

V53C16125H
HIGH PERFORMANCE
128K X 16 BIT FAST PAGE MODE
CMOS DYNAMIC RAM

HIGH PERFORMANCE	40	45	50	60
Max. $\overline{\text{RAS}}$ Access Time, (t_{RAC})	40 ns	45 ns	50 ns	60 ns
Max. Column Address Access Time, (t_{CAA})	20 ns	22 ns	24 ns	30 ns
Min. Fast Page Mode Cycle Time, (t_{PC})	23 ns	25 ns	28 ns	40 ns
Min. Read/Write Cycle Time, (t_{RC})	75 ns	80 ns	90 ns	110 ns

Features

- 256K x 16-bit 1.6
- Fast Page Mode for a sustained data rate of 44 MHz
- $\overline{\text{RAS}}$ access time: 40, 45, 50, 60ns
- Dual $\overline{\text{CAS}}$ Inputs
- Low Power Dissipation
- Read-Modify-Write, $\overline{\text{RAS}}$ -Only Refresh, $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh
- Refresh Interval: 256 cycles/8 ms
- Available in 40-pin 400 mil SOJ and 40/44L-pin 400 mil TSOP-II packages
- Single +5V \pm 10% Power Supply
- TTL Interface

Description

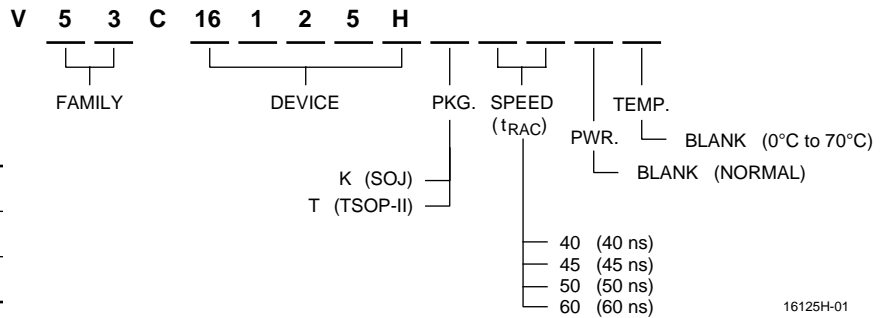
The V53C16125H is a 131,072 x 16 bit high performance CMOS dynamic random access memory. The V53C16125H offers Fast Page mode with dual $\overline{\text{CAS}}$ inputs. The V53C16125H has asymmetric address, 8-bit row and 9-bit column.

All inputs are TTL compatible. Fast Page Mode operation allows random access up to 256 x 16 bits, within a page, with cycle times as short as 19ns.

The V53C16125H is ideally suited for a wide variety of high performance computer systems and peripheral applications.

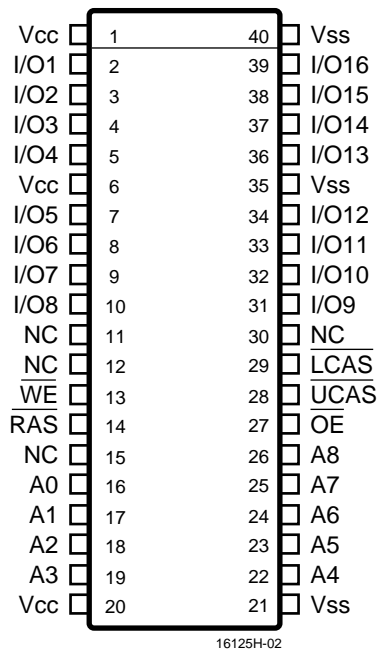
Device Usage Chart

Operating Temperature Range	Package Outline		Access Time (ns)				Power	Temperature Mark
	K	T	40	45	50	60	Std.	
0°C to 70 °C	•	•		•	•	•	•	Blank

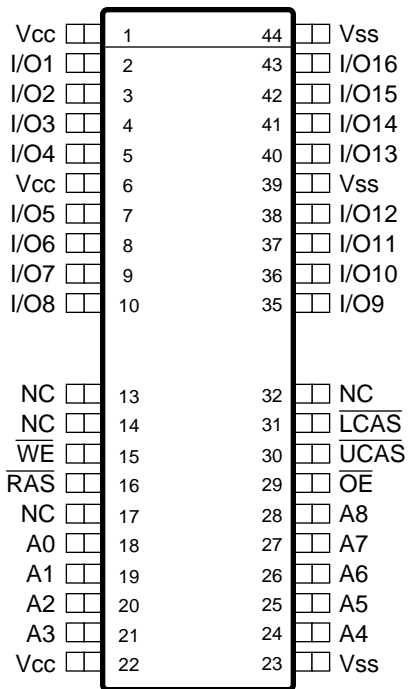


<i>Description</i>	<i>Pkg.</i>	<i>Pin Count</i>
SOJ	K	40
TSOP-II	T	40/44L

40-Pin Plastic SOJ
PIN CONFIGURATION
Top View



40/44L-Pin Plastic TSOP-II
PIN CONFIGURATION
Top View



Pin Names

A_0-A_8	Address Inputs
\overline{RAS}	Row Address Strobe
\overline{UCAS}	Column Address Strobe/Upper Byte Control
\overline{LCAS}	Column Address Strobe/Lower Byte Control
\overline{WE}	Write Enable
\overline{OE}	Output Enable
$I/O_1-I/O_{16}$	Data Input, Output
V_{CC}	+5V Supply
V_{SS}	0V Supply
NC	No Connect

Absolute Maximum Ratings*

Ambient Temperature

Under Bias -10°C to $+80^{\circ}\text{C}$

Storage Temperature (plastic) -55°C to $+125^{\circ}\text{C}$

Voltage Relative to V_{SS} -1.0 V to +7.0 V

Data Output Current 50 mA

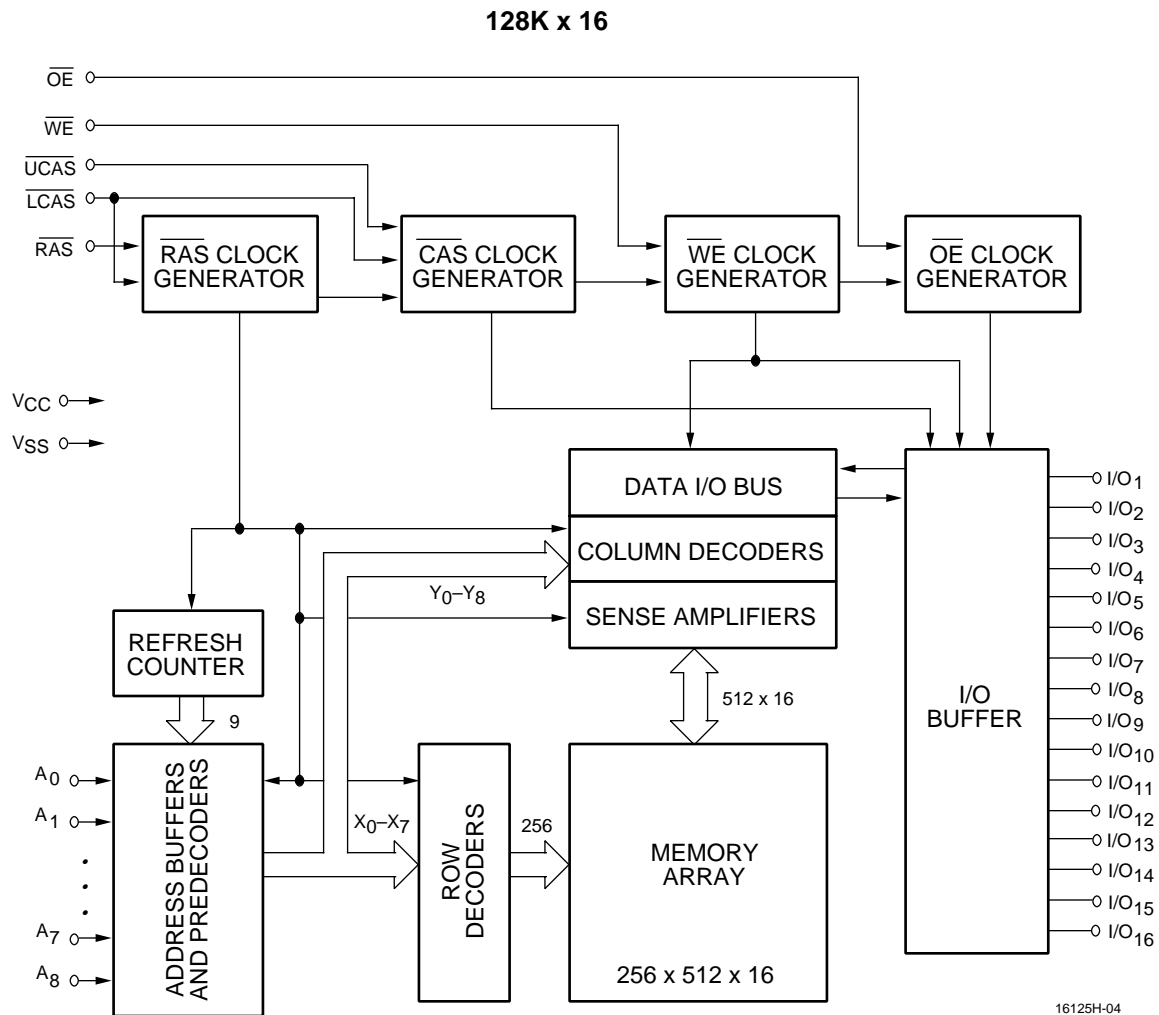
Data Output Current	55 mA
Power Dissipation	1.0 W

*Note: Operation above Absolute Maximum Ratings can adversely affect device reliability.

Capacitance*
$$T_A = 25^\circ\text{C}, V_{CC} = 5\text{ V} \pm 10\%, V_{SS} = 0\text{ V}$$

Symbol	Parameter	Typ.	Max.	Unit
C _{IN1}	Address Input	3	4	pF
C _{IN2}	RAS, CAS, \overline{WE} , \overline{OE}	4	5	pF
C _{OUT}	Data Input/Output	5	7	pF

*Note: Capacitance is sampled and not 100% tested

Block Diagram

DC and Operating Characteristics (1-2)

$T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$, unless otherwise specified.

Symbol	Parameter	Access Time	V53C16125H			Unit	Test Conditions	Notes
			Min.	Typ.	Max.			
I_{LI}	Input Leakage Current (any input pin)		-10		10	μA	$V_{SS} \leq V_{IN} \leq V_{CC}$	
I_{LO}	Output Leakage Current (for High-Z State)		-10		10	μA	$V_{SS} \leq V_{OUT} \leq V_{CC}$ $\overline{\text{RAS}}, \overline{\text{CAS}}$ at V_{IH}	
I_{CC1}	V_{CC} Supply Current, Operating	40			180	mA	$t_{RC} = t_{RC}(\text{min.})$	1, 2
		45			170			
		50			160			
		60			150			
I_{CC2}	V_{CC} Supply Current, TTL Standby				2	mA	$\overline{\text{RAS}}, \overline{\text{CAS}}$ at V_{IH} , other inputs $\geq V_{SS}$	
I_{CC3}	V_{CC} Supply Current, RAS-Only Refresh	40			180	mA	$t_{RC} = t_{RC}(\text{min.})$	2
		45			170			
		50			160			
		60			150			
I_{CC4}	V_{CC} Supply Current, Fast Page Mode Operation	40			170	mA	Minimum Cycle	1, 2
		45			160			
		50			150			
		60			140			
I_{CC5}	V_{CC} Supply Current, Standby, Output Enabled				2	mA	$\overline{\text{RAS}} = V_{IH}$, $\overline{\text{CAS}} = V_{IL}$, other inputs $\geq V_{SS}$	1
I_{CC6}	V_{CC} Supply Current, CMOS Standby				1	mA	$\overline{\text{RAS}} \geq V_{CC} - 0.2\text{ V}$, $\overline{\text{CAS}} \geq V_{CC} - 0.2\text{ V}$, All other inputs $\geq V_{SS}$	
V_{CC}	Supply Voltage		4.5	5.0	5.5	V		
V_{IL}	Input Low Voltage		-1		0.8	V		3
V_{IH}	Input High Voltage		2.4		$V_{CC} + 1$	V		3
V_{OL}	Output Low Voltage				0.4	V	$I_{OL} = 4.2\text{ mA}$	
V_{OH}	Output High Voltage		2.4		2.4	V	$I_{OH} = -5\text{ mA}$	

AC Characteristics

$T_A = 0^\circ\text{C}$ to 70°C , $V_{DD} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{V}$ unless otherwise noted

AC Test conditions, input pulse levels 0 to 3V15

#	Symbol	Parameter	40		45		50		60		Unit	Notes
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.		
1	t_{RAS}	\overline{RAS} Pulse Width	40	75K	45	75K	50	75K	60	75K	ns	
2	t_{RC}	Read or Write Cycle Time	75		80		90		110		ns	
3	t_{RP}	\overline{RAS} Precharge Time	25		25		30		40		ns	
4	t_{CSH}	\overline{CAS} Hold Time	40		45		50		60		ns	
5	t_{CAS}	\overline{CAS} Pulse Width	12		13		14		15		ns	
6	t_{RCD}	\overline{RAS} to \overline{CAS} Delay	17	28	18	32	19	36	20	45	ns	
7	t_{RCS}	Read Command Setup Time	0		0		0		0		ns	4
8	t_{ASR}	Row Address Setup Time	0		0		0		0		ns	
9	t_{RAH}	Row Address Hold Time	7		8		9		10		ns	
10	t_{ASC}	Column Address Setup Time	0		0		0		0		ns	
11	t_{CAH}	Column Address Hold Time	5		6		7		10		ns	
12	$t_{RSH(R)}$	\overline{RAS} Hold Time (Read Cycle)	12		13		14		15		ns	
13	t_{CRP}	\overline{CAS} to \overline{RAS} Precharge Time	4		4		5		5		ns	
14	t_{RCH}	Read Command Hold Time Referenced to \overline{CAS}	0		0		0		0		ns	5
15	t_{RRH}	Read Command Hold Time Referenced to \overline{RAS}	0		0		0		0		ns	5
16	t_{ROH}	\overline{RAS} Hold Time Referenced to \overline{OE}	8		9		10		10		ns	
17	t_{OAC}	Access Time from \overline{OE}		12		13		14		15	ns	
18	t_{CAC}	Access Time from \overline{CAS}		12		13		14		15	ns	6, 7
19	t_{RAC}	Access Time from \overline{RAS}		40		45		50		60	ns	6, 8, 9
20	t_{CAA}	Access Time from Column Address		20		22		24		30	ns	6, 7, 10
21	t_{LZ}	\overline{OE} or \overline{CAS} to Low-Z Output	0		0		0		0		ns	16
22	t_{HZ}	\overline{OE} or \overline{CAS} to High-Z Output	0	6	0	7	0	8	0	10	ns	16
23	t_{AR}	Column Address Hold Time from \overline{RAS}	30		35		40		50		ns	
24	t_{RAD}	\overline{RAS} to Column Address Delay Time	12	20	13	23	14	26	15	30	ns	11
25	$t_{RSH(W)}$	\overline{RAS} or \overline{CAS} Hold Time in Write Cycle	12		13		14		15		ns	
26	t_{CWL}	Write Command to \overline{CAS} Lead Time	12		13		14		15		ns	
27	t_{WCS}	Write Command Setup Time	0		0		0		0		ns	12, 13
28	t_{WCH}	Write Command Hold Time	5		6		7		10		ns	

AC Characteristics (Cont'd)

#	Symbol	Parameter	40		45		50		60		Unit	Notes
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.		
29	t_{WP}	Write Pulse Width	5		6		7		10		ns	
30	t_{WCR}	Write Command Hold Time from \overline{RAS}	30		35		40		50		ns	
31	t_{RWL}	Write Command to \overline{RAS} Lead Time	12		13		14		15		ns	
32	t_{DS}	Data in Setup Time	0		0		0		0		ns	14
33	t_{DH}	Data in Hold Time	5		6		7		10		ns	14
34	t_{WOH}	Write to \overline{OE} Hold Time	6		7		8		10		ns	14
35	t_{OED}	\overline{OE} to Data Delay Time	6		7		8		10		ns	14
36	t_{RWC}	Read-Modify-Write Cycle Time	110		115		130		170		ns	
37	t_{RRW}	Read-Modify-Write Cycle \overline{RAS} Pulse Width	75		80		87		105		ns	
38	t_{CWD}	\overline{CAS} to \overline{WE} Delay	30		32		34		40		ns	12
39	t_{RWD}	\overline{RAS} to \overline{WE} Delay in Read-Modify-Write Cycle	58		62		68		85		ns	12
40	t_{CRW}	\overline{CAS} Pulse Width (RMW)	48		50		52		65		ns	
41	t_{AWD}	Col. Address to \overline{WE} Delay	38		41		42		58		ns	12
42	t_{PC}	Fast Page Mode Read or Write Cycle Time	23		25		28		35		ns	
43	t_{CP}	\overline{CAS} Precharge Time	5		6		7		10		ns	
44	t_{CAR}	Column Address to \overline{RAS} Setup Time	20		22		24		30		ns	
45	t_{CAP}	Access Time from Column Precharge		22		24		27		34	ns	7
46	t_{DHR}	Data in Hold Time Referenced to RAS	30		35		40		50		ns	
47	t_{CSR}	\overline{CAS} Setup Time \overline{CAS} -before- \overline{RAS} Refresh	10		10		10		10		ns	
48	t_{RPC}	RAS to CAS Precharge Time	0		0		0		0		ns	
49	t_{CHR}	\overline{CAS} Hold Time \overline{CAS} -before- \overline{RAS} Refresh	8		10		12		15		ns	
50	t_{PCM}	Fast Page Mode Read-Modify-Write Cycle Time	60		65		70		85		ns	
51	t_T	Transition Time (Rise and Fall)	3	50	3	50	3	50	3	50	ns	15
52	t_{REF}	Refresh Interval (256 Cycles)		8		8		8		8	ms	17

Notes

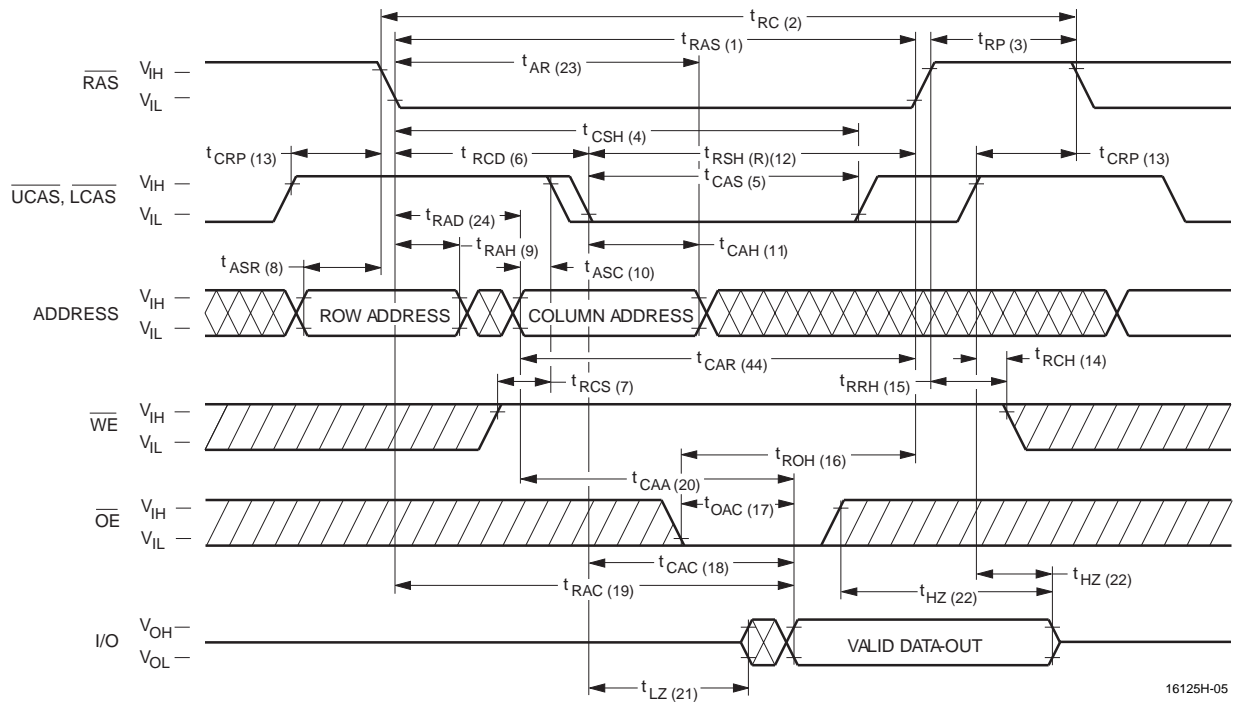
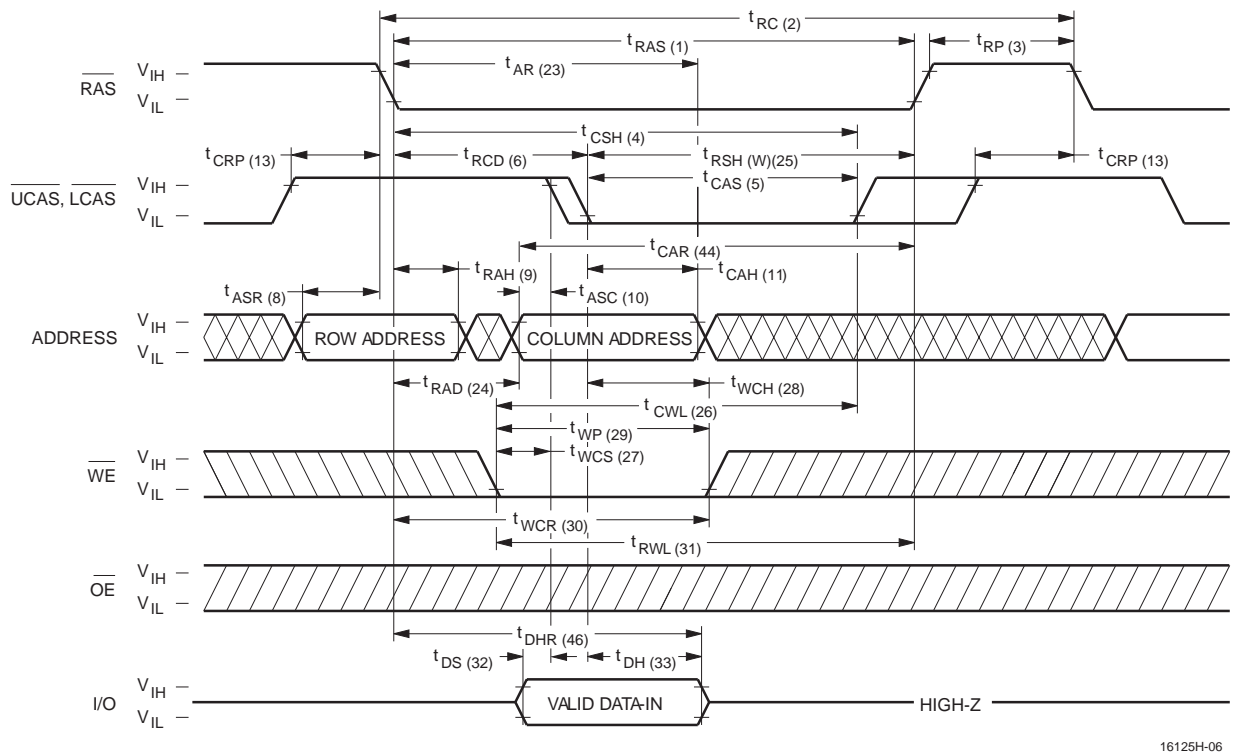
1. I_{CC} is dependent on output loading when the device output is selected. Specified I_{CC} (max.) is measured with the output open.
2. I_{CC} is dependent upon the number of address transitions. Specified I_{CC} (max.) is measured with a maximum of two transitions per address cycle in Fast Page Mode.
3. Specified V_{IL} (min.) is steady state operating. During transitions, V_{IL} (min.) may undershoot to -1.0 V for a period not to exceed 20 ns. All AC parameters are measured with V_{IL} (min.) $\geq V_{SS}$ and V_{IH} (max.) $\leq V_{CC}$.
4. t_{RCD} (max.) is specified for reference only. Operation within t_{RCD} (max.) limits insures that t_{RAC} (max.) and t_{CAA} (max.) can be met. If t_{RCD} is greater than the specified t_{RCD} (max.), the access time is controlled by t_{CAA} and t_{CAC} .
5. Either t_{RRH} or t_{RCH} must be satisfied for a Read Cycle to occur.
6. Measured with a load equivalent to two TTL inputs and 50 pF.
7. Access time is determined by the longest of t_{CAA} , t_{CAC} and t_{CAP} .
8. Assumes that $t_{RAD} \leq t_{RAD}$ (max.). If t_{RAD} is greater than t_{RAD} (max.), t_{RAC} will increase by the amount that t_{RAD} exceeds t_{RAD} (max.).
9. Assumes that $t_{RCD} \leq t_{RCD}$ (max.). If t_{RCD} is greater than t_{RCD} (max.), t_{RAC} will increase by the amount that t_{RCD} exceeds t_{RCD} (max.).
10. Assumes that $t_{RAD} \geq t_{RAD}$ (max.).
11. Operation within the t_{RAD} (max.) limit ensures that t_{RAC} (max.) can be met. t_{RAD} (max.) is specified as a reference point only. If t_{RAD} is greater than the specified t_{RAD} (max.) limit, the access time is controlled by t_{CAA} and t_{CAC} .
12. t_{WCS} , t_{RWD} , t_{AWD} and t_{CWD} are not restrictive operating parameters.
13. t_{WCS} (min.) must be satisfied in an Early Write Cycle.
14. t_{DS} and t_{DH} are referenced to the latter occurrence of \overline{CAS} or \overline{WE} .
15. t_T is measured between V_{IH} (min.) and V_{IL} (max.). AC-measurements assume $t_T = 3$ ns.
16. Assumes a three-state test load (5 pF and a 380 Ohm Thevenin equivalent).
17. An initial 200 μ s pause and 8 \overline{RAS} -containing cycles are required when exiting an extended period of bias without clocks. An extended period of time without clocks is defined as one that exceeds the specified Refresh Interval.

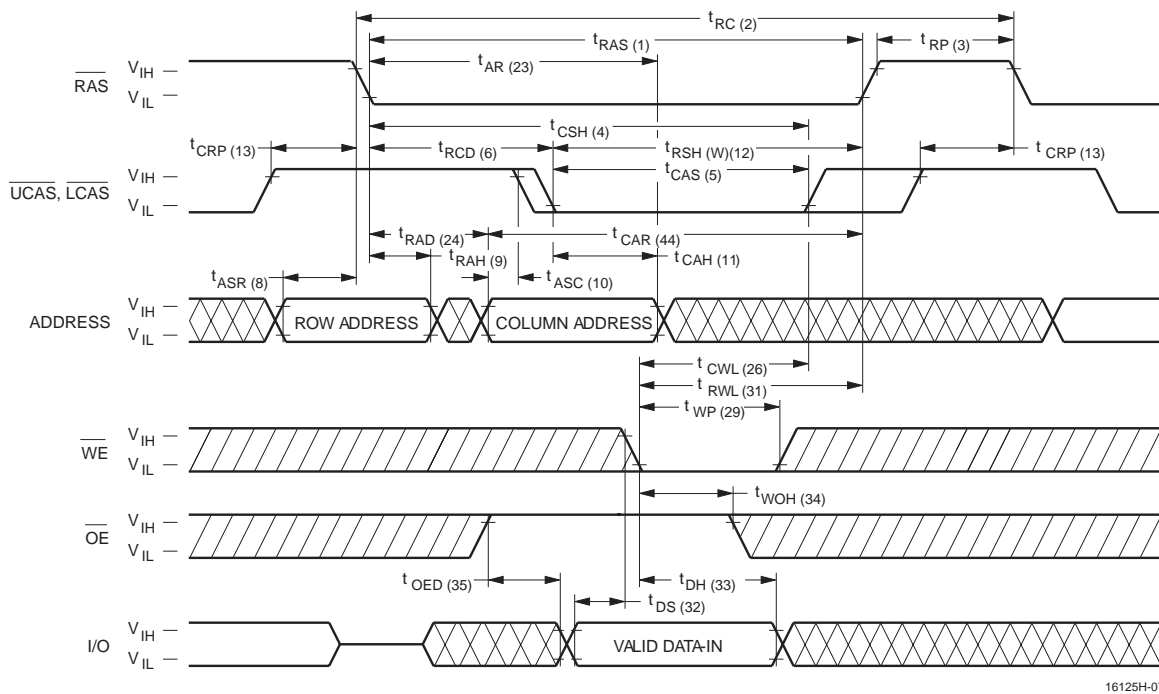
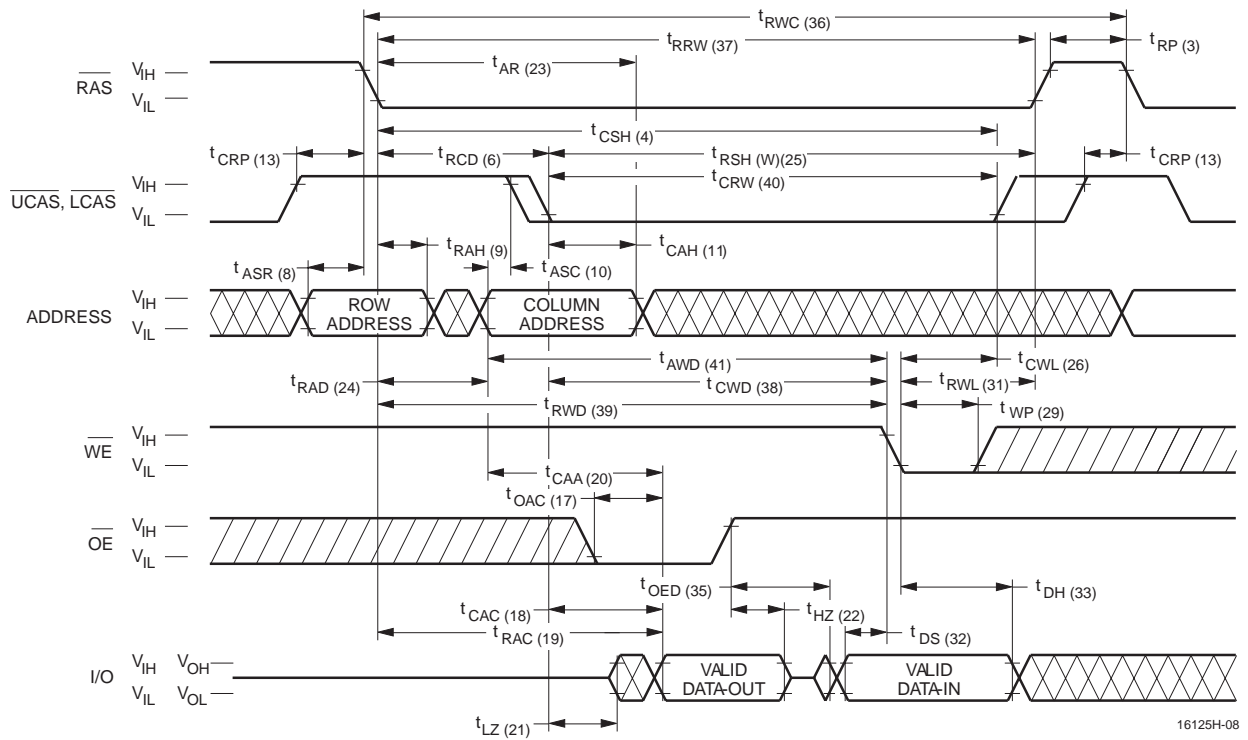
Truth Table

Function	$\overline{\text{RAS}}$	$\overline{\text{LCAS}}$	$\overline{\text{UCAS}}$	$\overline{\text{WE}}$	$\overline{\text{OE}}$	ADDRESS	I/O	Notes
Standby	H	H	H	X	X	X	High-Z	
Read: Word	L	L	L	H	L	ROW/COL	Data Out	
Read: Lower Byte	L	L	H	H	L	ROW/COL	Lower Byte, Data-Out	
							Upper Byte, High-Z	
Read: Upper Byte	L	H	L	H	L	ROW/COL	Lower Byte, High-Z	
							Upper Byte, Data-Out	
Write: Word (Early-Write)	L	L	L	L	X	ROW/COL	Data-In	
Write: Lower Byte (Early)	L	L	H	L	X	ROW/COL	Lower Byte, Data-In	
							Upper Byte, High-Z	
Read: Upper Byte (Early)	L	H	L	L	X	ROW/COL	Lower Byte, High-Z	
							Upper Byte, Data-In	
Read-Write	L	L	L	H→L	L→H	ROW/COL	Data-Out, Data-In	1,2
Page-Mode Read	L	H→L	H→L	H	L	COL	Data-Out	2
Page-Mode Write	L	H→L	H→L	L	X	COL	Data-In	2
Page-Mode Read-Write	L	H→L	H→L	H→L	L→H	COL	Data-Out, Data-In	1,2
Hidden Refresh Read	L→H→L	L	L	H	L	ROW/COL	Data-Out	2
RAS-Only Refresh	L	H	H	X	X	ROW	High-Z	
CBR Refresh	H→L	L	L	X	X	X	High-Z	3

Notes:

1. Byte Write cycles $\overline{\text{LCAS}}$ or $\overline{\text{UCAS}}$ active.
2. Byte Read cycles $\overline{\text{LCAS}}$ or $\overline{\text{UCAS}}$ active.
3. Only one of the two $\overline{\text{CAS}}$ must be active ($\overline{\text{LCAS}}$ or $\overline{\text{UCAS}}$).

Waveforms of Read Cycle**Waveforms of Early Write Cycle**

Waveforms of \overline{OE} -Controlled Write Cycle**Waveforms of Read-Modify-Write Cycle**

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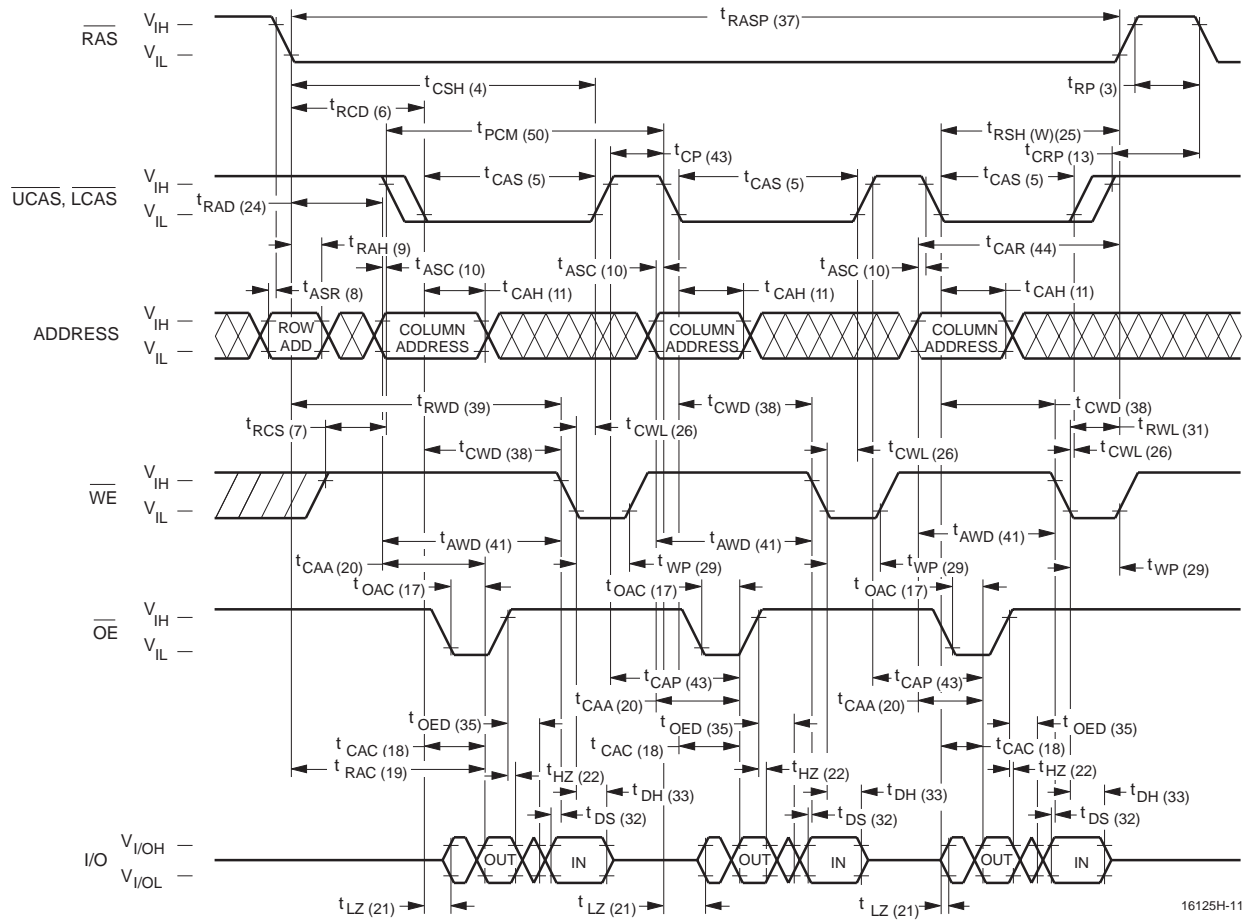
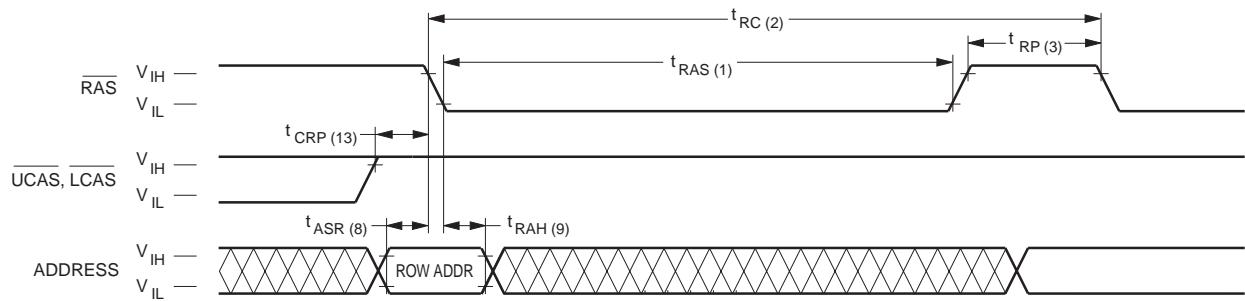
16125H-09

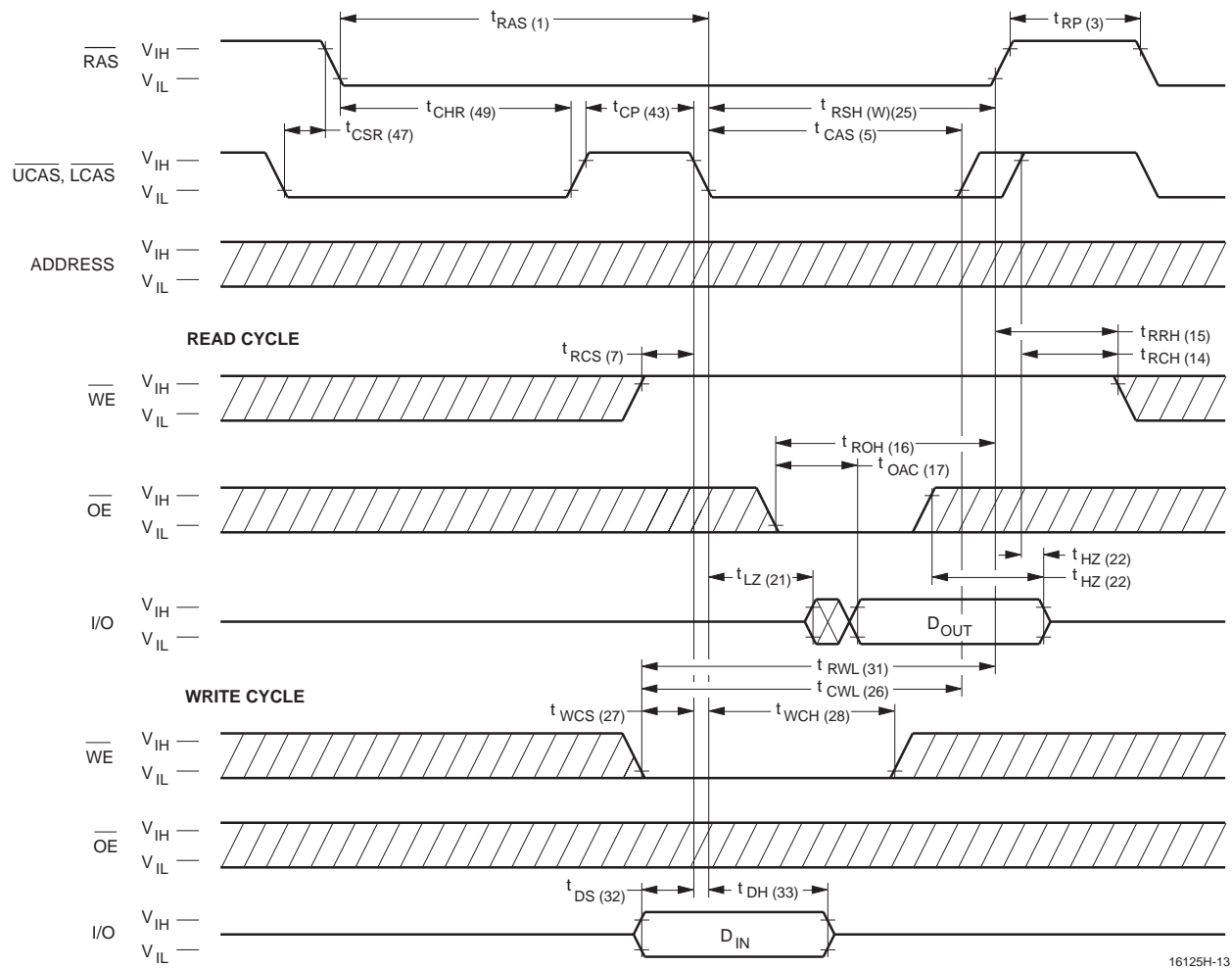
The timing diagram illustrates the relationship between several signals and their timing parameters:

- RAS:** Shows the RAS signal with parameters t_{AR} (23), t_{RASP} (37), and t_{RP} (3).
- UCAS, LCAS:** Shows the UCAS and LCAS signals with parameters t_{CRP} (13), t_{PC} (42), t_{CP} (43), t_{RSH} (W)(25), and t_{CAS} (5).
- ADDRESS:** Shows the ADDRESS signal with parameters t_{RAH} (9), t_{ASH} (8), t_{CAH} (11), t_{ASC} (10), t_{CAR} (44), and t_{CAH} (11).
- WE:** Shows the WE signal with parameters t_{RAD} (24), t_{CWL} (26), t_{WCS} (27), t_{WCH} (28), t_{WP} (29), t_{RWL} (31), t_{WCH} (28), and t_{WP} (29).
- OE:** Shows the OE signal with parameters t_{DS} (32) and t_{DH} (33).
- I/O:** Shows the I/O signal with parameters t_{DS} (32) and t_{DH} (33).

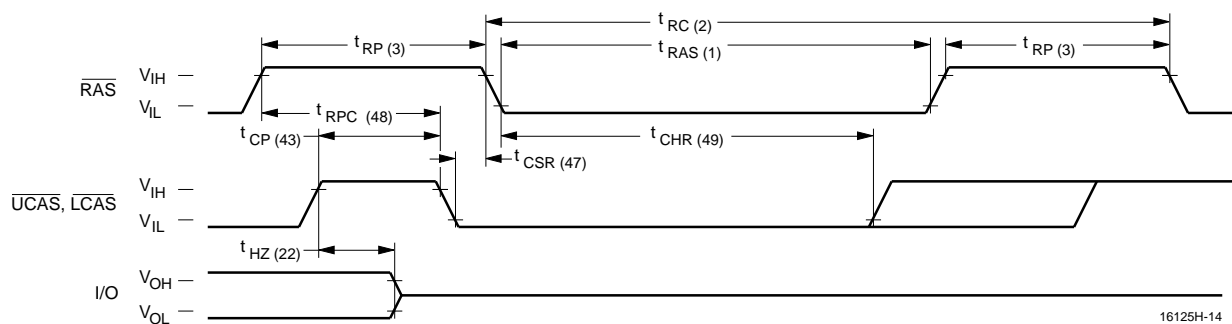
The diagram also includes labels for **ROW ADDRESS**, **COLUMN ADDRESS**, **VALID DATA IN**, and **OPEN**.

16125H-10

Waveforms of Fast Page Mode Read-Write Cycle**Waveforms of RAS-Only Refresh Cycle**NOTE: $\overline{\text{WE}}$, $\overline{\text{OE}}$ = Don't care

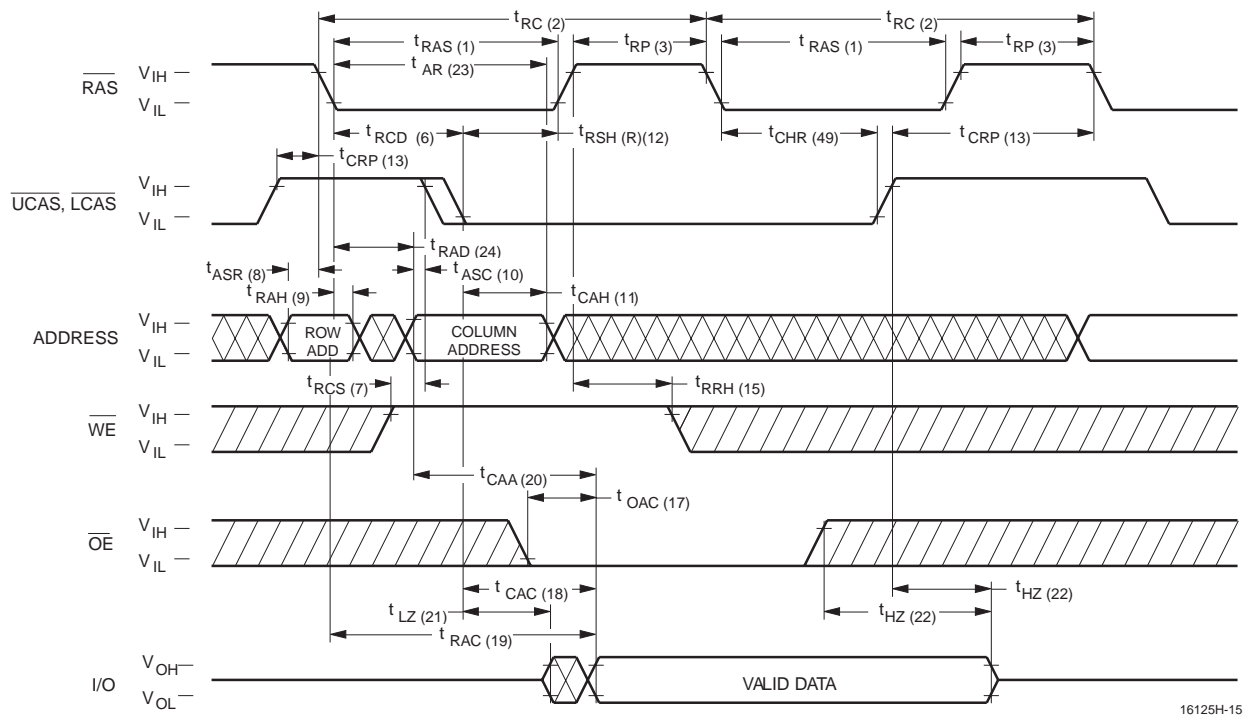
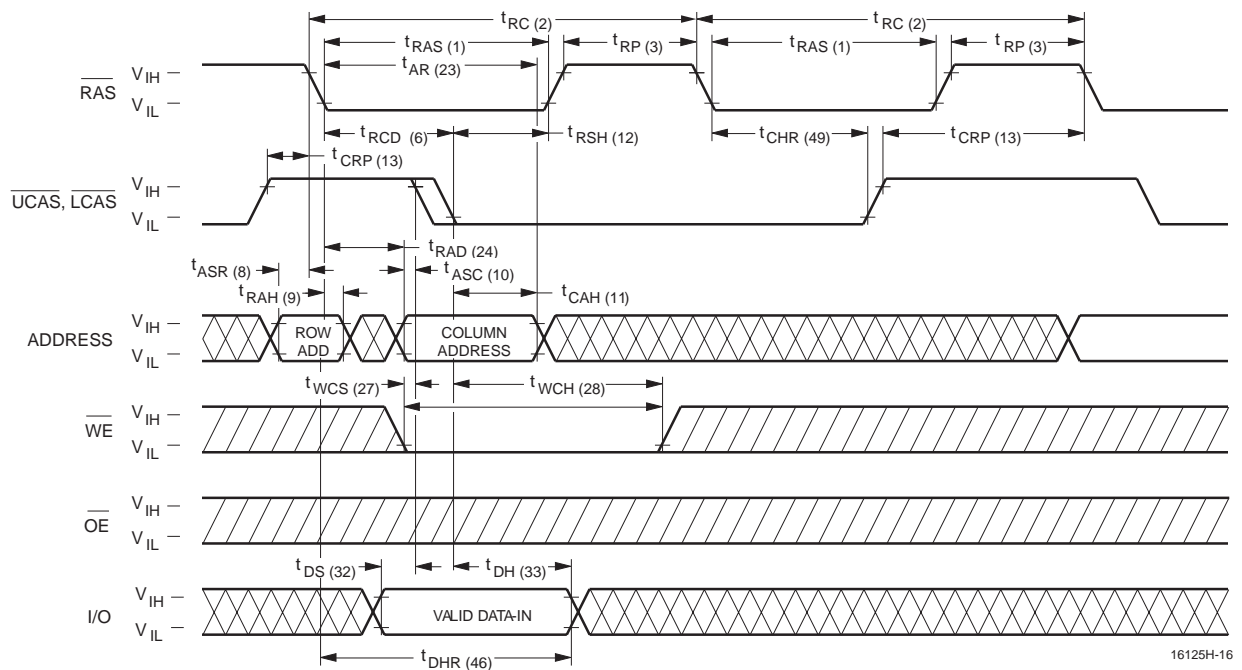
Waveforms of $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ Refresh Counter Test Cycle

16125H-13

Waveforms of $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ Refresh Cycle

16125H-14

NOTE: $\overline{\text{WE}}$, $\overline{\text{OE}}$, A_0-A_8 = Don't care

Waveforms of Hidden Refresh Cycle (Read)**Waveforms of Hidden Refresh Cycle (Write)**

Functional Description

The V53C16125H is a CMOS dynamic RAM optimized for high data bandwidth, low power applications. It is functionally similar to a traditional dynamic RAM. The V53C16125H reads and writes data by multiplexing an 17-bit address into a 8-bit row and a 9-bit column address. The row address is latched by the Row Address Strobe (\overline{RAS}). The column address “flows through” an internal address buffer and is latched by the Column Address Strobe (\overline{CAS}). Because access time is primarily dependent on a valid column address rather than the precise time that the \overline{CAS} edge occurs, the delay time from \overline{RAS} to \overline{CAS} has little effect on the access time.

Memory Cycle

A memory cycle is initiated by bringing \overline{RAS} low. Any memory cycle, once initiated, must not be ended or aborted before the minimum t_{RAS} time has expired. This ensures proper device operation and data integrity. A new cycle must not be initiated until the minimum precharge time t_{RP}/t_{CP} has elapsed.

Read Cycle

A Read cycle is performed by holding the Write Enable (\overline{WE}) signal High during a $\overline{RAS}/\overline{CAS}$ operation. The column address must be held for a minimum specified by t_{AR} . Data Out becomes valid only when t_{OAC} , t_{RAC} , t_{CAA} and t_{CAC} are all satisfied. As a result, the access time is dependent on the timing relationships between these parameters. For example, the access time is limited by t_{CAA} when t_{RAC} , t_{CAC} and t_{OAC} are all satisfied.

Write Cycle

A Write Cycle is performed by taking \overline{WE} and \overline{CAS} low during a \overline{RAS} operation. The column address is latched by \overline{CAS} . The Write Cycle can be \overline{WE} controlled or \overline{CAS} controlled depending on whether \overline{WE} or \overline{CAS} falls later. Consequently, the input data must be valid at or before the falling edge of \overline{WE} or \overline{CAS} , whichever occurs last. In the \overline{CAS} -controlled Write Cycle, when the leading edge of \overline{WE} occurs prior to the \overline{CAS} low transition, the I/O data pins will be in the High-Z state at the beginning of the Write function. Ending the Write with \overline{RAS} or \overline{CAS} will maintain the output in the High-Z state.

In the \overline{WE} controlled Write Cycle, \overline{OE} must be in the high state and t_{OED} must be satisfied.

Refresh Cycle

To retain data, 256 Refresh Cycles are required in each 8 ms period. There are two ways to refresh the memory:

1. By clocking each of the 512 row addresses (A_0 through A_8) with \overline{RAS} at least once every 8 ms. Any Read, Write, Read-Modify-Write or \overline{RAS} -only cycle refreshes the addressed row.
2. Using a \overline{CAS} -before- \overline{RAS} Refresh Cycle. If \overline{CAS} makes a transition from low to high to low after the previous cycle and before \overline{RAS} falls, \overline{CAS} -before- \overline{RAS} refresh is activated. The V53C16125H uses the output of an internal 9-bit counter as the source of row addresses and ignore external address inputs.

\overline{CAS} -before- \overline{RAS} is a “refresh-only” mode and no data access or device selection is allowed. Thus, the output remains in the High-Z state during the cycle. A \overline{CAS} -before- \overline{RAS} counter test mode is provided to ensure reliable operation of the internal refresh counter.

Fast Page Mode Operation

Fast Page Mode operation permits all 512 columns within a selected row of the device to be randomly accessed at a high data rate. Maintaining $\overline{\text{RAS}}$ low while performing successive $\overline{\text{CAS}}$ cycles retains the row address internally and eliminates the need to reapply it for each cycle. The column address buffer acts as a transparent or flow-through latch while $\overline{\text{CAS}}$ is high. Thus, access begins from the occurrence of a valid column address rather than from the falling edge of $\overline{\text{CAS}}$, eliminating t_{ASC} and t_{T} from the critical timing path. $\overline{\text{CAS}}$ latches the address into the column address buffer and acts as an output enable. During Fast Page Mode operation, Read, Write, Read-Modify-Write or Read-Write-Read cycles are possible at random addresses within a row. Following the initial entry cycle into Fast Page Mode, access is t_{CAA} or t_{CAP} controlled. If the column address is valid prior to the rising edge of $\overline{\text{CAS}}$, the access time is referenced to the $\overline{\text{CAS}}$ rising edge and is specified by t_{CAP} . If the column address is valid after the rising $\overline{\text{CAS}}$ edge, access is timed from the occurrence of a valid address and is specified by t_{CAA} . In both cases, the falling edge of $\overline{\text{CAS}}$ latches the address and enables the output.

Fast Page Mode provides sustained data rates up to 40 MHz for applications that require high data rates such as bit-mapped graphics or high-speed signal processing. The following equation can be used to calculate the maximum data rate:

$$\text{Data Rate} = \frac{512}{t_{\text{RC}} + 511 \times t_{\text{PC}}}$$

Data Output Operation

The V53C16125H Input/Output is controlled by $\overline{\text{OE}}$, $\overline{\text{CAS}}$, $\overline{\text{WE}}$ and $\overline{\text{RAS}}$. A $\overline{\text{RAS}}$ low transition enables the transfer of data to and from the selected row address in the Memory Array. A $\overline{\text{RAS}}$ high transition disables data transfer and latches the output data if the output is enabled. After a memory cycle is initiated with a $\overline{\text{RAS}}$ low transition, a $\overline{\text{CAS}}$ low transition or $\overline{\text{CAS}}$ low level enables the internal I/O path. A $\overline{\text{CAS}}$ high transition or a $\overline{\text{CAS}}$ high level disables the I/O path and the output driver if it is enabled. A $\overline{\text{CAS}}$ low transition while $\overline{\text{RAS}}$ is high has no effect on the I/O data path or on the output drivers. The output drivers, when otherwise enabled, can be disabled by holding $\overline{\text{OE}}$ high. The $\overline{\text{OE}}$ signal has no effect on any data stored in the output latches. A $\overline{\text{WE}}$ low level can

also disable the output drivers when $\overline{\text{CAS}}$ is low. During a Write cycle, if $\overline{\text{WE}}$ goes low at a time in relationship to $\overline{\text{CAS}}$ that would normally cause the outputs to be active, it is necessary to use $\overline{\text{OE}}$ to disable the output drivers prior to the $\overline{\text{WE}}$ low transition to allow Data In Setup Time (t_{DS}) to be satisfied.

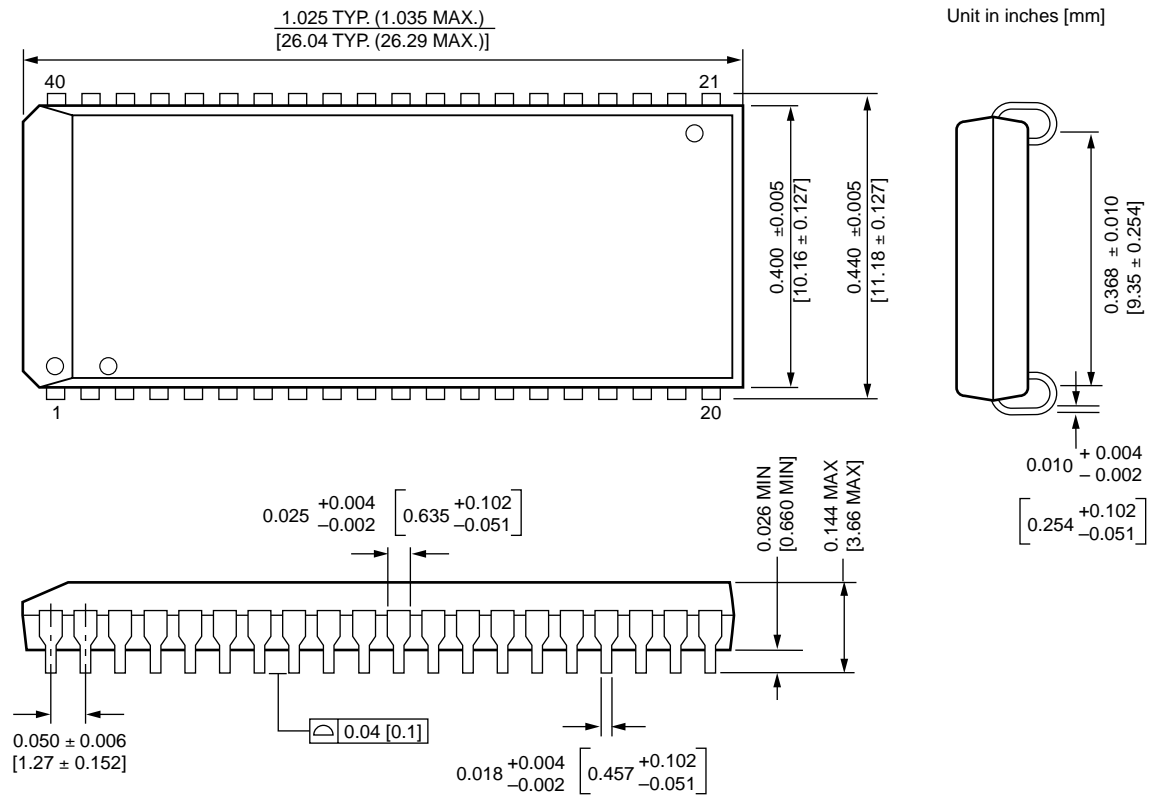
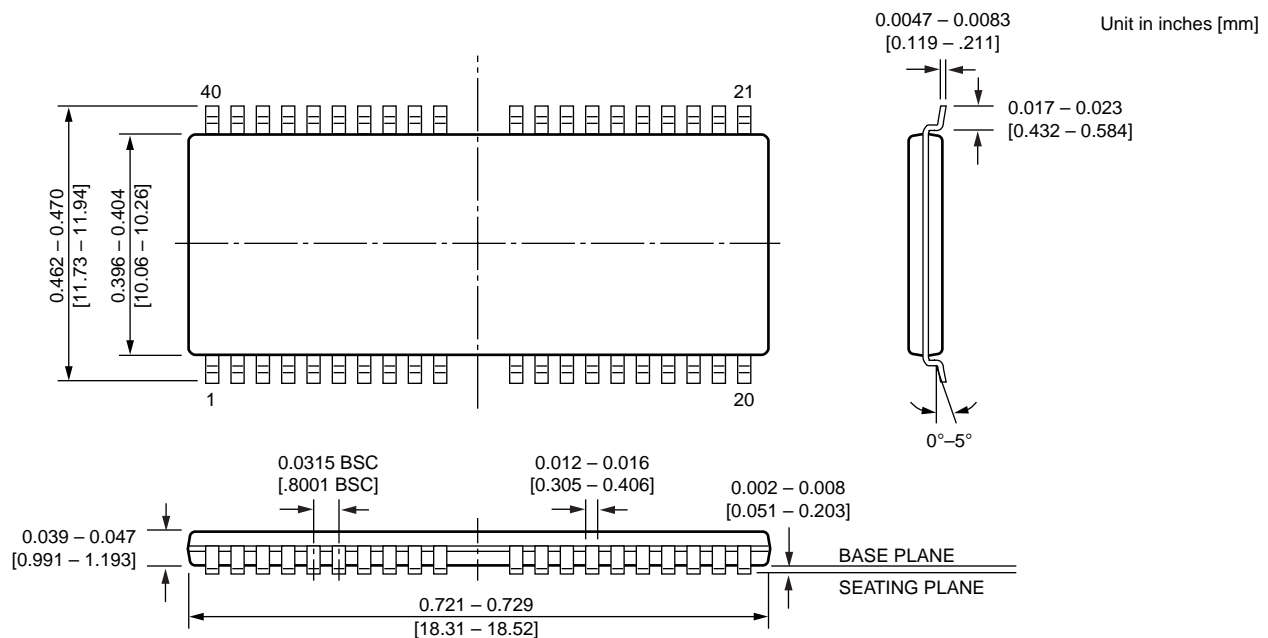
Power-On

After application of the V_{CC} supply, an initial pause of 200 μs is required followed by a minimum of 8 initialization cycles (any combination of cycles containing a $\overline{\text{RAS}}$ clock). Eight initialization cycles are required after extended periods of bias without clocks (greater than the Refresh Interval).

During Power-On, the V_{CC} current requirement of the V53C16125H is dependent on the input levels of $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$. If $\overline{\text{RAS}}$ is low during Power-On, the device will go into an active cycle and I_{DD} will exhibit current transients. It is recommended that $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ track with V_{CC} or be held at a valid V_{IH} during Power-On to avoid current surges.

**Table 1. V53C16125H Data Output
Operation for Various Cycle Types**

Cycle Type	I/O State
Read Cycles	Data from Addressed Memory Cell
$\overline{\text{CAS}}$ -Controlled Write Cycle (Early Write)	High-Z
$\overline{\text{WE}}$ -Controlled Write Cycle (Late Write)	$\overline{\text{OE}}$ Controlled. High $\overline{\text{OE}}$ = High-Z I/Os
Read-Modify-Write Cycles	Data from Addressed Memory Cell
Fast Page Mode Read	Data from Addressed Memory Cell
Fast Page Mode Write Cycle (Early Write)	High-Z
Fast Page Mode Read-Modify-Write Cycle	Data from Addressed Memory Cell
$\overline{\text{RAS}}$ -only Refresh	High-Z
$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ Refresh Cycle	Data remains as in previous cycle
$\overline{\text{CAS}}$ -only Cycles	High-Z

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