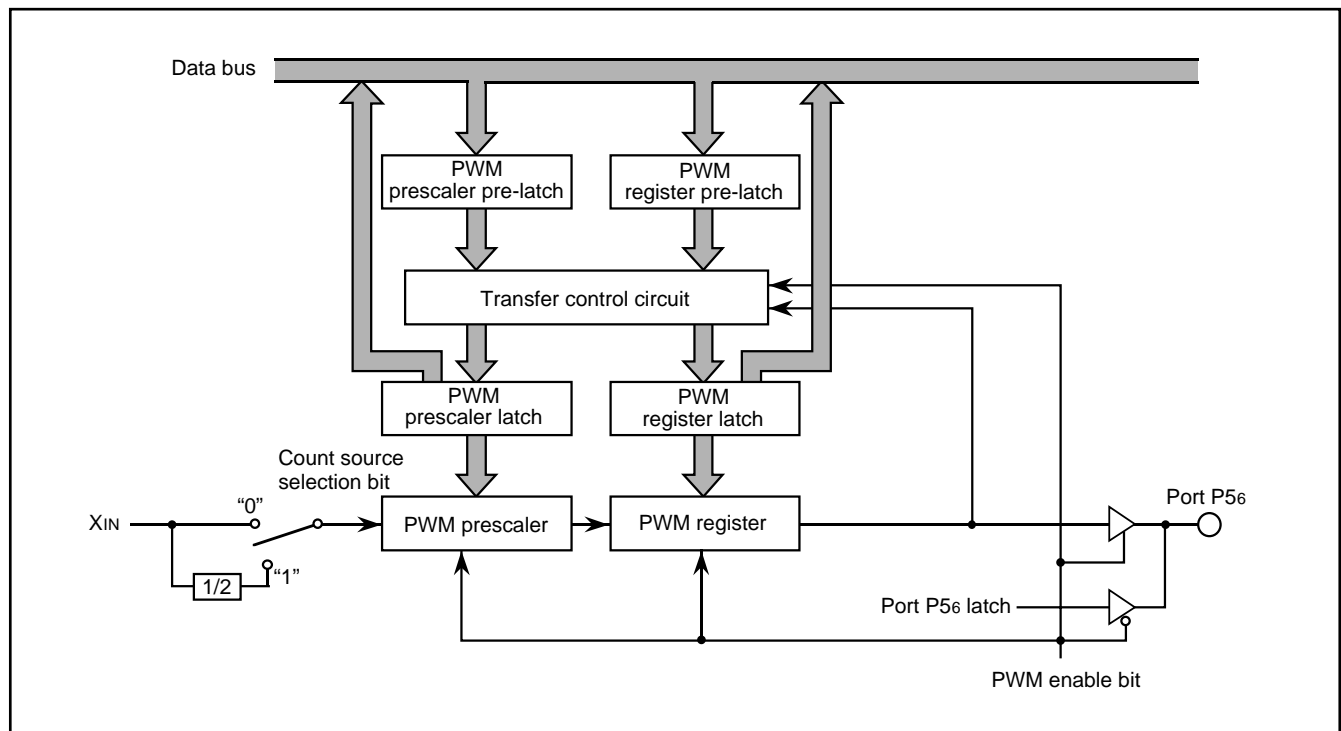


Fig. 19 Block diagram of PWM function

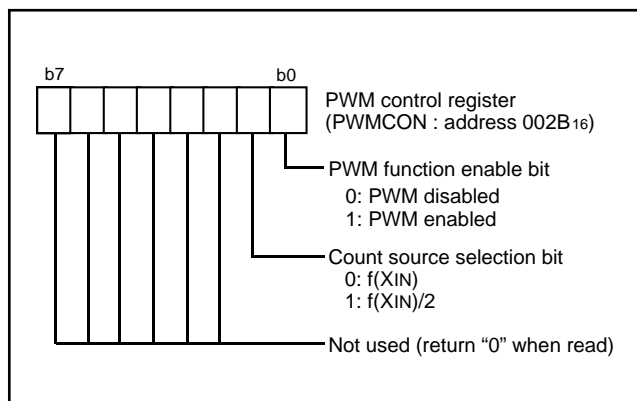


Fig. 20 Structure of PWM control register

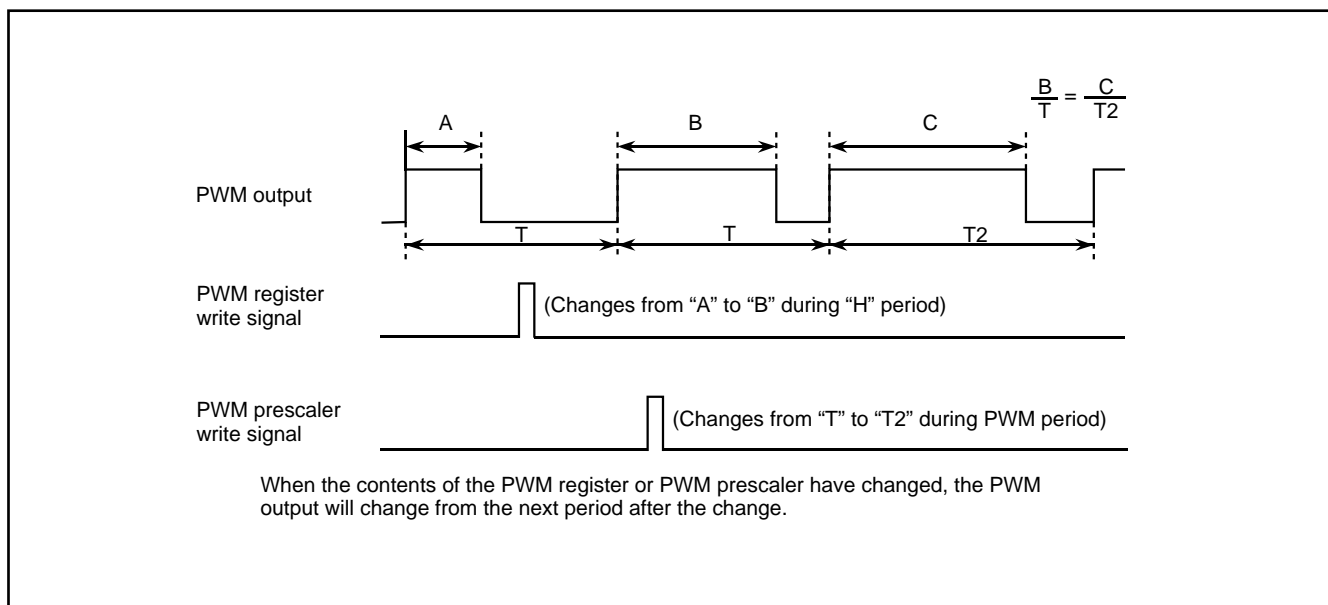


Fig. 21 PWM output timing when PWM register or PWM prescaler is changed

A-D Converter

The functional blocks of the A-D converter are described below.

[A-D conversion register]

The A-D conversion register is a read-only register that stores the result of an A-D conversion. When reading this register during an A-D conversion, the previous conversion result is read.

[AD/DA control register]

The AD/DA control register controls the A-D conversion process. Bits 0 to 2 select a specific analog input pin. Bit 3 signals the completion of an A-D conversion. The value of this bit remains at "0" during an A-D conversion, and changes to "1" when an A-D conversion ends. Writing "0" to this bit starts the A-D conversion. Bits 6 and 7 are used to control the output of the D-A converter.

[Comparison voltage generator]

The comparison voltage generator divides the voltage between AVSS and VREF into 256, and outputs the divided voltages.

[Channel selector]

The channel selector selects one of the ports P60/AN0 to P67/AN7, and inputs the voltage to the comparator.

[Comparator and Control circuit]

The comparator and control circuit compares an analog input voltage with the comparison voltage, then stores the result in the A-D conversion register. When an A-D conversion is complete, the control circuit sets the AD conversion completion bit and the AD interrupt request bit to "1".

Note that the comparator is constructed linked to a capacitor, so set $f(XIN)$ to 500 kHz or more during an A-D conversion.

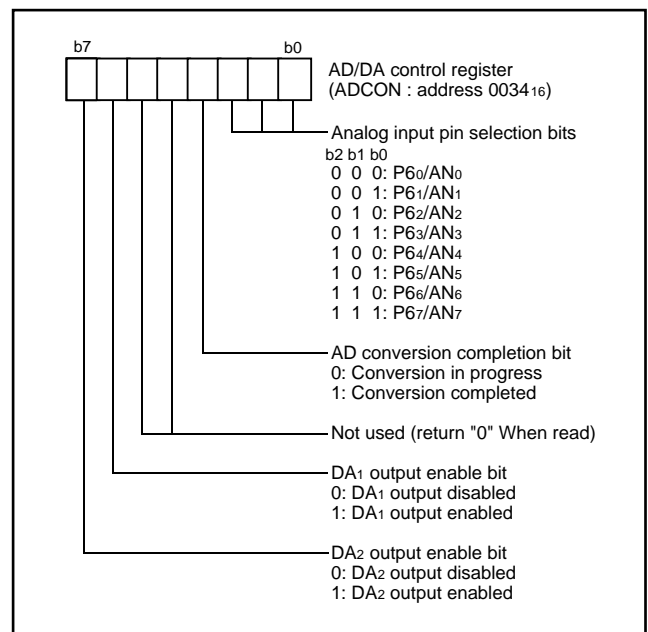


Fig.22 Structure of AD/DA control register

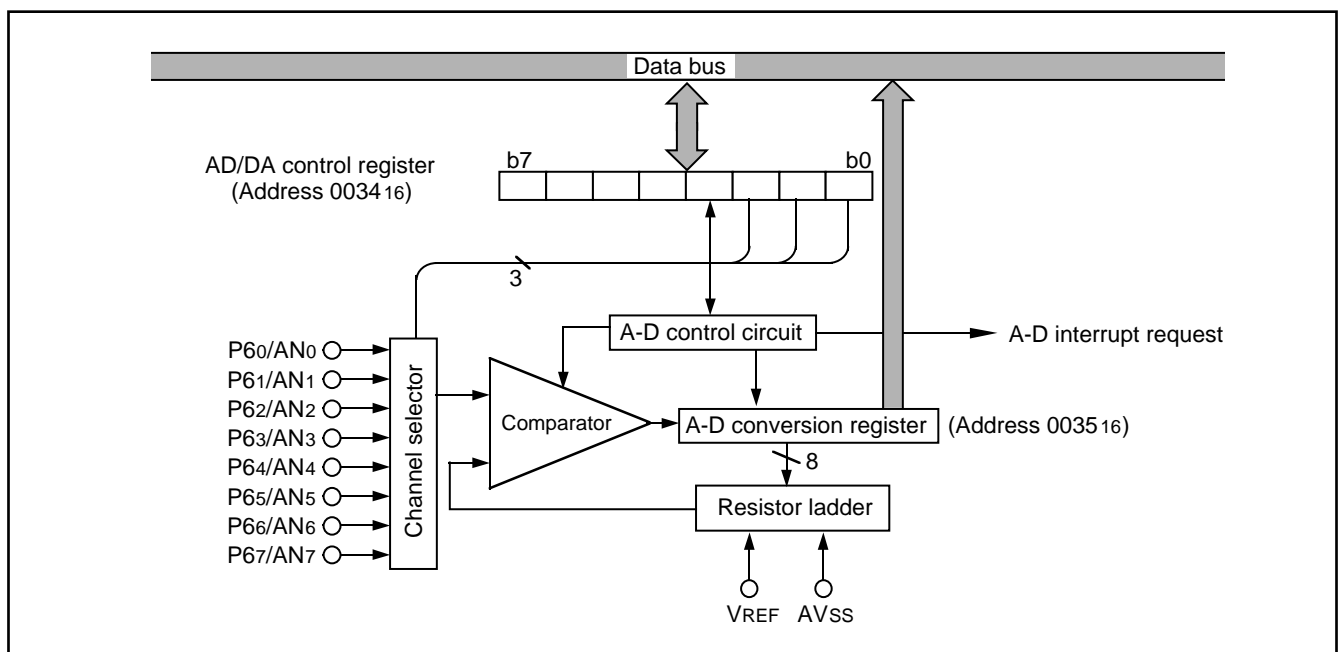


Fig. 23 Block diagram of A-D converter

D-A Converter

The 3802 group has two internal D-A converters (DA1 and DA2) with 8-bit resolutions.

The D-A converter is performed by setting the value in the D-A conversion register. The result of D-A converter is output from the DA1 or DA2 pin by setting the DA output enable bit to "1".

When using the D-A converter, the corresponding port direction register bit (P30/DA1 or P31/DA2) should be set to "0" (input status).

The output analog voltage V is determined by the value n (base 10) in the D-A conversion register as follows:

$$V = V_{REF} \times n / 256 \quad (n = 0 \text{ to } 255)$$

Where V_{REF} is the reference voltage.

At reset, the D-A conversion registers are cleared to "0016", the DA output enable bits are cleared to "0", and the P30/DA1 and P31/DA2 pins are set to input (high impedance).

The D-A output is not buffered, so connect an external buffer when driving a low-impedance load.

Set V_{CC} to 3.0 V or more when using the D-A converter.

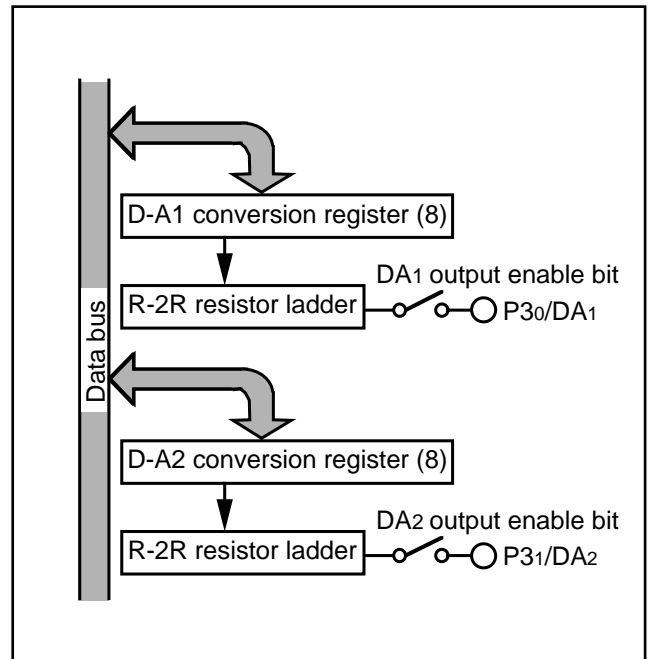


Fig. 24 Block diagram of D-A converter

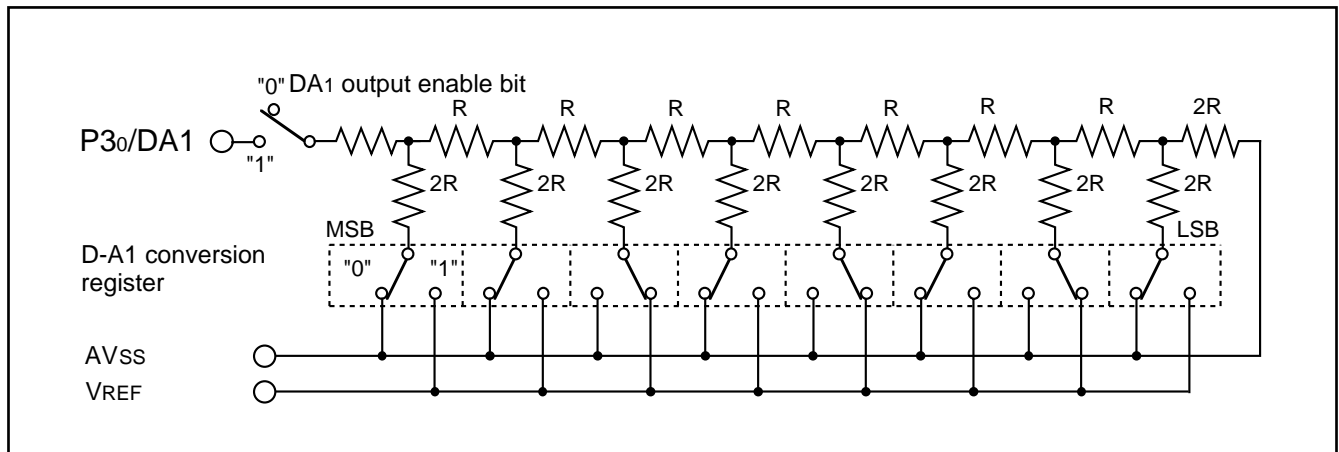


Fig. 25 Equivalent connection circuit of D-A converter

Reset Circuit

To reset the microcomputer, the $\overline{\text{RESET}}$ pin should be held at an "L" level for 2 μs or more. Then the $\overline{\text{RESET}}$ pin is returned to an "H" level (the power source voltage should be between 4.0 V and 5.5 V), reset is released. Internal operation begin until after 8 to 13 X_{IN} clock cycles are completed. After the reset is completed, the program starts from the address FFFD₁₆ (high-order byte) and address FFFC₁₆ (low-order byte).

Make sure that the reset input voltage is less than 0.6 V for V_{CC} of 3.0 V (Extended operating temperature version : the reset input voltage is less than 0.8 V for V_{CC} of 4.0 V).

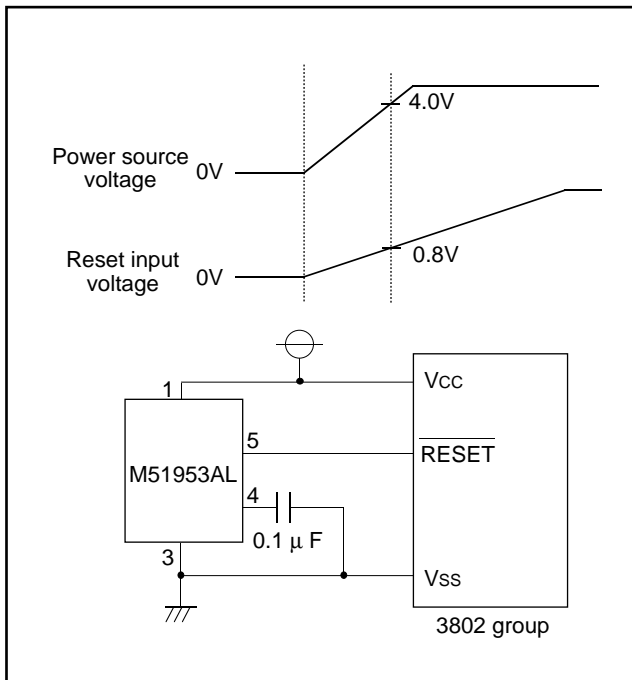


Fig. 26 Example of reset circuit

	Address	Register contents
(1) Port P0 direction register	(0001 ₁₆) ...	00 ₁₆
(2) Port P1 direction register	(0003 ₁₆) ...	00 ₁₆
(3) Port P2 direction register	(0005 ₁₆) ...	00 ₁₆
(4) Port P3 direction register	(0007 ₁₆) ...	00 ₁₆
(5) Port P4 direction register	(0009 ₁₆) ...	00 ₁₆
(6) Port P5 direction register	(000B ₁₆) ...	00 ₁₆
(7) Port P6 direction register	(000D ₁₆) ...	00 ₁₆
(8) Serial I/O1 status register	(0019 ₁₆) ...	1 0 0 0 0 0 0 0
(9) Serial I/O1 control register	(001A ₁₆) ...	00 ₁₆
(10) UART control register	(001B ₁₆) ...	1 1 1 0 0 0 0 0
(11) Serial I/O2 control register	(001D ₁₆) ...	00 ₁₆
(12) Prescaler 12	(0020 ₁₆) ...	FF ₁₆
(13) Timer 1	(0021 ₁₆) ...	01 ₁₆
(14) Timer 2	(0022 ₁₆) ...	FF ₁₆
(15) Timer XY mode register	(0023 ₁₆) ...	00 ₁₆
(16) Prescaler X	(0024 ₁₆) ...	FF ₁₆
(17) Timer X	(0025 ₁₆) ...	FF ₁₆
(18) Prescaler Y	(0026 ₁₆) ...	FF ₁₆
(19) Timer Y	(0027 ₁₆) ...	FF ₁₆
(20) PWM control register	(002B ₁₆) ...	00 ₁₆
(21) AD/DA control register	(0034 ₁₆) ...	0 0 0 0 0 1 0 0
(22) D-A1 conversion register	(0036 ₁₆) ...	00 ₁₆
(23) D-A2 conversion register	(0037 ₁₆) ...	00 ₁₆
(24) Interrupt edge selection register	(003A ₁₆) ...	00 ₁₆
(25) CPU mode register	(003B ₁₆) ...	0 0 0 0 0 0 0 *
(26) Interrupt request register 1	(003C ₁₆) ...	00 ₁₆
(27) Interrupt request register 2	(003D ₁₆) ...	00 ₁₆
(28) Interrupt control register 1	(003E ₁₆) ...	00 ₁₆
(29) Interrupt control register 2	(003F ₁₆) ...	00 ₁₆
(30) Processor status register	(PS)	x x x x x 1 x x
(31) Program counter	(PC _H)	Contents of address FFFD ₁₆
	(PC _L)	Contents of address FFFC ₁₆

Note. x : Undefined

* : The initial values of CM₁ are determined by the level at the CNV_{SS} pin.

The contents of all other registers and RAM are undefined after a reset, so they must be initialized by software.

Fig. 27 Internal status of microcomputer after reset

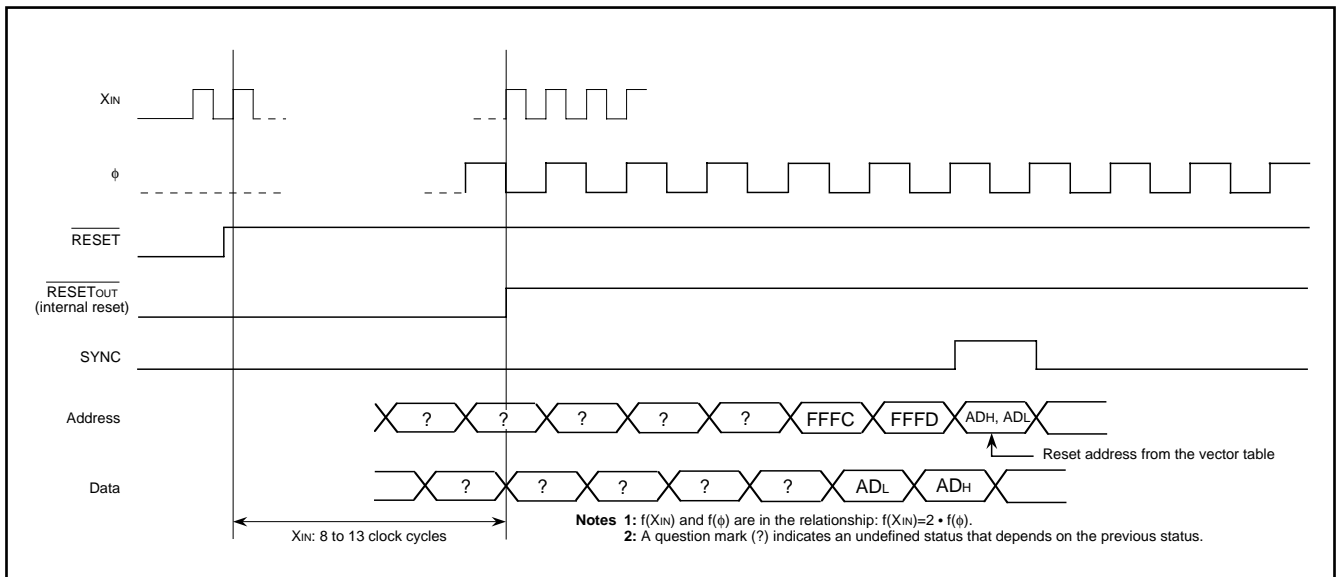


Fig. 28 Timing of reset

Clock Generating Circuit

An oscillation circuit can be formed by connecting a resonator between XIN and XOUT. To supply a clock signal externally, input it to the XIN pin and make the XOUT pin open.

Oscillation control

Stop Mode

If the STP instruction is executed, the internal clock ϕ stops at an "H". Timer 1 is set to "0116" and prescaler 12 is set to "FF16". Oscillator restarts when an external interrupt is received, but the internal clock ϕ remains at an "H" until timer 1 underflow. This allows time for the clock circuit oscillation to stabilize. If oscillator is restarted by a reset, no wait time is generated, so keep the $\overline{\text{RESET}}$ pin at an "L" level until oscillation has stabilized.

Wait Mode

If the WIT instruction is executed, the internal clock ϕ stops at an "H" level, but the oscillator itself does not stop. The internal clock restarts if a reset occurs or when an interrupt is received. Since the oscillator does not stop, normal operation can be started immediately after the clock is restarted. To ensure that interrupts will be received to release the STP or WIT state, interrupt enable bits must be set to "1" before the STP or WIT instruction is executed.

When the STP status is released, prescaler 12 and timer 1 will start counting and reset will not be released until timer 1 underflows, so set the timer 1 interrupt enable bit to "0" before the STP instruction is executed.

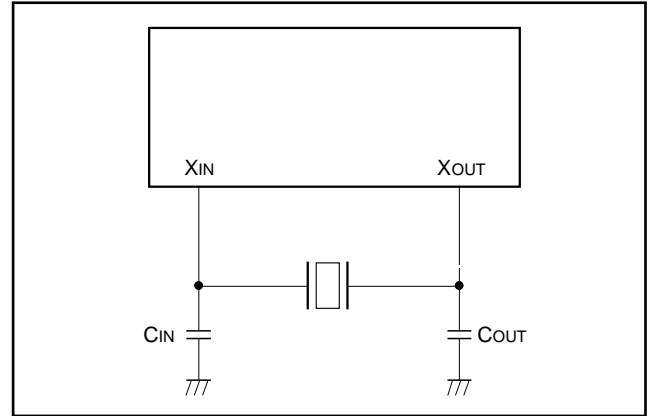


Fig. 29 Ceramic resonator circuit

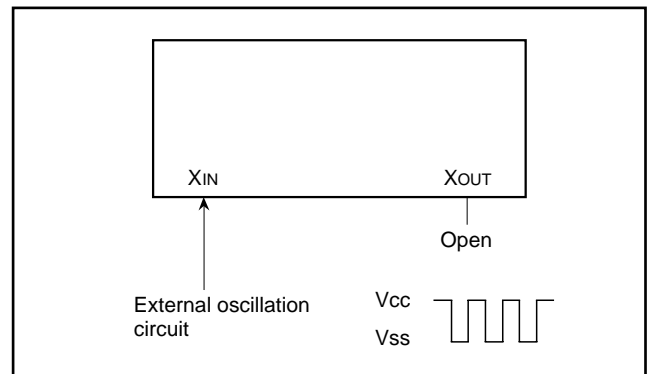


Fig. 30 External clock input circuit

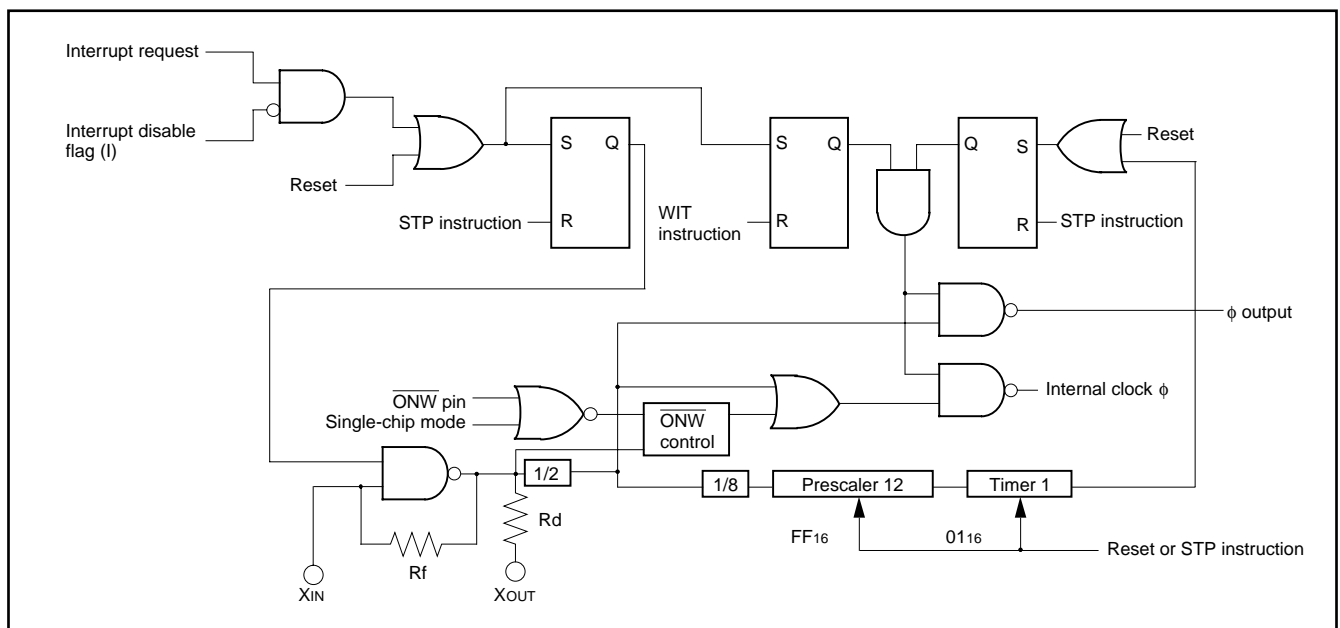


Fig. 31 Block diagram of clock generating circuit

Processor Modes

Single-chip mode, memory expansion mode, and microprocessor mode can be selected by changing the contents of the processor mode bits CM0 and CM1 (bits 0 and 1 of address 003B₁₆). In memory expansion mode and microprocessor mode, memory can be expanded externally through ports P0 to P3. In these modes, ports P0 to P3 lose their I/O port functions and become bus pins.

Table 2. Functions of ports in memory expansion mode and microprocessor mode

Port Name	Function
Port P0	Outputs low-order byte of address.
Port P1	Outputs high-order byte of address.
Port P2	Operates as I/O pins for data D7 to D0 (including instruction codes).
Port P3	P30 and P31 function only as output pins (except that the port latch cannot be read). P32 is the $\overline{\text{ONW}}$ input pin. P33 is the $\overline{\text{RESETOUT}}$ output pin. (Note) P34 is the ϕ output pin. P35 is the SYNC output pin. P36 is the $\overline{\text{WR}}$ output pin, and P37 is the $\overline{\text{RD}}$ output pin.

Note: If CNVss is connected to Vss, the microcomputer goes to single-chip mode after a reset, so this pin cannot be used as the $\overline{\text{RESETOUT}}$ output pin.

Single-Chip Mode

Select this mode by resetting the microcomputer with CNVss connected to Vss.

Memory Expansion Mode

Select this mode by setting the processor mode bits to "01" in software with CNVss connected to Vss. This mode enables external memory expansion while maintaining the validity of the internal ROM. Internal ROM will take precedence over external memory if addresses conflict.

Microprocessor Mode

Select this mode by resetting the microcomputer with CNVss connected to Vcc, or by setting the processor mode bits to "10" in software with CNVss connected to Vss. In microprocessor mode, the internal ROM is no longer valid and external memory must be used.

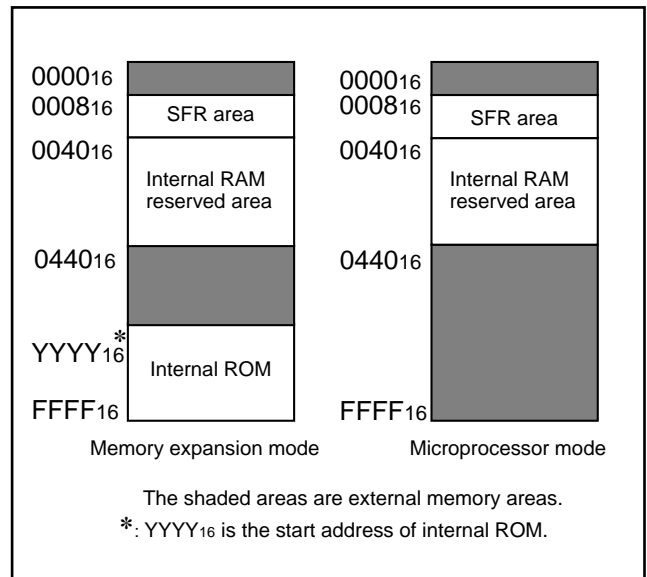


Fig. 32 Memory maps in various processor modes

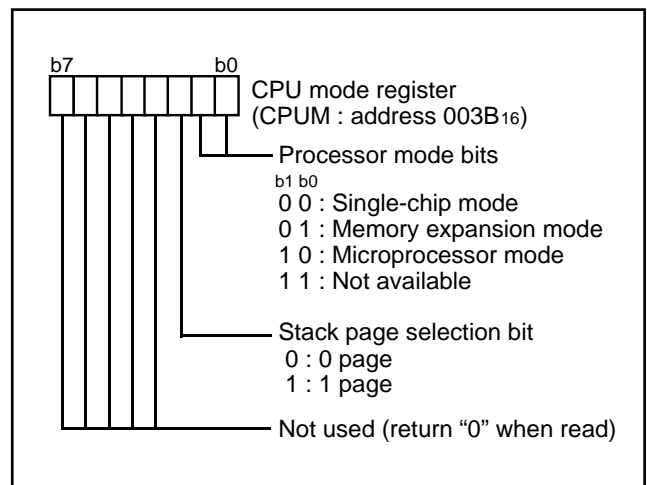


Fig. 33 Structure of CPU mode register

Bus control with memory expansion

The 3802 group has a built-in $\overline{\text{ONW}}$ function to facilitate access to external memory and I/O devices in memory expansion mode or microprocessor mode.

If an "L" level signal is input to the $\overline{\text{ONW}}$ pin when the CPU is in a read or write state, the corresponding read or write cycle is extended by one cycle of ϕ . During this extended period, the $\overline{\text{RD}}$ or $\overline{\text{WR}}$ signal remains at "L". This extension period is valid only for writing to and reading from addresses 0000₁₆ to 0007₁₆ and 0440₁₆ to FFFF₁₆ in microprocessor mode, 0440₁₆ to YYYYY₁₆ in memory expansion mode, and only read and write cycles are extended.

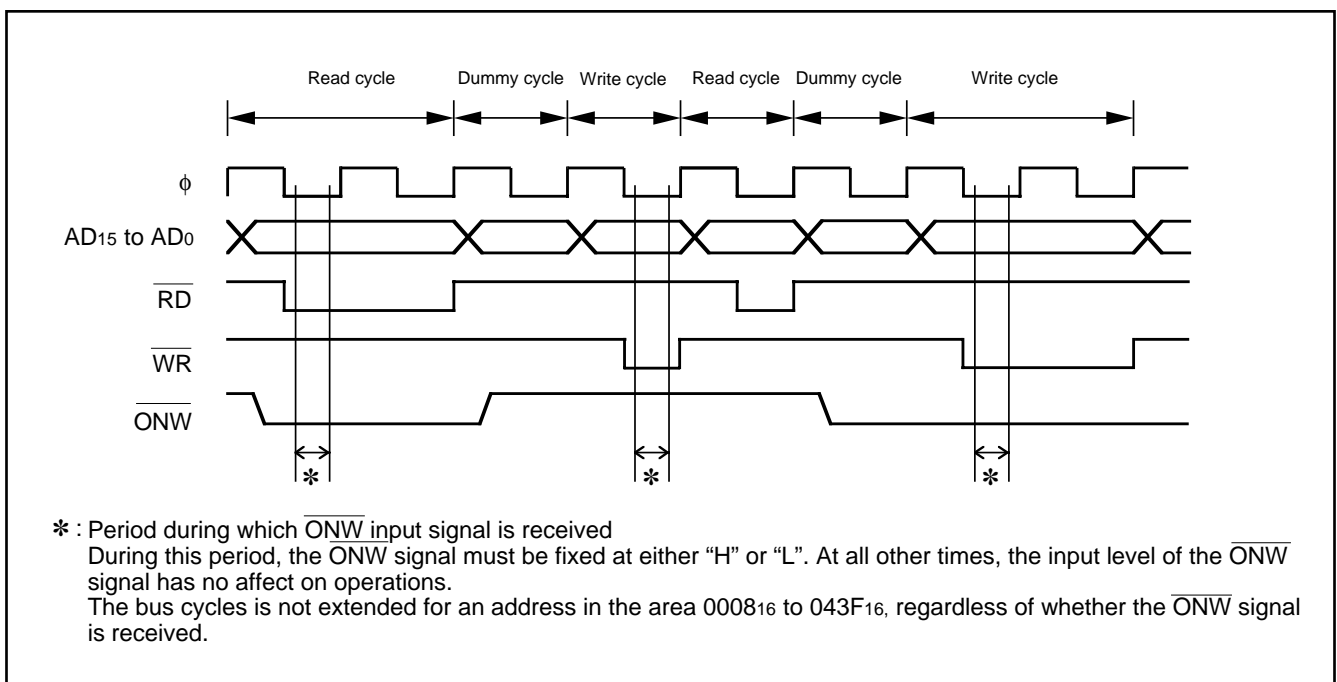


Fig. 34 $\overline{\text{ONW}}$ function timing

NOTES ON PROGRAMMING

Processor Status Register

The contents of the processor status register (PS) after a reset are undefined, except for the interrupt disable flag (I) which is "1". After a reset, initialize flags which affect program execution. In particular, it is essential to initialize the index X mode (T) and the decimal mode (D) flags because of their effect on calculations.

Interrupts

The contents of the interrupt request bits do not change immediately after they have been written. After writing to an interrupt request register, execute at least one instruction before executing a BBC or BBS instruction.

Decimal Calculations

To calculate in decimal notation, set the decimal mode flag (D) to "1", then execute an ADC or SBC instruction. Only the ADC and SBC instructions yield proper decimal results. After executing an ADC or SBC instruction, execute at least one instruction before executing a SEC, CLC, or CLD instruction.

In decimal mode, the values of the negative (N), overflow (V), and zero (Z) flags are invalid.

The carry flag can be used to indicate whether a carry or borrow has occurred. Initialize the carry flag before each calculation. Clear the carry flag before an ADC and set the flag before an SBC.

Timers

If a value n (between 0 and 255) is written to a timer latch, the frequency division ratio is $1/(n + 1)$.

Multiplication and Division Instructions

The index X mode (T) and the decimal mode (D) flags do not affect the MUL and DIV instruction.

The execution of these instructions does not change the contents of the processor status register.

Ports

The contents of the port direction registers cannot be read.

The following cannot be used:

- The data transfer instruction (LDA, etc.)
- The operation instruction when the index X mode flag (T) is "1"
- The addressing mode which uses the value of a direction register as an index
- The bit-test instruction (BBC or BBS, etc.) to a direction register
- The read-modify-write instruction (ROR, CLB, or SEB, etc.) to a direction register

Use instructions such as LDM and STA, etc., to set the port direction registers.

Serial I/O

In clock synchronous serial I/O, if the receive side is using an external clock and it is to output the $\overline{\text{SRDY}}_1$ signal, set the transmit enable bit, the receive enable bit, and the $\overline{\text{SRDY}}_1$ output enable bit to "1".

Serial I/O1 continues to output the final bit from the TxD pin after transmission is completed. The SOUT2 pin from serial I/O2 goes to high impedance after transmission is completed.

A-D Converter

The comparator uses internal capacitors whose charge will be lost if the clock frequency is too low.

Make sure that $f(\text{XIN})$ is at least 500 kHz during an A-D conversion. (If the $\overline{\text{ONW}}$ pin has been set to "L", the A-D conversion will take twice as long to match the longer bus cycle, and so $f(\text{XIN})$ must be at least 1 MHz.)

Do not execute the STP or WIT instruction during an A-D conversion.

D-A Converter

The accuracy of the D-A converter becomes poor rapidly under the $V_{CC} = 3.0 \text{ V}$ or less condition.

Instruction Execution Time

The instruction execution time is obtained by multiplying the frequency of the internal clock ϕ by the number of cycles needed to execute an instruction.

The number of cycles required to execute an instruction is shown in the list of machine instructions.

The frequency of the internal clock ϕ is half of the XIN frequency. When the $\overline{\text{ONW}}$ function is used in modes other than single-chip mode, the frequency of the internal clock ϕ may be one fourth the XIN frequency.

Memory Expansion Mode

The memory expansion mode is not available in the following microcomputers.

- M38024M6-XXXSP
- M38024M6-XXXFP

Memory Expansion Mode and Microprocessor Mode

Execute the LDM or STA instruction for writing to port P3 (address 000616) in memory expansion mode and microprocessor mode.

Set areas which can be read out and write to port P3 (address 000616) in a memory, using the read-modify-write instruction (SEB, CLB).

DATA REQUIRED FOR MASK ORDERS

The following are necessary when ordering a mask ROM production:

1. Mask ROM Order Confirmation Form
2. Mask Specification Form
3. Data to be written to ROM, in EPROM form (three identical copies)

ROM PROGRAMMING METHOD

The built-in PROM of the blank One Time PROM version and built-in EPROM version can be read or programmed with a general-purpose PROM programmer using a special programming adapter. Set the address of PROM programmer in the user ROM area.

Package	Name of Programming Adapter
64P4B, 64S1B	PCA4738S-64A
64P6N	PCA4738F-64A
64D0	PCA4738L-64A

The PROM of the blank One Time PROM version is not tested or screened in the assembly process and following processes. To ensure proper operation after programming, the procedure shown in Figure 35 is recommended to verify programming.

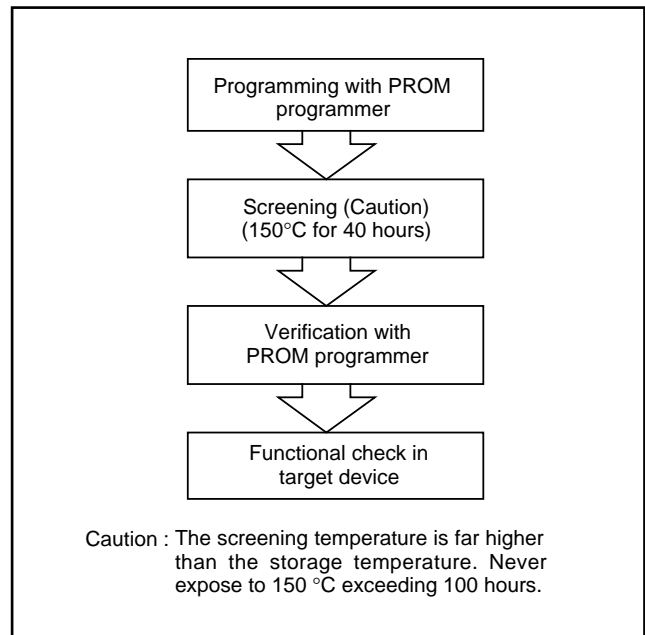


Fig. 35 Programming and testing of One Time PROM version

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Conditions	Ratings	Unit
V _{CC}	Power source voltage	All voltages are based on V _{SS} . Output transistors are cut off.	−0.3 to 7.0	V
V _I	Input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67, V _{REF}		−0.3 to V _{CC} +0.3	V
V _I	Input voltage $\overline{\text{RESET}}$, X _{IN}		−0.3 to V _{CC} +0.3	V
V _I	Input voltage CNV _{SS}		−0.3 to 13	V
V _O	Output voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67, X _{OUT}		−0.3 to V _{CC} +0.3	V
P _d	Power dissipation	T _a = 25 °C	1000 (Note)	mW
T _{opr}	Operating temperature		−20 to 85	°C
T _{stg}	Storage temperature		−40 to 125	°C

Note: 300 mW in case of the flat package.

RECOMMENDED OPERATING CONDITIONS (V_{CC} = 3.0 to 5.5 V, T_a = −20 to 85°C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
V _{CC}	Power source voltage (f(X _{IN}) < 2 MHz) (Note 1)	3.0	5.0	5.5	V
	Power source voltage (f(X _{IN}) = 8 MHz) (Note 1)	4.0	5.0	5.5	
V _{SS}	Power source voltage		0		V
V _{REF}	Analog reference voltage (when A-D converter is used)	2.0		V _{CC}	V
	Analog reference voltage (when D-A converter is used)	3.0		V _{CC}	
AV _{SS}	Analog power source voltage		0		V
V _{IA}	Analog input voltage AN ₀ –AN ₇	AV _{SS}		V _{CC}	V
V _{IH}	"H" input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	0.8 V _{CC}		V _{CC}	V
V _{IH}	"H" input voltage $\overline{\text{RESET}}$, X _{IN} , CNV _{SS}	0.8 V _{CC}		V _{CC}	V
V _{IL}	"L" input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	0		0.2 V _{CC}	V
V _{IL}	"L" input voltage $\overline{\text{RESET}}$, CNV _{SS}	0		0.2 V _{CC}	V
V _{IL}	"L" input voltage X _{IN}	0		0.16 V _{CC}	V
ΣIOH(peak)	"H" total peak output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 2)			−80	mA
ΣIOH(peak)	"H" total peak output current P40–P47, P50–P57, P60–P67 (Note 2)			−80	
ΣIOL(peak)	"L" total peak output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 2)			80	mA
ΣIOL(peak)	"L" total peak output current P40–P47, P50–P57, P60–P67 (Note 2)			80	
ΣIOH(avg)	"H" total average output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 2)			−40	mA
ΣIOH(avg)	"H" total average output current P40–P47, P50–P57, P60–P67 (Note 2)			−40	
ΣIOL(avg)	"L" total average output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 2)			40	mA
ΣIOL(avg)	"L" total average output current P40–P47, P50–P57, P60–P67 (Note 2)			40	
IOH(peak)	"H" peak output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 3)			−10	mA
IOL(peak)	"L" peak output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 3)			10	
IOH(avg)	"H" average output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 4)			−5	mA
IOL(avg)	"L" average output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 4)			5	
f(X _{IN})	Internal clock oscillation frequency (V _{CC} = 4.0 to 5.5 V)			8	MHz
	Internal clock oscillation frequency (V _{CC} = 3.0 to 4.0 V)			6 V _{CC} −16	

Note 1: The minimum power source voltage is $\frac{X+16}{6}$ [V] (f(X_{IN}) = XMHz) on the condition of 2 MHz < f(X_{IN}) < 8 MHz.

2: The total output current is the sum of all the currents flowing through all the applicable ports. The total average current is an average value measured over 100 ms. The total peak current is the peak value of all the currents.

3: The peak output current is the peak current flowing in each port.

4: The average output current IOL(avg), IOH(avg) in an average value measured over 100 ms.

ELECTRICAL CHARACTERISTICS ($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = 0$ V, $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
VOH	“H” output voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 1)	IOH = –10 mA VCC = 4.0 to 5.5 V	VCC–2.0			V
		IOH = –1.0 mA VCC = 3.0 to 5.5 V	VCC–1.0			
VOL	“L” output voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	IOL = 10 mA VCC = 4.0 to 5.5 V			2.0	V
		IOL = 1.0 mA VCC = 3.0 to 5.5 V			1.0	
VT+ – VT–	Hysteresis	CNTR0, CNTR1, INT0–INT4		0.4		V
VT+ – VT–	Hysteresis	RxD, SCLK1, SIN2, SCLK2		0.5		V
VT+ – VT–	Hysteresis	RESET		0.5		V
IIH	“H” input current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	VI = VCC			5.0	μA
IIH	“H” input current	RESET, CNVss	VI = VCC		5.0	μA
IIH	“H” input current	XIN	VI = VCC	4		μA
IIL	“L” input current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67, RESET, CNVss	VI = VSS			–5.0	μA
IIL	“L” input current	RESET, CNVss	VI = VSS		–5.0	μA
IIL	“L” input current	XIN	VI = VSS	–4		μA
VRAM	RAM hold voltage	When clock stopped	2.0		5.5	V
ICC	Power source current	f(XIN) = 8 MHz, VCC = 5 V		6.4	13	mA
		f(XIN) = 5 MHz, VCC = 5 V		4	8	
		f(XIN) = 2 MHz, VCC = 3 V		0.8	2.0	
		When WIT instruction is executed with f(Xin) = 8MHz, VCC=5V		1.5		
		When WIT instruction is executed with f(Xin) = 5MHz, VCC=5V		1		
		When WIT instruction is executed with f(Xin) = 2MHz, VCC=3V		0.2		
		When STP instruction is executed with clock stopped, output transistors isolated.	Ta = 25 °C (Note 2)	0.1	1	μA
			Ta = 85 °C (Note 2)		10	

Note 1: P45 is measured when the P45/TXD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is “0”.

P51 is measured when the P51/SOUT2 P-channel output disable bit of the serial I/O2 control register (bit 7 of address 001D16) is “0”.

2: With output transistors isolated and A-D converter having completed conversion, and not including current flowing through VREF pin.

A–D CONVERTER CHARACTERISTICS

($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = AV_{SS} = 0$ V, $V_{REF} = 2.0$ V to V_{CC} , $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
—	Resolution				8	Bits
—	Absolute accuracy (excluding quantization error)			±1	±2.5	LSB
tCONV	Conversion time				50	tc(φ)
RLADDER	Ladder resistor			35		kΩ
IVREF	Reference power source input current (Note)	VREF = 5.0 V	50	150	200	μA
II(AD)	A-D port input current			0.5	5.0	μA

Note: When D-A conversion registers (addresses 003616 and 003716) contain “0016”.

D-A CONVERTER CHARACTERISTICS

(VCC = 3.0 to 5.5 V, VSS = AVSS = 0 V, VREF = 3.0 V to VCC, Ta = -20 to 85 °C, unless otherwise noted)

Symbol	Parameter		Test conditions	Limits			Unit
				Min.	Typ.	Max.	
—	Resolution					8	Bits
—	Absolute accuracy	VCC = 4.0 to 5.5 V				1.0	%
		VCC = 3.0 to 4.0 V				2.5	
tsu	Setting time					3	μs
RO	Output resistor			1	2.5	4	kΩ
IVREF	Reference power source input current (Note)					3.2	mA

Note: Using one D-A converter, with the value in the D-A conversion register of the other D-A converter being "0016", and excluding currents flowing through the A-D resistance ladder.

TIMING REQUIREMENTS 1 ($V_{CC} = 4.0$ to 5.5 V, $V_{SS} = 0$ V, $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
$t_w(\overline{\text{RESET}})$	Reset input "L" pulse width	2			μs
$t_c(X_{IN})$	External clock input cycle time	125			ns
$t_{wH}(X_{IN})$	External clock input "H" pulse width	50			ns
$t_{wL}(X_{IN})$	External clock input "L" pulse width	50			ns
$t_c(\text{CNTR})$	CNTR ₀ , CNTR ₁ input cycle time	200			ns
$t_{wH}(\text{CNTR})$	CNTR ₀ , CNTR ₁ input "H" pulse width	80			ns
$t_{wH}(\text{INT})$	INT ₀ to INT ₄ input "H" pulse width	80			ns
$t_{wL}(\text{CNTR})$	CNTR ₀ , CNTR ₁ input "L" pulse width	80			ns
$t_{wL}(\text{INT})$	INT ₀ to INT ₄ input "L" pulse width	80			ns
$t_c(\text{SCLK1})$	Serial I/O1 clock input cycle time (Note)	800			ns
$t_c(\text{SCLK2})$	Serial I/O2 clock input cycle time	1000			ns
$t_{wH}(\text{SCLK1})$	Serial I/O1 clock input "H" pulse width (Note)	370			ns
$t_{wH}(\text{SCLK2})$	Serial I/O2 clock input "H" pulse width	400			ns
$t_{wL}(\text{SCLK1})$	Serial I/O1 clock input "L" pulse width (Note)	370			ns
$t_{wL}(\text{SCLK2})$	Serial I/O2 clock input "L" pulse width	400			ns
$t_{su}(\text{RxD-SCLK1})$	Serial I/O1 input set up time	220			ns
$t_{su}(\text{SIN2-SCLK2})$	Serial I/O2 input set up time	200			ns
$t_h(\text{SCLK1-RxD})$	Serial I/O1 input hold time	100			ns
$t_h(\text{SCLK2-SIN2})$	Serial I/O2 input hold time	200			ns

Note: When $f(X_{IN}) = 8$ MHz and bit 6 of address 001A₁₆ is "1". Divide this value by four when $f(X_{IN}) = 8$ MHz and bit 6 of address 001A₁₆ is "0".

TIMING REQUIREMENTS 2 ($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = 0$ V, $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
$t_w(\overline{\text{RESET}})$	Reset input "L" pulse width	2			μs
$t_c(X_{IN})$	External clock input cycle time	500/ (3 $V_{CC}-8$)			ns
$t_{wH}(X_{IN})$	External clock input "H" pulse width	200/ (3 $V_{CC}-8$)			ns
$t_{wL}(X_{IN})$	External clock input "L" pulse width	200/ (3 $V_{CC}-8$)			ns
$t_c(\text{CNTR})$	CNTR ₀ , CNTR ₁ input cycle time	500			ns
$t_{wH}(\text{CNTR})$	CNTR ₀ , CNTR ₁ input "H" pulse width	230			ns
$t_{wH}(\text{INT})$	INT ₀ to INT ₄ input "H" pulse width	230			ns
$t_{wL}(\text{CNTR})$	CNTR ₀ , CNTR ₁ input "L" pulse width	230			ns
$t_{wL}(\text{INT})$	INT ₀ to INT ₄ input "L" pulse width	230			ns
$t_c(\text{SCLK1})$	Serial I/O1 clock input cycle time (Note)	2000			ns
$t_c(\text{SCLK2})$	Serial I/O2 clock input cycle time	2000			ns
$t_{wH}(\text{SCLK1})$	Serial I/O1 clock input "H" pulse width (Note)	950			ns
$t_{wH}(\text{SCLK2})$	Serial I/O2 clock input "H" pulse width	950			ns
$t_{wL}(\text{SCLK1})$	Serial I/O1 clock input "L" pulse width (Note)	950			ns
$t_{wL}(\text{SCLK2})$	Serial I/O2 clock input "L" pulse width	950			ns
$t_{su}(\text{RxD-SCLK1})$	Serial I/O1 input set up time	400			ns
$t_{su}(\text{SIN2-SCLK2})$	Serial I/O2 input set up time	400			ns
$t_h(\text{SCLK1-RxD})$	Serial I/O1 input hold time	200			ns
$t_h(\text{SCLK2-SIN2})$	Serial I/O2 input hold time	300			ns

Note: When $f(X_{IN}) = 2$ MHz and bit 6 of address 001A₁₆ is "1". Divide this value by four when $f(X_{IN}) = 2$ MHz and bit 6 of address 001A₁₆ is "0".

SWITCHING CHARACTERISTICS 1 ($V_{CC} = 4.0$ to 5.5 V, $V_{SS} = 0$ V, $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
$t_{wH}(SCLK1)$	Serial I/O1 clock output "H" pulse width	Fig. 36	$t_c(SCLK1)/2-30$			ns
$t_{wH}(SCLK2)$	Serial I/O2 clock output "H" pulse width		$t_c(SCLK2)/2-160$			ns
$t_{wL}(SCLK1)$	Serial I/O1 clock output "L" pulse width		$t_c(SCLK1)/2-30$			ns
$t_{wL}(SCLK2)$	Serial I/O2 clock output "L" pulse width		$t_c(SCLK2)/2-160$			ns
$t_d(SCLK1-TxD)$	Serial I/O1 output delay time (Note 1)				140	ns
$t_d(SCLK2-SOUT2)$	Serial I/O2 output delay time (Note 2)				200	ns
$t_v(SCLK1-TxD)$	Serial I/O1 output valid time (Note 1)		-30			ns
$t_v(SCLK2-SOUT2)$	Serial I/O2 output valid time (Note 2)		0			ns
$t_r(SCLK1)$	Serial I/O1 clock output rising time				30	ns
$t_f(SCLK1)$	Serial I/O1 clock output falling time				30	ns
$t_r(SCLK2)$	Serial I/O2 clock output rising time				30	ns
$t_f(SCLK2)$	Serial I/O2 clock output falling time				40	ns
$t_r(CMOS)$	CMOS output rising time (Note 3)			10	30	ns
$t_f(CMOS)$	CMOS output falling time (Note 3)			10	30	ns

Note1: When the P45/TxD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is "0".

2: When the P51/SOUT2 P-channel output disable bit of the serial I/O2 control register (bit 7 of address 001D16) is "0".

3: XOUT pin is excluded.

SWITCHING CHARACTERISTICS 2 ($V_{CC} = 3.0$ to 5.5 V, $V_{SS} = 0$ V, $T_a = -20$ to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
$t_{wH}(SCLK1)$	Serial I/O1 clock output "H" pulse width	Fig. 36	$t_c(SCLK1)/2-50$			ns
$t_{wH}(SCLK2)$	Serial I/O2 clock output "H" pulse width		$t_c(SCLK2)/2-240$			ns
$t_{wL}(SCLK1)$	Serial I/O1 clock output "L" pulse width		$t_c(SCLK1)/2-50$			ns
$t_{wL}(SCLK2)$	Serial I/O2 clock output "L" pulse width		$t_c(SCLK2)/2-240$			ns
$t_d(SCLK1-TxD)$	Serial I/O1 output delay time (Note 1)				350	ns
$t_d(SCLK2-SOUT2)$	Serial I/O2 output delay time (Note 2)				400	ns
$t_v(SCLK1-TxD)$	Serial I/O1 output valid time (Note 1)		-30			ns
$t_v(SCLK2-SOUT2)$	Serial I/O2 output valid time (Note 2)		0			ns
$t_r(SCLK1)$	Serial I/O1 clock output rising time				50	ns
$t_f(SCLK1)$	Serial I/O1 clock output falling time				50	ns
$t_r(SCLK2)$	Serial I/O2 clock output rising time				50	ns
$t_f(SCLK2)$	Serial I/O2 clock output falling time				50	ns
$t_r(CMOS)$	CMOS output rising time (Note 3)			20	50	ns
$t_f(CMOS)$	CMOS output falling time (Note 3)			20	50	ns

Note1: When the P45/TxD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is "0".

2: When the P51/SOUT2 P-channel output disable bit of the serial I/O2 control register (bit 7 of address 001D16) is "0".

3: XOUT pin is excluded.

TIMING REQUIREMENTS 1 IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 4.0 to 5.5 V, V_{SS} = 0 V, T_a = -20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
t _{su} ($\overline{\text{ONW}}$ - ϕ)	Before ϕ $\overline{\text{ONW}}$ input set up time	-20			ns
t _h (ϕ - $\overline{\text{ONW}}$)	After ϕ $\overline{\text{ONW}}$ input hold time	-20			ns
t _{su} (DB- ϕ)	Before ϕ data bus set up time	60			ns
t _h (ϕ -DB)	After ϕ data bus hold time	0			ns
t _{su} ($\overline{\text{ONW}}$ - $\overline{\text{RD}}$) t _{su} ($\overline{\text{ONW}}$ - $\overline{\text{WR}}$)	Before $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input set up time Before $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input set up time	-20			ns
t _h ($\overline{\text{RD}}$ - $\overline{\text{ONW}}$) t _h ($\overline{\text{WR}}$ - $\overline{\text{ONW}}$)	After $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input hold time After $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input hold time	-20			ns
t _{su} (DB- $\overline{\text{RD}}$)	Before $\overline{\text{RD}}$ data bus set up time	65			ns
t _h ($\overline{\text{RD}}$ -DB)	After $\overline{\text{RD}}$ data bus hold time	0			ns

SWITCHING CHARACTERISTICS 1 IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 4.0 to 5.5 V, V_{SS} = 0 V, T_a = -20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
t _c (ϕ)	ϕ clock cycle time	Fig. 36		2t _c (X _{IN})		ns
t _{wH} (ϕ)	ϕ clock "H" pulse width		t _c (X _{IN})-10			ns
t _{wL} (ϕ)	ϕ clock "L" pulse width		t _c (X _{IN})-10			ns
t _d (ϕ -AH)	After ϕ AD ₁₅ -AD ₈ delay time			20	40	ns
t _v (ϕ -AH)	After ϕ AD ₁₅ -AD ₈ valid time		6	10		ns
t _d (ϕ -AL)	After ϕ AD ₇ -AD ₀ delay time			25	45	ns
t _v (ϕ -AL)	After ϕ AD ₇ -AD ₀ valid time		6	10		ns
t _d (ϕ -SYNC)	SYNC delay time			20		ns
t _v (ϕ -SYNC)	SYNC valid time			10		ns
t _d (ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ delay time			10	20	ns
t _v (ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ valid time		3	5	10	ns
t _d (ϕ -DB)	After ϕ data bus delay time			20	70	ns
t _v (ϕ -DB)	After ϕ data bus valid time		15			ns
t _{wL} ($\overline{\text{RD}}$) t _{wL} ($\overline{\text{WR}}$)	$\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width $\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width (When one-wait is valid)		t _c (X _{IN})-10			ns
			3t _c (X _{IN})-10			ns
t _d (AH- $\overline{\text{RD}}$) t _d (AH- $\overline{\text{WR}}$)	After AD ₁₅ -AD ₈ $\overline{\text{RD}}$ delay time After AD ₁₅ -AD ₈ $\overline{\text{WR}}$ delay time		t _c (X _{IN})-35	t _c (X _{IN})-15		ns
t _d (AL- $\overline{\text{RD}}$) t _d (AL- $\overline{\text{WR}}$)	After AD ₇ -AD ₀ $\overline{\text{RD}}$ delay time After AD ₇ -AD ₀ $\overline{\text{WR}}$ delay time		t _c (X _{IN})-40	t _c (X _{IN})-20		ns
t _v ($\overline{\text{RD}}$ -AH) t _v ($\overline{\text{WR}}$ -AH)	After $\overline{\text{RD}}$ AD ₁₅ -AD ₈ valid time After $\overline{\text{WR}}$ AD ₁₅ -AD ₈ valid time		0	5		ns
t _v ($\overline{\text{RD}}$ -AL) t _v ($\overline{\text{WR}}$ -AL)	After $\overline{\text{RD}}$ AD ₇ -AD ₀ valid time After $\overline{\text{WR}}$ AD ₇ -AD ₀ valid time		0	5		ns
t _d ($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus delay time			15	65	ns
t _v ($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus valid time		10			ns
t _d ($\overline{\text{RESET}}$ - $\overline{\text{RESETOUT}}$)	$\overline{\text{RESETOUT}}$ output delay time (Note 1)				200	ns
t _v (ϕ - $\overline{\text{RESET}}$)	$\overline{\text{RESETOUT}}$ output valid time (Note 1)		0		200	ns

Note 1: The $\overline{\text{RESETOUT}}$ output goes "H" in sync with the rise of the ϕ clock that is anywhere between about 8 cycle and 13 cycles after the $\overline{\text{RESET}}$ input goes "H".

TIMING REQUIREMENTS 2 IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 3.0 V, V_{SS} = 0 V, T_a = -20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
tsu($\overline{\text{ONW}}-\phi$)	Before ϕ $\overline{\text{ONW}}$ input set up time	-20			ns
th($\phi-\overline{\text{ONW}}$)	After ϕ $\overline{\text{ONW}}$ input hold time	-20			ns
tsu(DB- ϕ)	Before ϕ data bus set up time	180			ns
th(ϕ -DB)	After ϕ data bus hold time	0			ns
tsu($\overline{\text{ONW}}-\overline{\text{RD}}$)	Before $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input set up time	-20			ns
tsu($\overline{\text{ONW}}-\overline{\text{WR}}$)	Before $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input set up time	-20			ns
th($\overline{\text{RD}}-\overline{\text{ONW}}$)	After $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input hold time	-20			ns
th($\overline{\text{WR}}-\overline{\text{ONW}}$)	After $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input hold time	-20			ns
tsu(DB- $\overline{\text{RD}}$)	Before $\overline{\text{RD}}$ data bus set up time	185			ns
th($\overline{\text{RD}}$ -DB)	After $\overline{\text{RD}}$ data bus hold time	0			ns

SWITCHING CHARACTERISTICS 2 IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 3.0 V, V_{SS} = 0 V, T_a = -20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
tc(ϕ)	ϕ clock cycle time	Fig. 36		2tc(X _{IN})		ns
twH(ϕ)	ϕ clock "H" pulse width		tc(X _{IN})-20			ns
twL(ϕ)	ϕ clock "L" pulse width		tc(X _{IN})-20			ns
td(ϕ -AH)	After ϕ AD15-AD8 delay time				150	ns
tv(ϕ -AH)	After ϕ AD15-AD8 valid time		10	15		ns
td(ϕ -AL)	After ϕ AD7-AD0 delay time				150	ns
tv(ϕ -AL)	After ϕ AD7-AD0 valid time		10	15		ns
td(ϕ -SYNC)	SYNC delay time			40		ns
tv(ϕ -SYNC)	SYNC valid time			20		ns
td(ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ delay time			15	25	ns
tv(ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ valid time		3	7	15	ns
td(ϕ -DB)	After ϕ data bus delay time				200	ns
tv(ϕ -DB)	After ϕ data bus valid time		15			ns
twL($\overline{\text{RD}}$)	$\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width		tc(X _{IN})-20			ns
twL($\overline{\text{WR}}$)	$\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width (when one-wait is valid)		3tc(X _{IN})-20			ns
td(AH- $\overline{\text{RD}}$)	After AD15-AD8 $\overline{\text{RD}}$ delay time		tc(X _{IN})-145			ns
td(AH- $\overline{\text{WR}}$)	After AD15-AD8 $\overline{\text{WR}}$ delay time		tc(X _{IN})-145			ns
td(AL- $\overline{\text{RD}}$)	After AD7-AD0 $\overline{\text{RD}}$ delay time		tc(X _{IN})-145			ns
td(AL- $\overline{\text{WR}}$)	After AD7-AD0 $\overline{\text{WR}}$ delay time		tc(X _{IN})-145			ns
tv($\overline{\text{RD}}$ -AH)	After $\overline{\text{RD}}$ AD15-AD8 valid time		5	10		ns
tv($\overline{\text{WR}}$ -AH)	After $\overline{\text{WR}}$ AD15-AD8 valid time		5	10		ns
tv($\overline{\text{RD}}$ -AL)	After $\overline{\text{RD}}$ AD7-AD0 valid time		5	10		ns
tv($\overline{\text{WR}}$ -AL)	After $\overline{\text{WR}}$ AD7-AD0 valid time		5	10		ns
td($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus delay time				195	ns
tv($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus valid time		10			ns
td(RESET-RESET _{OUT})	RESET _{OUT} output delay time (Note 1)				300	ns
tv(ϕ -RESET)	RESET _{OUT} output valid time (Note 1)		0		300	ns

Note1: The RESET_{OUT} output goes "H" in sync with the fall of the ϕ clock that is anywhere between about 8 cycle and 13 cycles after the RESET input goes "H".

ABSOLUTE MAXIMUM RATINGS (Extended operating temperature version)

Symbol	Parameter	Conditions	Ratings	Unit
V _{CC}	Power source voltage	All voltage are based on V _{SS} . Output transistors are cut off.	−0.3 to 7.0	V
V _I	Input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67, V _{REF}		−0.3 to V _{CC} +0.3	V
V _I	Input voltage $\overline{\text{RESET}}$, X _{IN}		−0.3 to V _{CC} +0.3	V
V _I	Input voltage CNV _{SS}		−0.3 to 13	V
V _O	Output voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67, X _{OUT}		−0.3 to V _{CC} +0.3	V
P _d	Power dissipation	T _a = 25 °C	1000 (Note)	mW
T _{opr}	Operating temperature		−40 to 85	°C
T _{stg}	Storage temperature		−65 to 150	°C

RECOMMENDED OPERATING CONDITIONS (Extended operating temperature version)(V_{CC} = 4.0 to 5.5 V, T_a = −40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
V _{CC}	Power source voltage (f(X _{IN}) ≤ 2 MHz)	4.0	5.0	5.5	V
V _{SS}	Power source voltage		0		V
V _{REF}	Analog reference voltage (when A-D converter is used)	2.0		V _{CC}	V
	Analog reference voltage (when D-A converter is used)	4.0		V _{CC}	
AV _{SS}	Analog power source voltage		0		V
V _{IA}	Analog input voltage AN0–AN7	AV _{SS}		V _{CC}	V
V _{IH}	“H” input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	0.8 V _{CC}		V _{CC}	V
V _{IH}	“H” input voltage $\overline{\text{RESET}}$, X _{IN} , CNV _{SS}	0.8 V _{CC}		V _{CC}	V
V _{IL}	“L” input voltage P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67	0		0.2 V _{CC}	V
V _{IL}	“L” input voltage $\overline{\text{RESET}}$, CNV _{SS}	0		0.2 V _{CC}	V
V _{IL}	“L” input voltage X _{IN}	0		0.16 V _{CC}	V
ΣI _{OH} (peak)	“H” total peak output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 1)			−80	mA
ΣI _{OH} (peak)	“H” total peak output current P40–P47, P50–P57, P60–P67 (Note 1)			−80	mA
ΣI _{OL} (peak)	“L” total peak output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 1)			80	mA
ΣI _{OL} (peak)	“L” total peak output current P40–P47, P50–P57, P60–P67 (Note 1)			80	mA
ΣI _{OH} (avg)	“H” total average output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 1)			−40	mA
ΣI _{OH} (avg)	“H” total average output current P40–P47, P50–P57, P60–P67 (Note 1)			−40	mA
ΣI _{OL} (avg)	“L” total average output current P00–P07, P10–P17, P20–P27, P30–P37 (Note 1)			40	mA
ΣI _{OL} (avg)	“L” total average output current P40–P47, P50–P57, P60–P67 (Note 1)			40	mA
I _{OH} (peak)	“H” peak output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 2)			−10	mA
I _{OL} (peak)	“L” peak output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 2)			10	mA
I _{OH} (avg)	“H” average output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 3)			−5	mA
I _{OL} (avg)	“L” average output current P00–P07, P10–P17, P20–P27, P30–P37, P40–P47, P50–P57, P60–P67 (Note 3)			5	mA
f(X _{IN})	Internal clock oscillation frequency (V _{CC} = 4.0 to 5.5 V)			8	MHz

Note 1: The total output current is the sum of all the currents flowing through all the applicable ports. The total average current is an average value measured over 100 ms. The total peak current is the peak value of all the currents.

2: The peak output current is the peak current flowing in each port.

3: The average output current I_{OL}(avg), I_{OH}(avg) in an average value measured over 100 ms.

ELECTRICAL CHARACTERISTICS (Extended operating temperature version)

(VCC = 4.0 to 5.5 V, VSS = 0 V, Ta = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
VOH	"H" output voltage P00-P07, P10-P17, P20-P27, P30-P37, P40-P47, P50-P57, P60-P67 (Note 1)	IOH = -10 mA	VCC-2.0			V
VOL	"L" output voltage P00-P07, P10-P17, P20-P27, P30-P37, P40-P47, P50-P57, P60-P67	IOL = 10 mA			2.0	V
VT+ - VT-	Hysteresis CNTR0, CNTR1, INT0-INT4			0.4		V
VT+ - VT-	Hysteresis RXD, SCLK1, SIN2, SCLK2			0.5		V
VT+ - VT-	Hysteresis RESET			0.5		V
IiH	"H" input current P00-P07, P10-P17, P20-P27, P30-P37, P40-P47, P50-P57, P60-P67	Vi = VCC			5.0	μA
IiH	"H" input current RESET, CNVss	Vi = VCC			5.0	μA
IiH	"H" input current XIN	Vi = VCC		4		μA
IiL	"L" input current P00-P07, P10-P17, P20-P27, P30-P37, P40-P47, P50-P57, P60-P67, RESET, CNVss	Vi = VSS			-5.0	μA
IiL	"L" input current XIN	Vi = VSS		-4		μA
VRAM	RAM hold voltage	When clock stopped	2.0		5.5	V
ICC	Power source current	f(XIN) = 8 MHz		6.4	13	mA
		f(XIN) = 5 MHz		4	8	
		When WIT instruction is executed with f(XIN) = 8 MHz		1.5		
		When WIT instruction is executed with f(XIN) = 5 MHz		1		
		When STP instruction is executed with clock stopped, output transistors isolated.	Ta = 25 °C (Note 2) Ta = 85 °C (Note 2)	0.1	1 10	μA

Note 1: P45 is measured when the P45/TxD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is "0".

P51 is measured when the P51/SOUT2 P-channel output disable bit of the serial I/O2 control register (bit 7 of address 001D16) is "0".

2: With output transistors isolated and A-D converter having completed conversion, and not including current flowing through VREF pin.

A-D CONVERTER CHARACTERISTICS (Extended operating temperature version)

(VCC = 4.0 to 5.5 V, VSS = AVSS = 0 V, VREF = 2.0 V to VCC, Ta = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
—	Resolution				8	Bits
—	Absolute accuracy (excluding quantization error)			±1	±2.5	LSB
tCONV	Conversion time				50	tC(φ)
RLADDER	Ladder resistor			35		kΩ
IVREF	Reference power source input current (Note)	VREF = 5.0 V	50	150	200	μA
Ii(AD)	A-D port input current			0.5	5.0	μA

Note: When D-A conversion registers (addresses 003616 and 003716) contain "0016".

D-A CONVERTER CHARACTERISTICS (Extended operating temperature version)(V_{CC} = 4.0 to 5.5 V, V_{SS} = AV_{SS} = 0 V, V_{REF} = 4.0 V to V_{CC}, T_a = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
—	Resolution				8	Bits
—	Absolute accuracy				1.0	%
t _{su}	Setting time				3	μs
R _O	Output resistor		1	2.5	4	kΩ
I _{VREF}	Reference power source input current (Note)				3.2	mA

Note: Using one D-A converter, with the value in the D-A conversion register of the other D-A converter being "001₆", and excluding currents flowing through the A-D resistance ladder.

TIMING REQUIREMENTS 1 (Extended operating temperature version)

(VCC = 4.0 to 5.5 V, VSS = 0 V, Ta = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
tw(RESET)	Reset input "L" pulse width	2			μs
tc(XIN)	External clock input cycle time	125			ns
twH(XIN)	External clock input "H" pulse width	50			ns
twL(XIN)	External clock input "L" pulse width	50			ns
tc(CNTR)	CNTR0, CNTR1 input cycle time	200			ns
twH(CNTR)	CNTR0, CNTR1 input "H" pulse width	80			ns
twH(INT)	INT0 to INT4 input "H" pulse width	80			ns
twL(CNTR)	CNTR0, CNTR1 input "L" pulse width	80			ns
twL(INT)	INT0 to INT4 input "L" pulse width	80			ns
tc(SCLK1)	Serial I/O1 clock input cycle time (Note)	800			ns
tc(SCLK2)	Serial I/O2 clock input cycle time	1000			ns
twH(SCLK1)	Serial I/O1 clock input "H" pulse width (Note)	370			ns
twH(SCLK2)	Serial I/O2 clock input "H" pulse width	400			ns
twL(SCLK1)	Serial I/O1 clock input "L" pulse width (Note)	370			ns
twL(SCLK2)	Serial I/O2 clock input "L" pulse width	400			ns
tsu(RxD-SCLK1)	Serial I/O1 input set up time	220			ns
tsu(SIN2-SCLK2)	Serial I/O2 input set up time	200			ns
th(SCLK1-RxD)	Serial I/O1 input hold time	100			ns
th(SCLK2-SIN2)	Serial I/O2 input hold time	200			ns

Note: When f(XIN) = 8 MHz and bit 6 of address 001A16 is "1". Divide this value by four when f(XIN) = 8 MHz and bit 6 of address 001A16 is "0".

SWITCHING CHARACTERISTICS 1 (Extended operating temperature version)

(VCC = 4.0 to 5.5 V, VSS = 0 V, Ta = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
twH(SCLK1)	Serial I/O1 clock output "H" pulse width	Fig. 36	tc(SCLK1)/2-30			ns
twH(SCLK2)	Serial I/O2 clock output "H" pulse width		tc(SCLK2)/2-160			ns
twL(SCLK1)	Serial I/O1 clock output "L" pulse width		tc(SCLK1)/2-30			ns
twL(SCLK2)	Serial I/O2 clock output "L" pulse width		tc(SCLK2)/2-160			ns
td(SCLK1-TxD)	Serial I/O1 output delay time (Note 1)				140	ns
td(SCLK2-SOUT2)	Serial I/O2 output delay time (Note 2)				200	ns
tv(SCLK1-TxD)	Serial I/O1 output valid time (Note 1)		-30			ns
tv(SCLK2-SOUT2)	Serial I/O2 output valid time (Note 2)		0			ns
tr(SCLK1)	Serial I/O1 clock output rising time				30	ns
tr(SCLK1)	Serial I/O1 clock output falling time				30	ns
tr(SCLK2)	Serial I/O2 clock output rising time				30	ns
tr(SCLK2)	Serial I/O2 clock output falling time				40	ns
tr(CMOS)	CMOS output rising time (Note 3)			10	30	ns
tr(CMOS)	CMOS output falling time (Note 3)			10	30	ns

Note1: When the P45/TxD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is "0".

2: When the P51/SOUT2 P-channel output disable bit of the serial I/O2 control register (bit 7 of address 001D16) is "0".

3: XOUT pin excluded.

TIMING REQUIREMENTS IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(Extended operating temperature version)

(V_{CC} = 4.0 to 5.5 V, V_{SS} = 0 V, T_a = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
t _{su} ($\overline{\text{ONW}}-\phi$)	Before ϕ $\overline{\text{ONW}}$ input set up time	-20			ns
t _h ($\phi-\overline{\text{ONW}}$)	After ϕ $\overline{\text{ONW}}$ input hold time	-20			ns
t _{su} (DB- ϕ)	Before ϕ data bus set up time	60			ns
t _h (ϕ -DB)	After ϕ data bus hold time	0			ns
t _{su} ($\overline{\text{ONW}}-\overline{\text{RD}}$)	Before $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input set up time	-20			ns
t _{su} ($\overline{\text{ONW}}-\overline{\text{WR}}$)	Before $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input set up time	-20			ns
t _h ($\overline{\text{RD}}-\overline{\text{ONW}}$)	After $\overline{\text{RD}}$ $\overline{\text{ONW}}$ input hold time	-20			ns
t _h ($\overline{\text{WR}}-\overline{\text{ONW}}$)	After $\overline{\text{WR}}$ $\overline{\text{ONW}}$ input hold time	-20			ns
t _{su} (DB- $\overline{\text{RD}}$)	Before $\overline{\text{RD}}$ data bus set up time	65			ns
t _h ($\overline{\text{RD}}-\text{DB}$)	After $\overline{\text{RD}}$ data bus hold time	0			ns

SWITCHING CHARACTERISTICS IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(Extended operating temperature version)

(V_{CC} = 4.0 to 5.5 V, V_{SS} = 0 V, T_a = -40 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
t _c (ϕ)	ϕ clock cycle time	Fig. 36		2X t _c (X _{IN})		ns
t _{wH} (ϕ)	ϕ clock "H" pulse width		t _c (X _{IN})-10			ns
t _{wL} (ϕ)	ϕ clock "L" pulse width		t _c (X _{IN})-10			ns
t _d (ϕ -AH)	After ϕ AD15-AD8 delay time			20	40	ns
t _v (ϕ -AH)	After ϕ AD15-AD8 valid time		6	10		ns
t _d (ϕ -AL)	After ϕ AD7-AD0 delay time			25	45	ns
t _v (ϕ -AL)	After ϕ AD7-AD0 valid time		6	10		ns
t _d (ϕ -SYNC)	SYNC delay time			20		ns
t _v (ϕ -SYNC)	SYNC valid time			10		ns
t _d (ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ delay time			10	20	ns
t _v (ϕ - $\overline{\text{WR}}$)	$\overline{\text{RD}}$ and $\overline{\text{WR}}$ valid time		3	5	10	ns
t _d (ϕ -DB)	After ϕ data bus delay time			20	70	ns
t _v (ϕ -DB)	After ϕ data bus valid time		15			ns
t _{wL} ($\overline{\text{RD}}$)	$\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width		t _c (X _{IN})-10			ns
t _{wL} ($\overline{\text{WR}}$)	$\overline{\text{RD}}$ pulse width, $\overline{\text{WR}}$ pulse width (when one wait is valid)		3t _c (X _{IN})-10			ns
t _d (AH- $\overline{\text{RD}}$)	After AD15-AD8 $\overline{\text{RD}}$ delay time		t _c (X _{IN})-35	t _c (X _{IN})-15		ns
t _d (AH- $\overline{\text{WR}}$)	After AD15-AD8 $\overline{\text{WR}}$ delay time					
t _d (AL- $\overline{\text{RD}}$)	After AD7-AD0 $\overline{\text{RD}}$ delay time		t _c (X _{IN})-40	t _c (X _{IN})-20		ns
t _d (AL- $\overline{\text{WR}}$)	After AD7-AD0 $\overline{\text{WR}}$ delay time					
t _v ($\overline{\text{RD}}$ -AH)	After $\overline{\text{RD}}$ AD15-AD8 valid time		0	5		ns
t _v ($\overline{\text{WR}}$ -AH)	After $\overline{\text{WR}}$ AD15-AD8 valid time					
t _v ($\overline{\text{RD}}$ -AL)	After $\overline{\text{RD}}$ AD7-AD0 valid time		0	5		ns
t _v ($\overline{\text{WR}}$ -AL)	After $\overline{\text{WR}}$ AD7-AD0 valid time					
t _d ($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus delay time			15	65	ns
t _v ($\overline{\text{WR}}$ -DB)	After $\overline{\text{WR}}$ data bus valid time		10			ns
t _d (RESET-RESET _{OUT})	RESET _{OUT} output delay time				200	ns
t _v (ϕ -RESET)	RESET _{OUT} output valid time (Note 1)		0		200	ns

Note 1: The RESET_{OUT} output goes "H" in sync with the rise of the ϕ clock that is anywhere between about 8 cycle and 13 cycles after the RESET input goes "H".

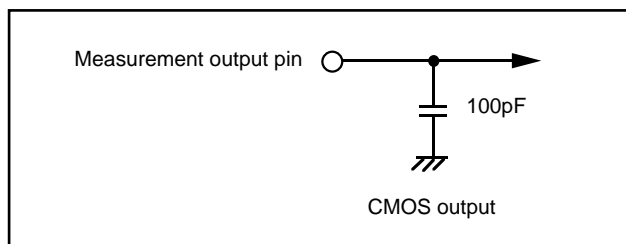
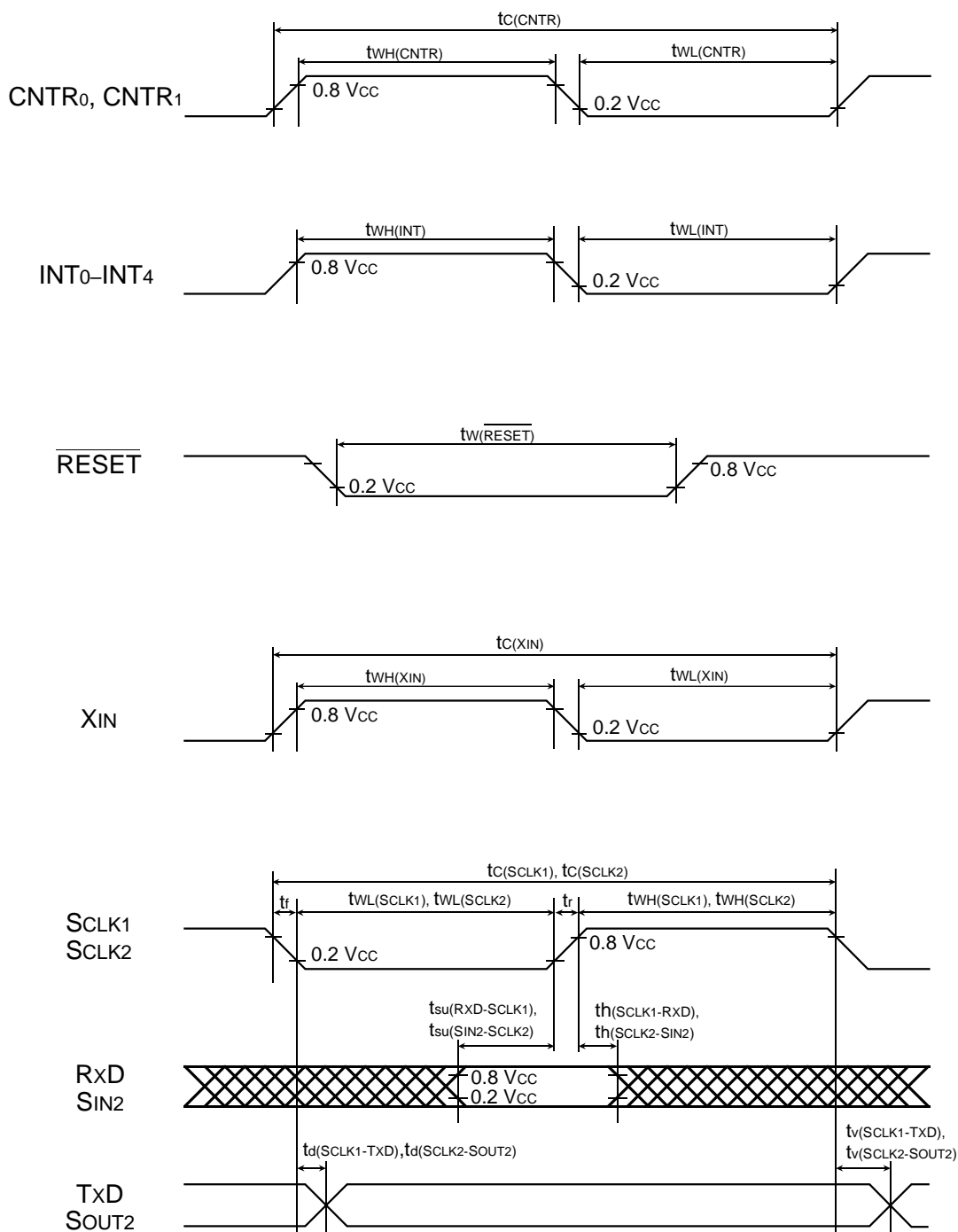


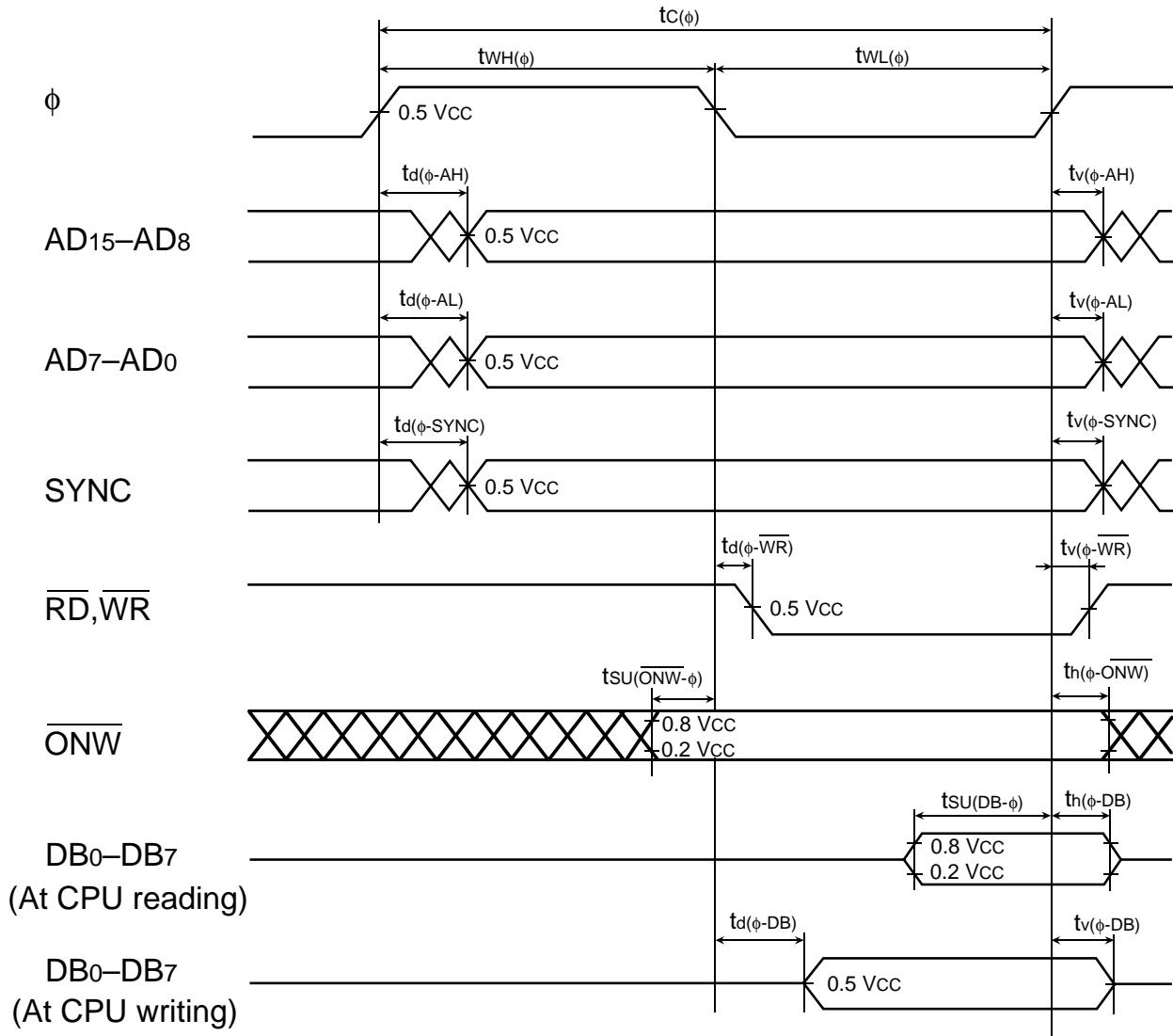
Fig. 36 Circuit for measuring output switching characteristics

TIMING DIAGRAM

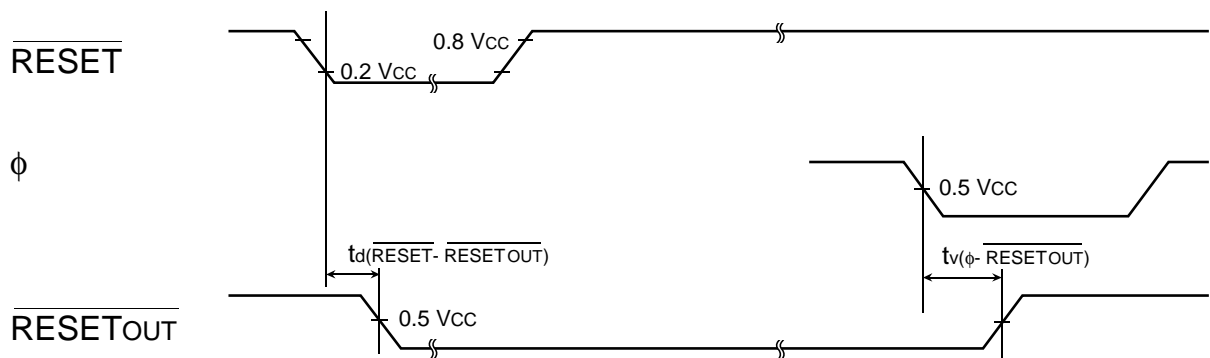
(1) Timing Diagram



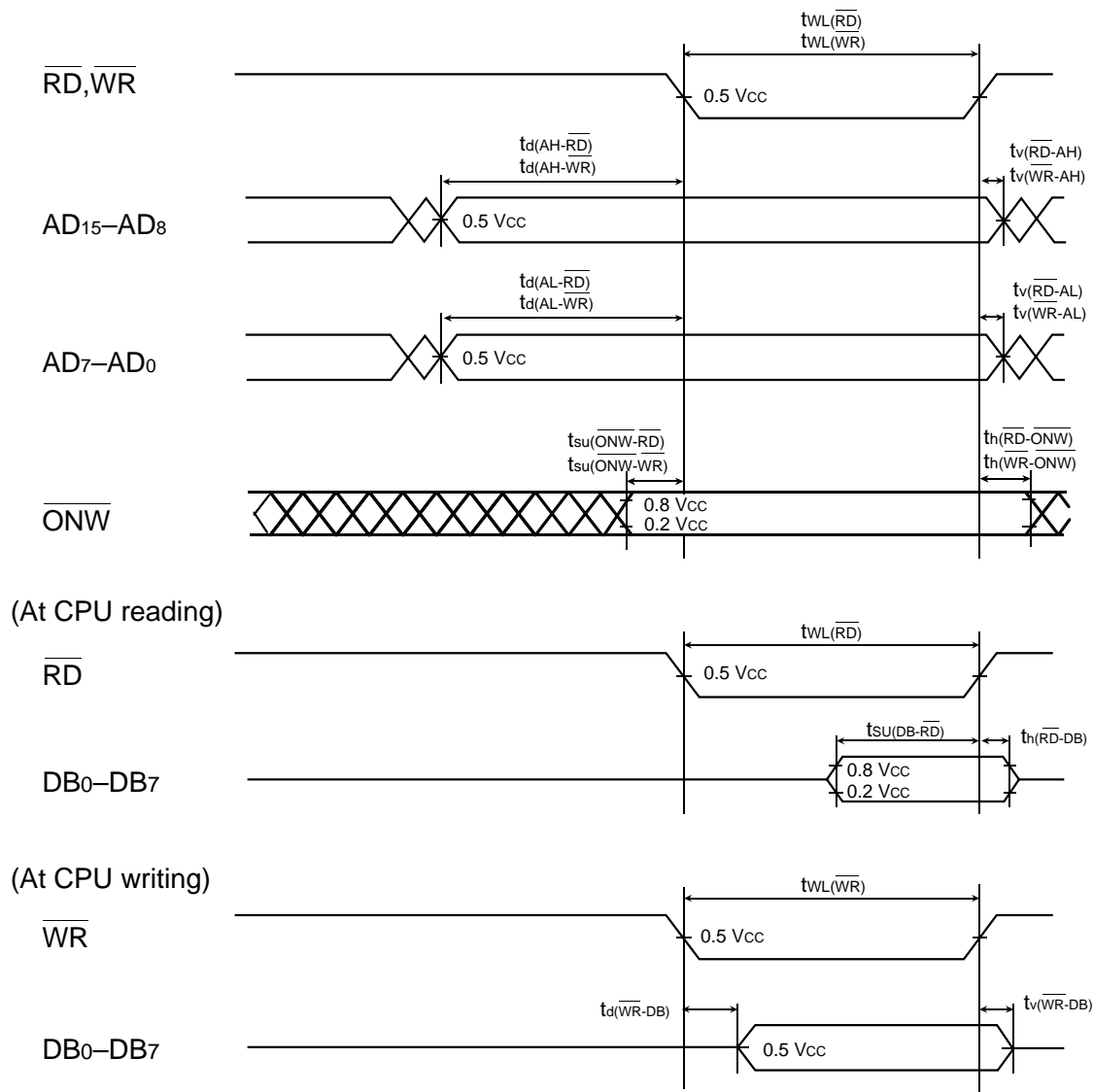
(2) Timing Diagram in Memory Expansion Mode and Microprocessor Mode (a)



(3) Timing Diagram in Microprocessor Mode



(4) Timing Diagram in Memory Expansion Mode and Microprocessor Mode (b)



Keep safety first in your circuit designs!

- Mitsubishi Electric Corporation puts the maximum effort into making semiconductor products better and more reliable, but there is always the possibility that trouble may occur with them. Trouble with semiconductors may lead to personal injury, fire or property damage. Remember to give due consideration to safety when making your circuit designs, with appropriate measures such as (i) placement of substitutive, auxiliary circuits, (ii) use of non-flammable material or (iii) prevention against any malfunction or mishap.

Notes regarding these materials

- These materials are intended as a reference to assist our customers in the selection of the Mitsubishi semiconductor product best suited to the customer's application; they do not convey any license under any intellectual property rights, or any other rights, belonging to Mitsubishi Electric Corporation or a third party.
- Mitsubishi Electric Corporation assumes no responsibility for any damage, or infringement of any third-party's rights, originating in the use of any product data, diagrams, charts or circuit application examples contained in these materials.
- All information contained in these materials, including product data, diagrams and charts, represent information on products at the time of publication of these materials, and are subject to change by Mitsubishi Electric Corporation without notice due to product improvements or other reasons. It is therefore recommended that customers contact Mitsubishi Electric Corporation or an authorized Mitsubishi Semiconductor product distributor for the latest product information before purchasing a product listed herein.
- Mitsubishi Electric Corporation semiconductors are not designed or manufactured for use in a device or system that is used under circumstances in which human life is potentially at stake. Please contact Mitsubishi Electric Corporation or an authorized Mitsubishi Semiconductor product distributor when considering the use of a product contained herein for any specific purposes, such as apparatus or systems for transportation, vehicular, medical, aerospace, nuclear, or undersea repeater use.
- The prior written approval of Mitsubishi Electric Corporation is necessary to reprint or reproduce in whole or in part these materials.
- If these products or technologies are subject to the Japanese export control restrictions, they must be exported under a license from the Japanese government and cannot be imported into a country other than the approved destination.
- Any diversion or reexport contrary to the export control laws and regulations of Japan and/or the country of destination is prohibited.
- Please contact Mitsubishi Electric Corporation or an authorized Mitsubishi Semiconductor product distributor for further details on these materials or the products contained therein.

