

64K X 16 FAST PAGE MODE**BYTE WRITE CMOS DYNAMIC RAM**

HIGH PERFORMANCE	30	35	40	45	50
Max. $\overline{\text{RAS}}$ Access Time, (t_{RAC})	30 ns	35 ns	40 ns	45 ns	50 ns
Max. Column Address Access Time, (t_{CAA})	16 ns	18 ns	20 ns	22 ns	24 ns
Min. Fast Page Mode Cycle Time, (t_{PC})	19 ns	21 ns	23 ns	25 ns	28 ns
Min. Read/Write Cycle Time, (t_{RC})	65 ns	70 ns	75 ns	80 ns	90 ns

Features

- 64K by 16-bit organization
- Fast Page Mode for a sustained data rate of 53 MHz
- $\overline{\text{RAS}}$ Access time: 30, 35, 40, 45, 50 ns
- Dual $\overline{\text{WE}}$ Inputs
- Low power dissipation
- Read-Modify-Write, $\overline{\text{RAS}}$ -Only Refresh, $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ refresh
- Refresh Interval: 256 cycles/4ms
- Available in 40-pin 400 mil SOJ and 40/44L-pin 400 mil TSOP-II packages
- Single +5V \pm 10% Power Supply
- TTL Interface

Description

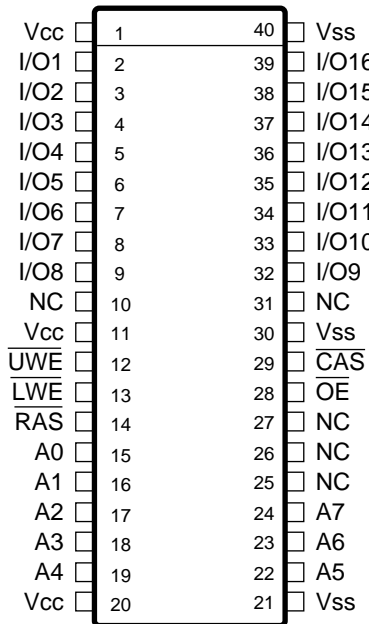
The V53C664H is a high speed 65,536 x 16 bit high performance CMOS dynamic random access memory. The V53C664H offers a combination of unique features including: Fast Page Mode operation for sustained high bandwidth with Page Mode cycle times as short as 19ns. All inputs are TTL compatible. Input and output capacitance is significantly lowered to increase performance and minimize loading.

The addition of Byte Write control, of upper and lower byte, makes the V53C664H ideally suited for use in 16- and 32-bit wide data bus systems.

Device Usage Chart

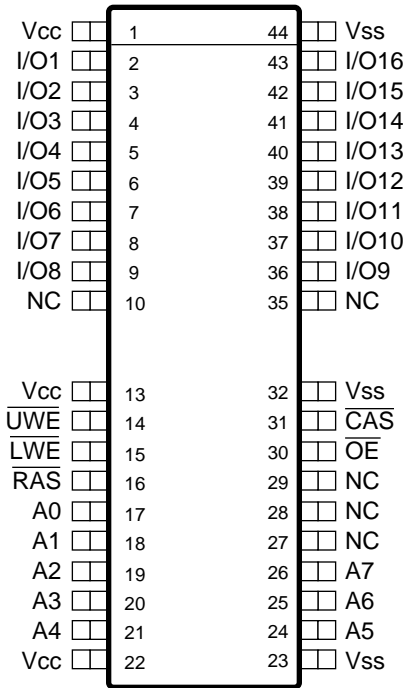
Operating Temperature Range	Package Outline		Access Time (ns)					Power	Temperature Mark
	K	T	30	35	40	45	50	Std.	
0°C to 70°C	•	•	•	•	•	•	•	•	Blank

40-Pin Plastic SOJ
PIN CONFIGURATION
Top View



664H-02

40/44L-Pin Plastic TSOP-II
PIN CONFIGURATION
Top View



664H-03

Pin Names

Symbol	Name
A0–A7	Address Inputs
RAS	Row Address Strobe
CAS	Column Address Strobe
UWE	Read/Upper Byte Write Input
LWE	Read/Lower Byte Write Input
OE	Output Enable
I/O1–I/O16	Data Input/Output
V _{CC}	+5V Supply
V _{SS}	0V Supply
NC	No Connect

Absolute Maximum Ratings*

Ambient Temperature

Under Bias -10°C to +80°C

Storage Temperature (plastic) -55°C to +125°C

Voltage Relative to V_{SS} -1.0 to +7.0 V

Data Out Current 50 mA

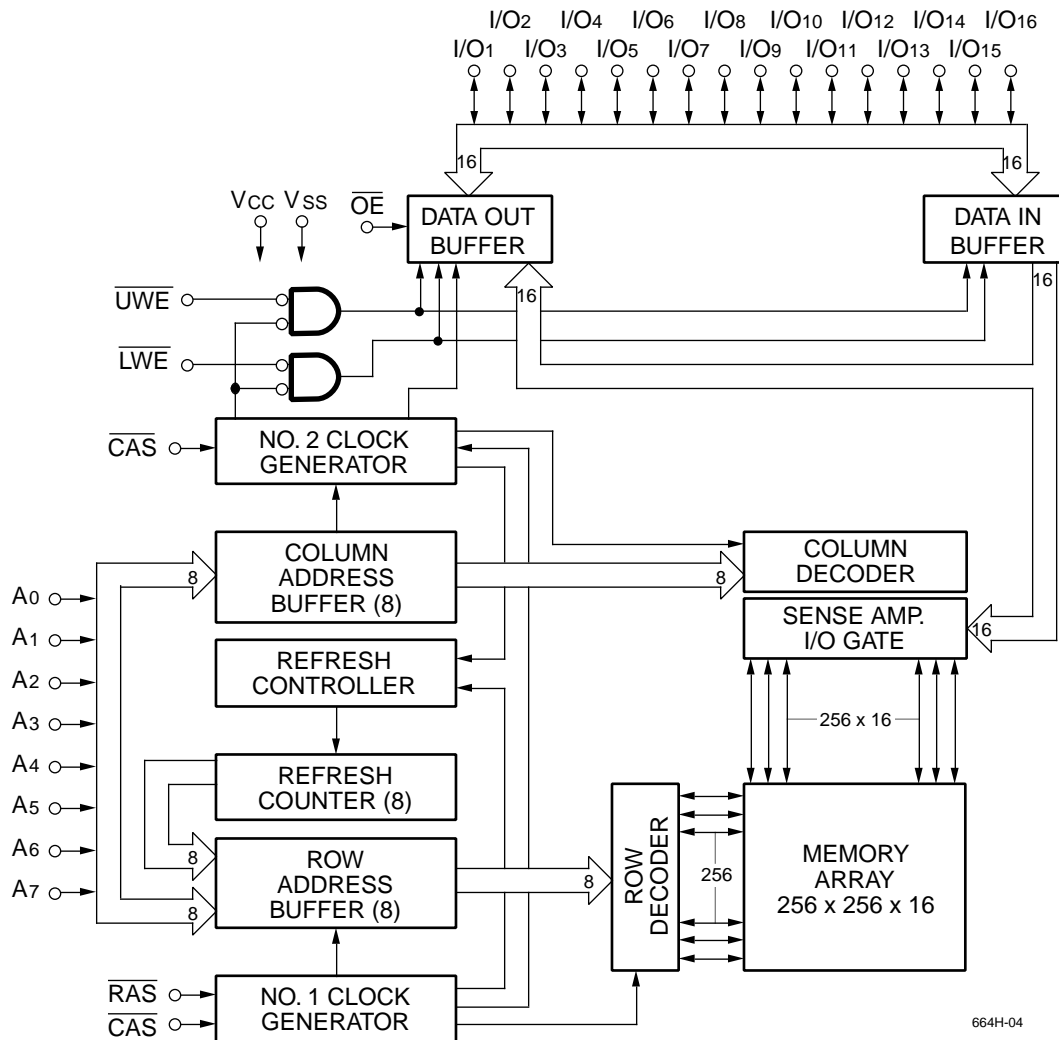
Power Dissipation 1.0 W

***Note:** Operation above Absolute Maximum Ratings can adversely affect device reliability.

Capacitance* $V_{CC} = 5V \pm 10\%$, $V_{SS} = 0V$

Symbol	Parameter	Min.	Max.	Unit
C_{IN1}	Address Input (A0–A7)	3	4	pF
C_{IN2}	Address Input (\overline{RAS} , \overline{CAS} , \overline{UWE} , \overline{LWE} , \overline{OE})	4	5	pF
C_{OUT}	Data Input/Output (I/O1–I/O16)	5	7	pF

***Note:** Capacitance is sampled and not 100% tested

Block Diagram

664H-04

DC and Operating Characteristics (1-2)

$T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$, unless otherwise specified.

Symbol	Parameter	Access Time	V53C664H			Unit	Test Conditions	Notes
			Min.	Typ.	Max.			
I_{LI}	Input Leakage Current (any input pin)		-10		10	μA	$V_{SS} \leq V_{IN} \leq V_{CC}$	
I_{LO}	Output Leakage Current (for High-Z State)		-10		10	μA	$V_{SS} \leq V_{OUT} \leq V_{CC}$ $\overline{\text{RAS}}, \overline{\text{CAS}}$ at V_{IH}	
I_{CC1}	V_{CC} Supply Current, Operating	30			200	mA	$t_{RC} = t_{RC} (\text{min.})$	1, 2
		35			190			
		40			180			
		45			170			
		50			160			
I_{CC2}	V_{CC} Supply Current, TTL Standby				2	mA	$\overline{\text{RAS}}, \overline{\text{CAS}}$ at V_{IH} , other inputs $\geq V_{SS}$	
I_{CC3}	V_{CC} Supply Current, $\overline{\text{RAS}}$ -Only Refresh	30			200	mA	$t_{RC} = t_{RC} (\text{min.})$	2
		35			190			
		40			180			
		45			170			
		50			160			
I_{CC4}	V_{CC} Supply Current, Fast Page Mode Operation	30			190	mA	Minimum Cycle	1, 2
		35			180			
		40			170			
		45			160			
		50			150			
I_{CC5}	V_{CC} Supply Current, Standby Output Enable other inputs $\geq V_{SS}$				2	mA	$\overline{\text{RAS}} = V_{IH}$ $\overline{\text{CAS}} = V_{IL}$	1
I_{CC6}	V_{CC} Supply Current, CMOS Standby				1	mA	$\overline{\text{RAS}} \geq V_{CC} - 0.2\text{ V}$, $\overline{\text{CAS}} \geq V_{CC} - 0.2\text{ V}$, All other inputs $\geq V_{SS}$	
V_{CC}	Supply Voltage		4.5	5.0	5.5	V		
V_{IL}	Input Low Voltage		-1		0.8	V		3
V_{IH}	Input High Voltage		2.4		$V_{CC} + 1$	V		3
V_{OL}	Output Low Voltage				0.4	V	$I_{OL} = 4.2\text{ mA}$	
V_{OH}	Output High Voltage		2.4			V	$I_{OH} = -5\text{ mA}$	

AC Characteristics

$T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{V}$ unless otherwise noted

AC Test conditions, input pulse levels 0 to 3V

#	Symbol	Parameter	30		35		40		45		50		Unit	Notes
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.		
1	t_{RAS}	\overline{RAS} Pulse Width	30	75K	35	75K	40	75K	45	75K	50	75K	ns	
2	t_{RC}	Read or Write Cycle Time	65		70		75		80		90		ns	
3	t_{RP}	\overline{RAS} Precharge Time	25		25		25		25		30		ns	
4	t_{CSH}	\overline{CAS} Hold Time	30		35		40		45		50		ns	
5	t_{CAS}	\overline{CAS} Pulse Width	5		6		7		8		9		ns	
6	t_{RCD}	\overline{RAS} to \overline{CAS} Delay	15	20	16	24	17	28	18	32	19	36	ns	
7	t_{RCS}	Read Command Setup Time	0		0		0		0		0		ns	4
8	t_{ASR}	Row Address Setup Time	0		0		0		0		0		ns	
9	t_{RAH}	Row Address Hold Time	5		6		7		8		9		ns	
10	t_{ASC}	Column Address Setup Time	0		0		0		0		0		ns	
11	t_{CAH}	Column Address Hold Time	5		5		5		6		7		ns	
12	$t_{RSH(R)}$	\overline{RAS} Hold Time (Read Cycle)	10		10		10		10		10		ns	
13	t_{CRP}	\overline{CAS} to \overline{RAS} Precharge Time	5		5		5		5		5		ns	
14	t_{RCH}	Read Command Hold Time Referenced to \overline{CAS}	0		0		0		0		0		ns	5
15	t_{RRH}	Read Command Hold Time Referenced to \overline{RAS}	0		0		0		0		0		ns	5
16	t_{ROH}	\overline{RAS} Hold Time Referenced to \overline{OE}	6		7		8		9		10		ns	
17	t_{OAC}	Access Time from \overline{OE}		10		11		12		13		14	ns	12
18	t_{CAC}	Access Time from \overline{CAS}		10		11		12		13		14	ns	6,7,14
19	t_{RAC}	Access Time from \overline{RAS}		30		35		40		45		50	ns	6, 8, 9
20	t_{CAA}	Access Time from Column Address		16		18		20		22		24	ns	6,7,10
21	t_{LZ}	\overline{OE} or \overline{CAS} to Low-Z Output	0		0		0		0		0		ns	16
22	t_{HZ}	\overline{OE} or \overline{CAS} to High-Z Output	0	5	0	6	0	6	0	7	0	8	ns	16
23	t_{AR}	Column Address Hold Time from \overline{RAS}	26		28		30		35		40		ns	
24	t_{RAD}	\overline{RAS} to Column Address Delay Time	10	14	11	17	12	20	13	23	14	26	ns	11
25	$t_{RSH(W)}$	\overline{RAS} or \overline{CAS} Hold Time in Write Cycle	10		10		10		10		10		ns	
26	t_{CWL}	Write Command to \overline{CAS} Lead Time	10		11		12		13		14		ns	
27	t_{WCS}	Write Command Setup Time	0		0		0		0		0		ns	12, 13

AC Characteristics (Cont'd)

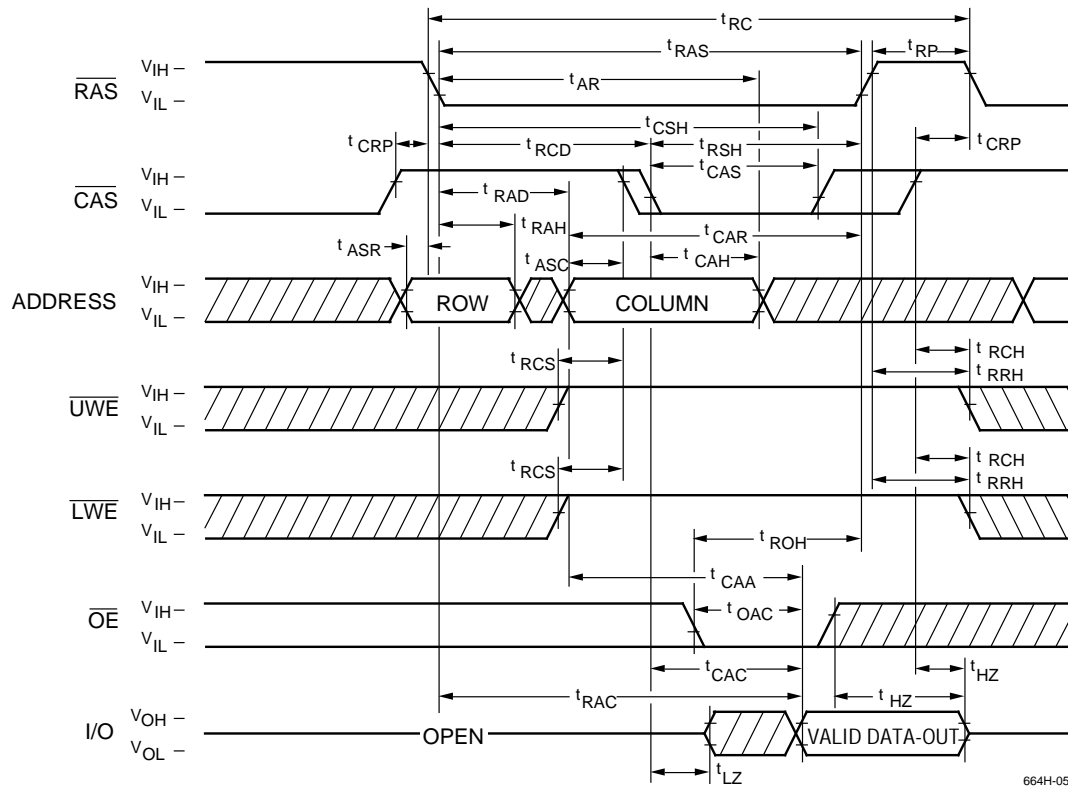
#	Symbol	Parameter	30		35		40		45		50		Unit	Notes
			Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.		
28	t_{WCH}	Write Command Hold Time	5		5		5		6		7		ns	
29	t_{WP}	Write Pulse Width	5		5		5		6		7		ns	
30	t_{WCR}	Write Command Hold Time from \overline{RAS}	26		28		30		35		40		ns	
31	t_{RWL}	Write Command to \overline{RAS} Lead Time	10		11		12		13		14		ns	
32	t_{DS}	Data in Setup Time	0		0		0		0		0		ns	14
33	t_{DH}	Data in Hold Time	5		5		5		6		7		ns	14
34	t_{WOH}	Write to \overline{OE} Hold Time	5		5		6		7		8		ns	14
35	t_{OED}	\overline{OE} to Data Delay Time	5		5		6		7		8		ns	14
36	t_{RWC}	Read-Modify-Write Cycle Time	100		105		110		115		130		ns	
37	t_{RRW}	Read-Modify-Write Cycle \overline{RAS} Pulse Width	65		70		75		80		87		ns	
38	t_{CWD}	\overline{CAS} to \overline{WE} Delay	26		28		30		32		34		ns	12
39	t_{RWD}	\overline{RAS} to \overline{WE} Delay in Read-Modify-Write Cycle	50		54		58		62		68		ns	12
40	t_{CRW}	\overline{CAS} Pulse Width (RMW)	44		46		48		50		52		ns	
41	t_{AWD}	Col. Address to \overline{WE} Delay	32		35		38		41		42		ns	12
42	t_{PC}	Fast Page Mode Read or Write Cycle Time	19		21		23		25		28		ns	
43	t_{CP}	\overline{CAS} Precharge Time	3		4		5		6		7		ns	
44	t_{CAR}	Column Address to \overline{RAS} Setup Time	16		18		20		22		24		ns	
45	t_{CAP}	Access Time from Column Precharge		19		21		23		25		27	ns	7
46	t_{DHR}	Data in Hold Time Referenced to \overline{RAS}	26		28		30		35		40		ns	
47	t_{CSR}	\overline{CAS} Setup Time \overline{CAS} - before- \overline{RAS} Refresh	10		10		10		10		10		ns	
48	t_{RPC}	\overline{RAS} to \overline{CAS} Precharge Time	0		0		0		0		0		ns	
49	t_{CHR}	\overline{CAS} Hold Time \overline{CAS} -before- \overline{RAS} Refresh	7		8		8		10		12		ns	
50	t_{PCM}	Fast Page Mode Read-Modify-Write Cycle Time	56		58		60		65		70		ns	
51	t_T	Transition Time (Rise and Fall)	1.5	50	1.5	50	1.5	50	1.5	50	1.5	50	ns	15
52	t_{REF}	Refresh Interval (256 Cycles)		4		4		4		4		4	ms	17

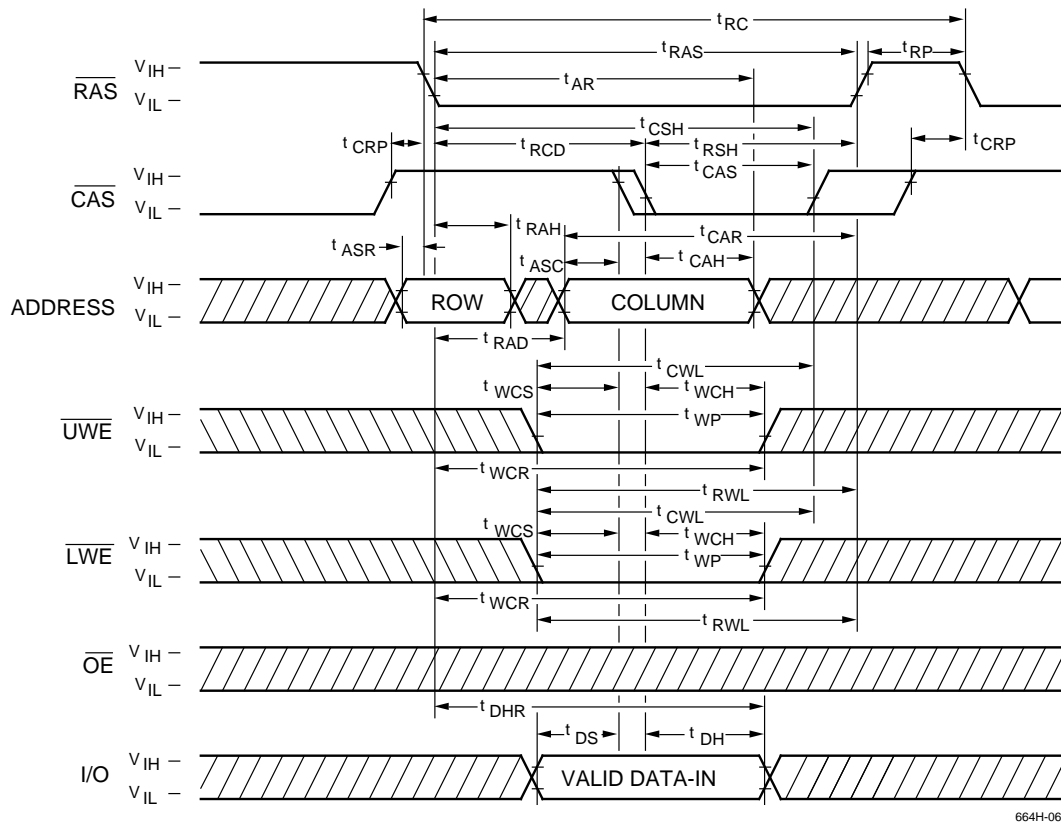
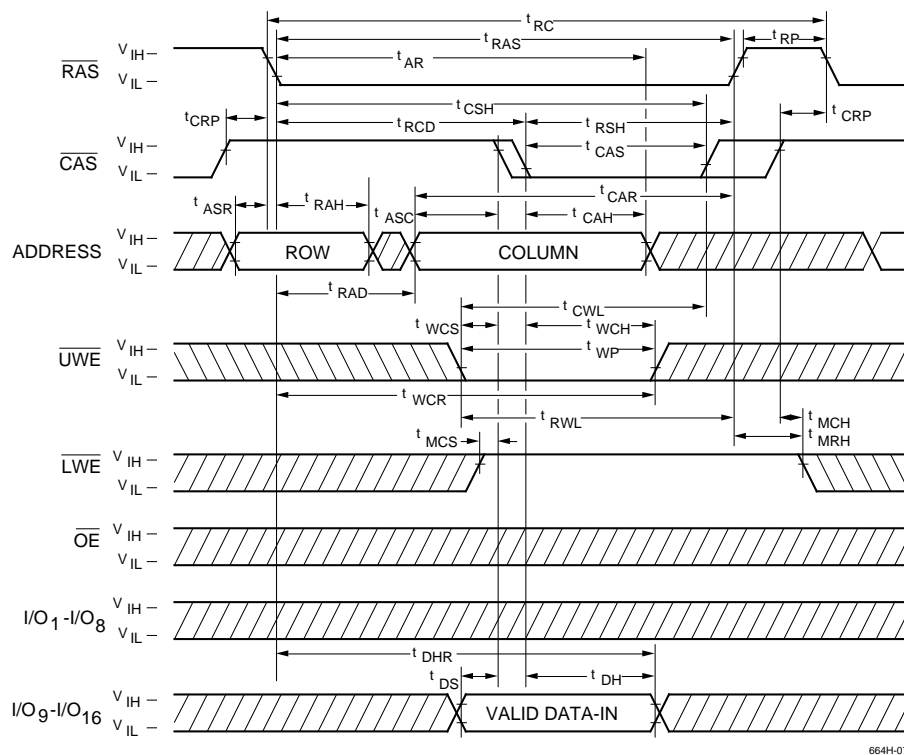
Notes:

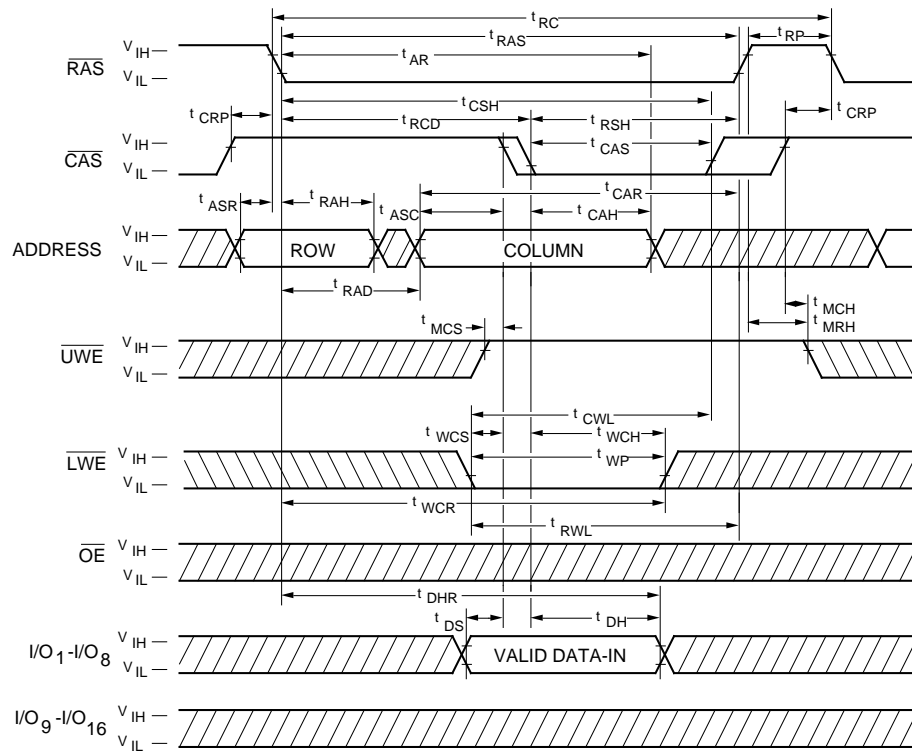
1. I_{CC} is dependent on output loading when the device output is selected. Specified I_{CC} (max.) is measured with the output open.
2. I_{CC} is dependent upon the number of address transitions. Specified I_{CC} (max.) is measured with a maximum of two transitions per address cycle in Fast Page Mode.
3. Specified V_{IL} (min.) is steady state operating. During transitions, V_{IL} (min.) may undershoot to -1.0 V for a period not to exceed 20 ns. All AC parameters are measured with V_{IL} (min.) $\geq V_{SS}$ and V_{IH} (max.) $\leq V_{CC}$.
4. t_{RCD} (max.) is specified for reference only. Operation within t_{RCD} (max.) limits insures that t_{RAC} (max.) and t_{CAA} (max.) can be met. If t_{RCD} is greater than the specified t_{RCD} (max.), the access time is controlled by t_{CAA} and t_{CAC} .
5. Either t_{RRH} or t_{RCH} must be satisfied for a Read Cycle to occur.
6. Measured with a load equivalent to one TTL input and 50 pF.
7. Access time is determined by the longest of t_{CAA} , t_{CAC} and t_{CAP} .
8. Assumes that $t_{RAD} \leq t_{RAD}$ (max.). If t_{RAD} is greater than t_{RAD} (max.), t_{RAC} will increase by the amount that t_{RAD} exceeds t_{RAD} (max.).
9. Assumes that $t_{RCD} \leq t_{RCD}$ (max.). If t_{RCD} is greater than t_{RCD} (max.), t_{RAC} will increase by the amount that t_{RCD} exceeds t_{RCD} (max.).
10. Assumes that $t_{RAD} \geq t_{RAD}$ (max.).
11. Operation within the t_{RAD} (max.) limit ensures that t_{RAC} (max.) can be met. t_{RAD} (max.) is specified as a reference point only. If t_{RAD} is greater than the specified t_{RAD} (max.) limit, the access time is controlled by t_{CAA} and t_{CAC} .
12. t_{WCS} , t_{RWD} , t_{AWD} and t_{CWD} are not restrictive operating parameters.
13. t_{WCS} (min.) must be satisfied in an Early Write Cycle.
14. t_{DS} and t_{DH} are referenced to the latter occurrence of \overline{CAS} or \overline{WE} .
15. t_T is measured between V_{IH} (min.) and V_{IL} (max.). AC-measurements assume $t_T = 3$ ns.
16. Assumes a three-state test load (5 pF and a 380 Ohm Thevenin equivalent).
17. An initial 200 μ s pause and 8 \overline{RAS} -containing cycles are required when exiting an extended period of bias without clocks. An extended period of time without clocks is defined as one that exceeds the specified Refresh Interval.

Truth Table

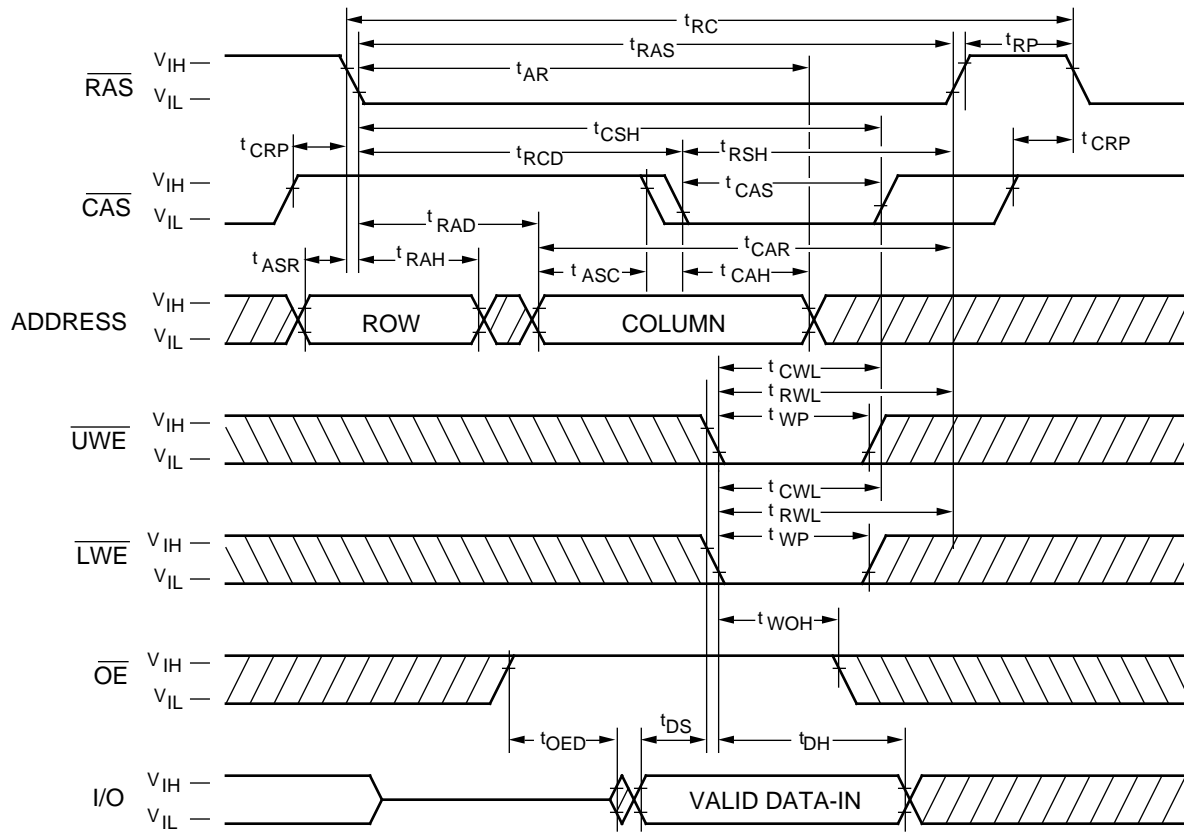
Function	$\overline{\text{RAS}}$	$\overline{\text{LW}}$	$\overline{\text{UW}}$	$\overline{\text{CAS}}$	$\overline{\text{OE}}$	ADDRESS	I/O	Notes
Read	L	H	H	L	L	ROW/COL	Data Out	
Early Write	L	L	L	L	X	ROW/COL	Data In	
Early Write: Upper Byte	L	H	L	L	X	ROW/COL	Lower Byte, High-Z Upper Byte, Data-In	
Early Write: Lower Byte	L	L	H	L	X	ROW/COL	Lower Byte, Data-In Upper Byte, High-Z	
Delayed Write	L	L	L	L	L	ROW/COL	Data-In	
Delayed Write: Upper Byte	L	H	L	L	L	ROW/COL	Lower Byte, High-Z Upper Byte, Data-In	
Delayed Write: Lower Byte	L	L	H	L	L	ROW/COL	Lower Byte, Data-In Upper Byte, High-Z	
Read-Modify Write	L	L	L	L	L	ROW/COL	Data In	
Upper Read-Modify-Write	L	H	L	L	L	ROW/COL	Lower Byte, High-Z Upper Byte, Data-In	
Lower Read-Modify-Write	L	L	H	L	L	ROW/COL	Lower Byte, Data-In Upper Byte, High-Z	
$\overline{\text{RAS}}$ -Only Refresh	L	X	X	H	X	ROW	High-Z	
Hidden Refresh	L	H	H	L	L	X	Data Out	
CBR Refresh (Extended)	L	X	X	L	X	X	High-Z	
Self Refresh	L	X	X	L	X	X	High-Z	
Standby	H	X	X	X	X	X	High-Z	

Waveforms of Read Cycle

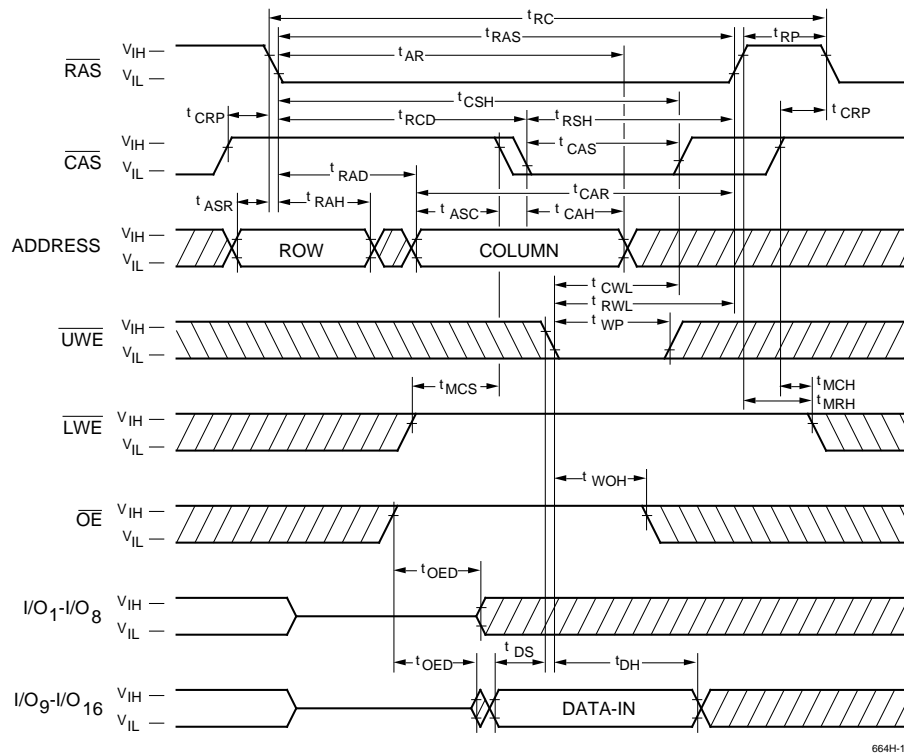
Waveforms of Write Cycle (Early Write)**Waveforms of Upper Byte Write Cycle (Early Write)**

Waveforms of Lower Byte Write Cycle (Early Write)

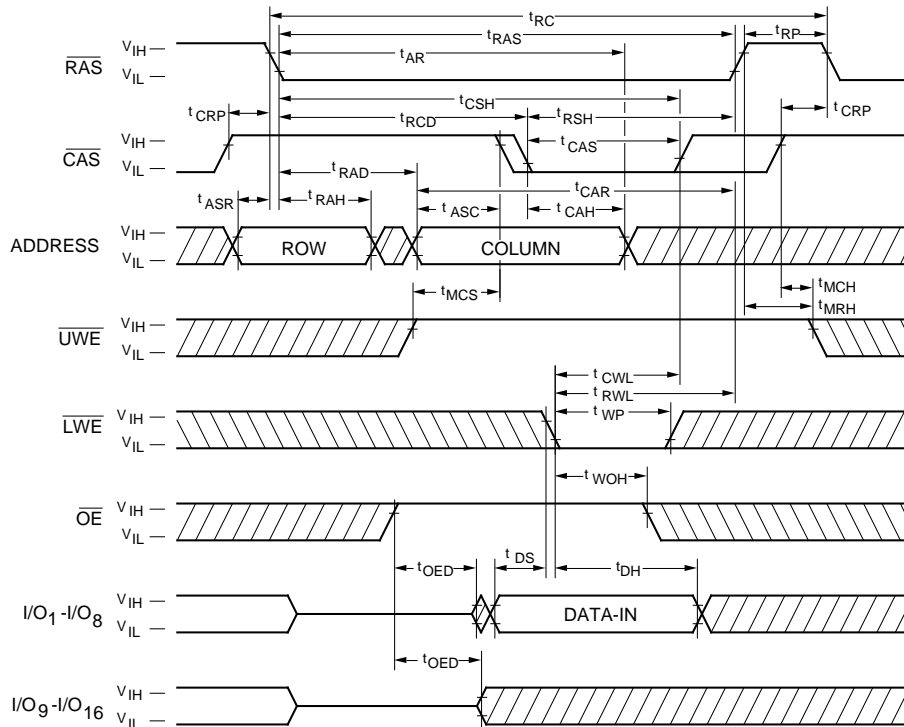
664H-08

Waveforms of Write Cycle (\overline{OE} -Controlled Write)

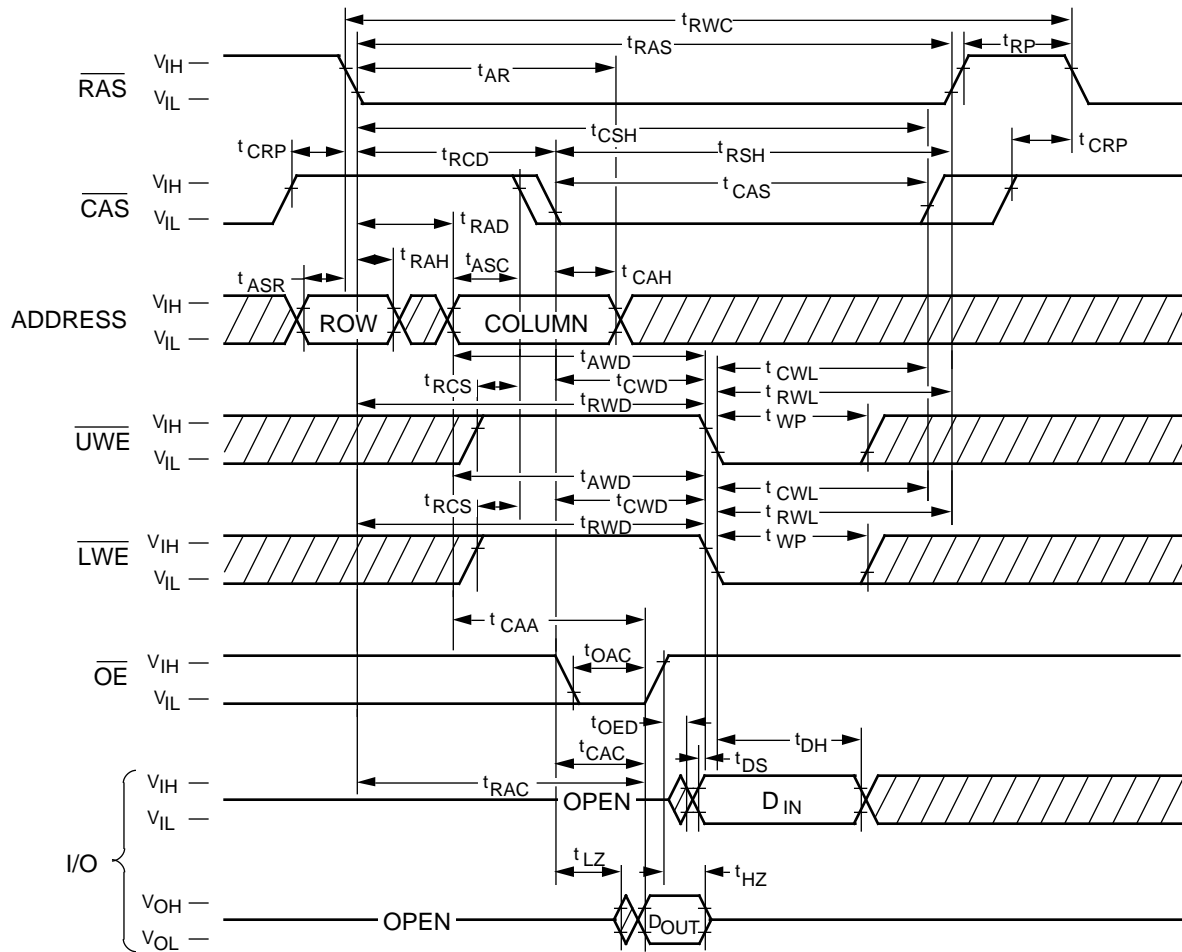
664H-09

Waveforms of Upper Byte Write Cycle ($\overline{\text{OE}}$ -Controlled Write)

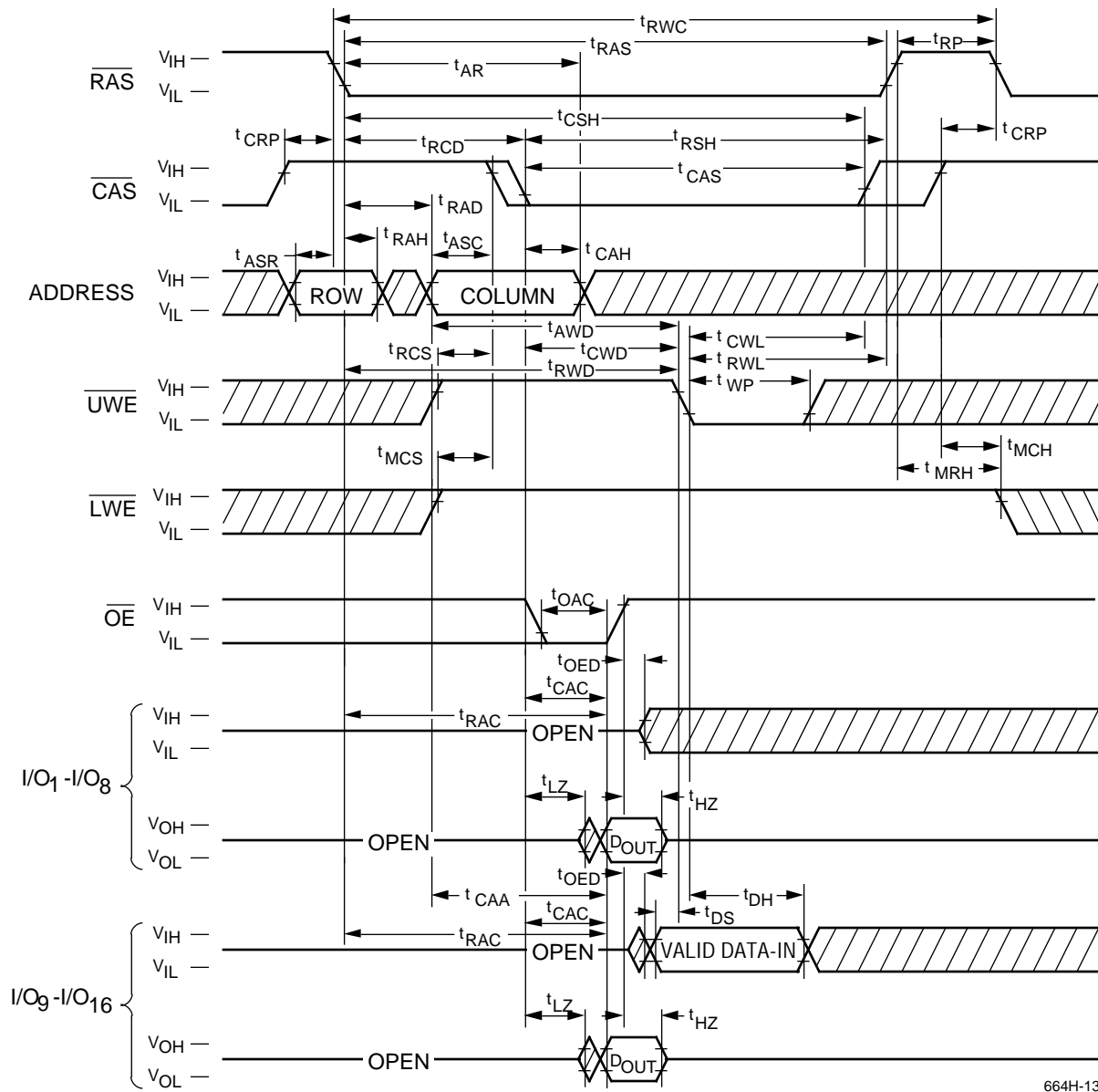
664H-10

Waveforms of Lower Byte Write Cycle ($\overline{\text{OE}}$ -Controlled Write)

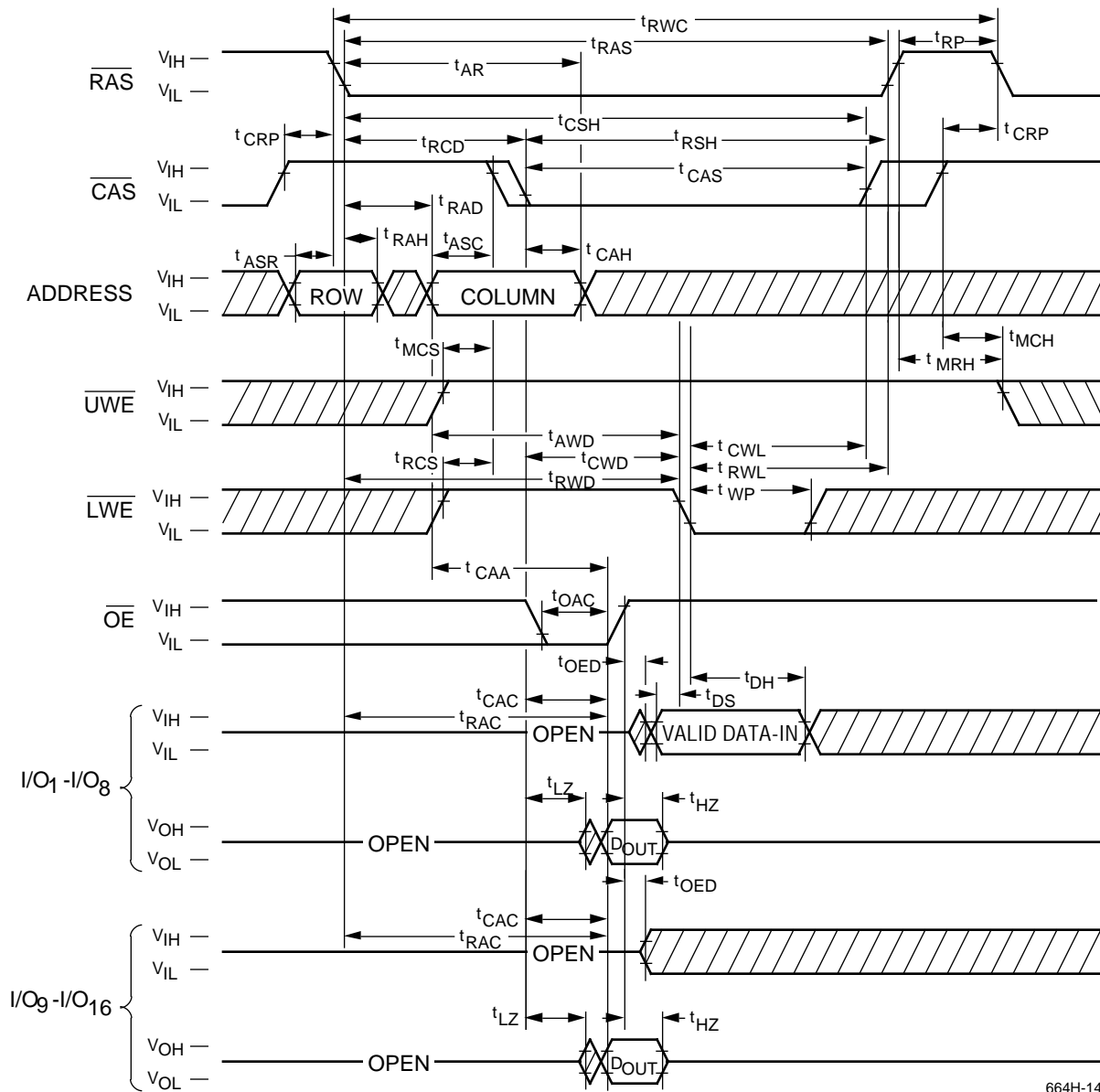
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Waveforms of Read-Modify-Write Cycle

664H-12

Waveforms of Read-Modify-Upper-Byte-Write Cycle

664H-13

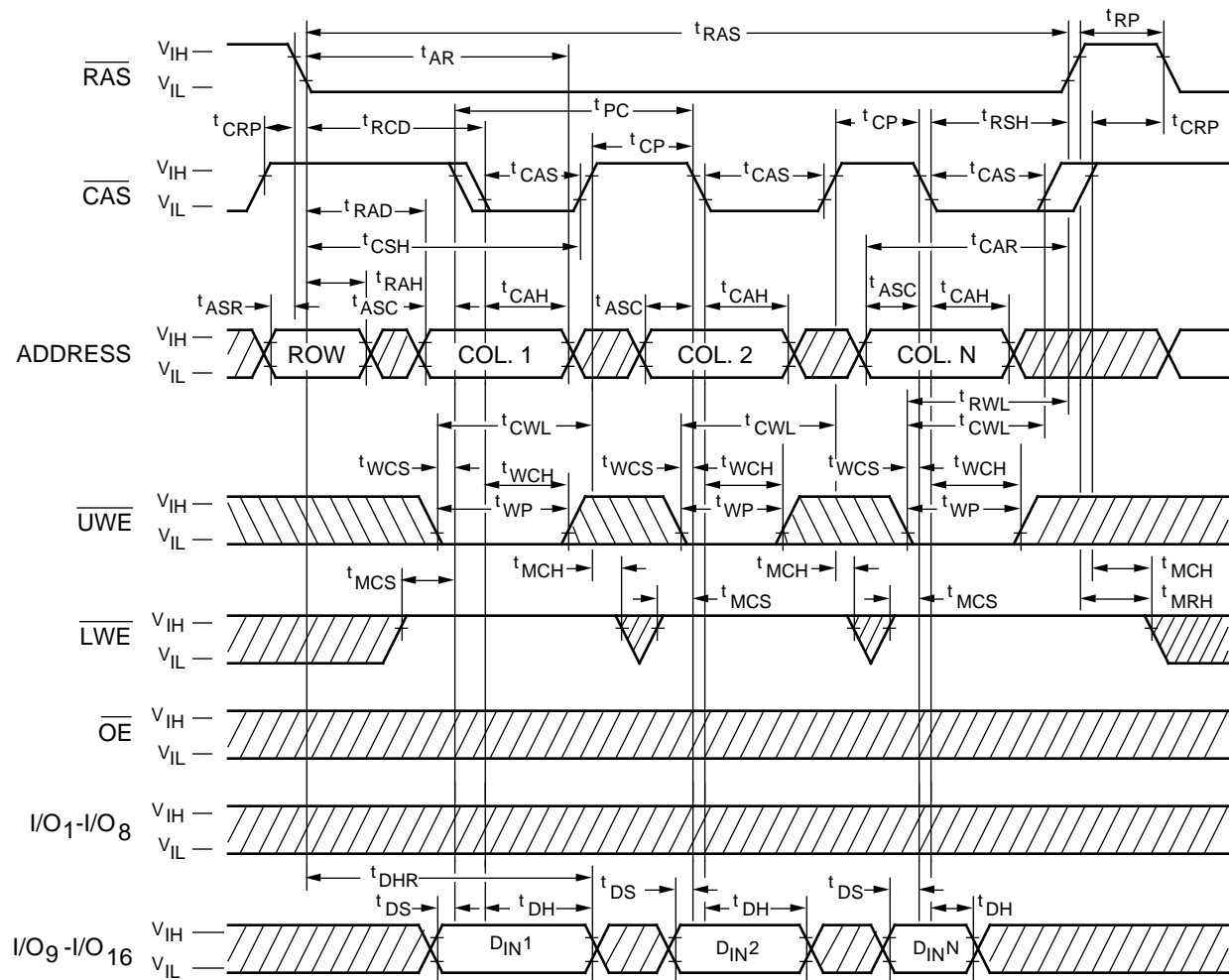
Waveforms of Read-Modify-Lower-Byte-Write Cycle

664H-14

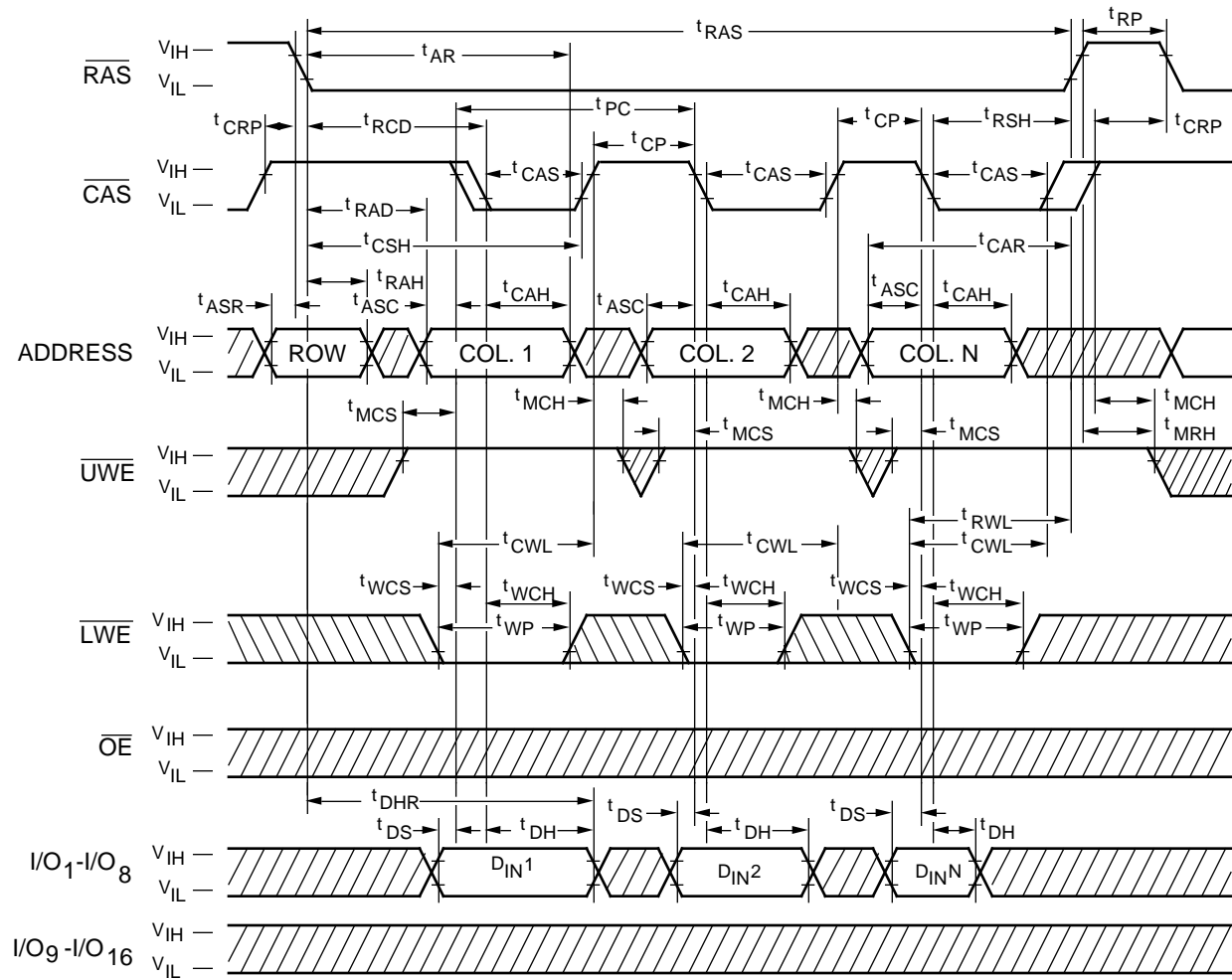
[illegible]

The timing diagram illustrates the relationship between several signals and their timing parameters:

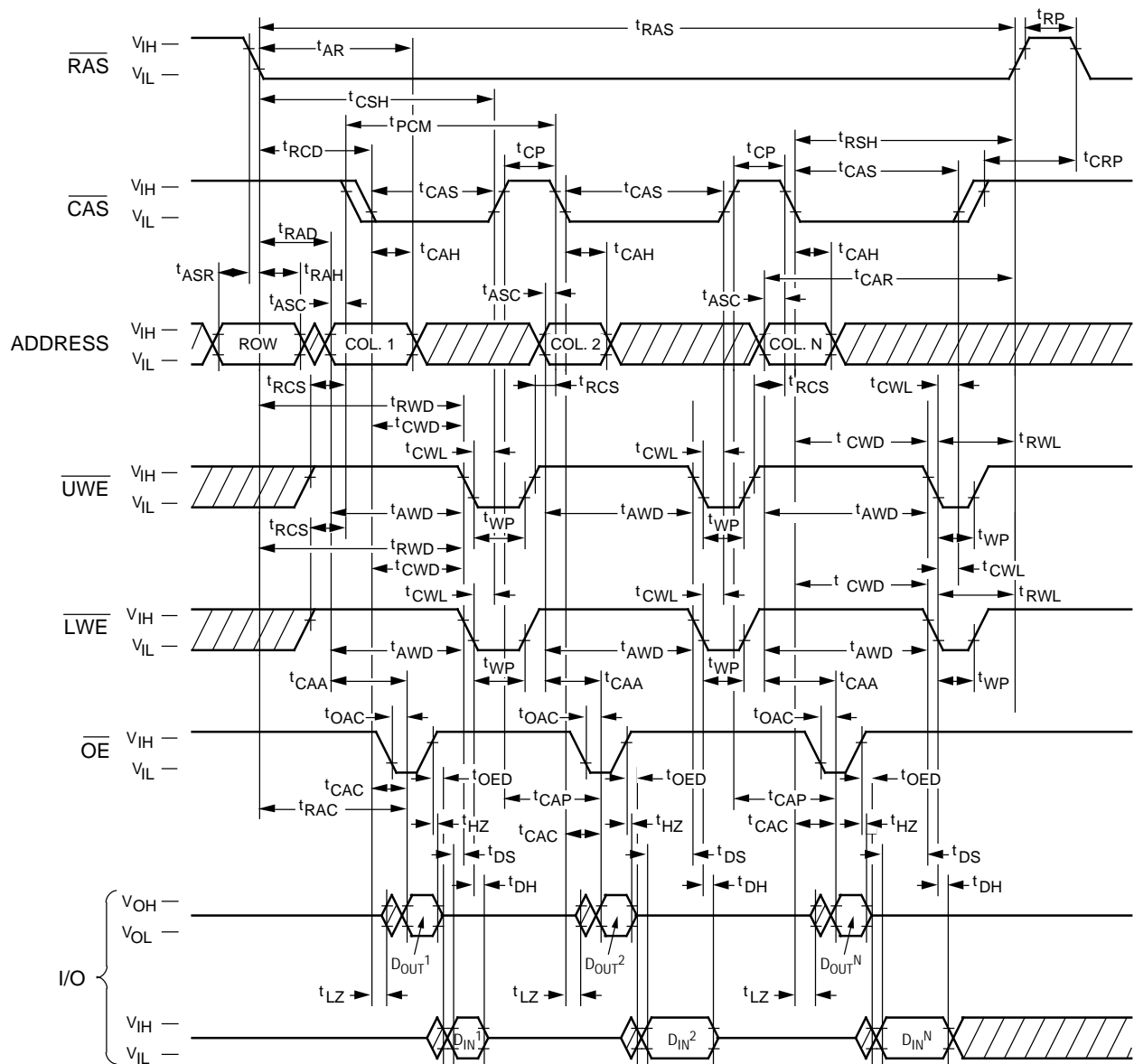
- RAS:** Shows the RAS enable signal with parameters t_{AR} (RAS access time), t_{RAS} (RAS pulse width), and t_{RP} (RAS recovery time).
- CAS:** Shows the CAS enable signal with parameters t_{CRP} (CAS precharge time), t_{RCD} (RAS to CAS delay), t_{PC} (RAS precharge time), t_{CP} (CAS precharge time), t_{RSH} (RAS to SH output delay), and t_{CRP} (CAS recovery time).
- ADDRESS:** Shows the address signal with parameters t_{ASR} (ADDRESS setup time), t_{ASC} (ADDRESS setup time), t_{CAH} (ADDRESS hold time), t_{ASC} (ADDRESS setup time), t_{CAH} (ADDRESS hold time), t_{ASC} (ADDRESS setup time), t_{CAH} (ADDRESS hold time), t_{CAR} (ADDRESS recovery time), t_{ASC} (ADDRESS setup time), and t_{CAH} (ADDRESS hold time).
- UWE:** Shows the UWE (User Write Enable) signal with parameters t_{CWL} (UWE pulse width), t_{WCS} (UWE to CAS delay), t_{WCH} (UWE to CAS delay), and t_{WP} (UWE pulse width).
- LWE:** Shows the LWE (Local Write Enable) signal with parameters t_{CWL} (LWE pulse width), t_{WCS} (LWE to CAS delay), t_{WCH} (LWE to CAS delay), and t_{WP} (LWE pulse width).
- OE:** Shows the OE (Output Enable) signal with parameters t_{DHR} (OE delay time), t_{DS} (OE delay time), t_{DH} (OE delay time), t_{DS} (OE delay time), t_{DH} (OE delay time), and t_{DS} (OE delay time).
- I/O:** Shows the I/O data signal with parameters t_{DS} (I/O delay time), t_{DH} (I/O delay time), t_{DS} (I/O delay time), t_{DH} (I/O delay time), t_{DS} (I/O delay time), and t_{DH} (I/O delay time).

Waveforms of Fast Page Mode Upper Byte Write Cycle

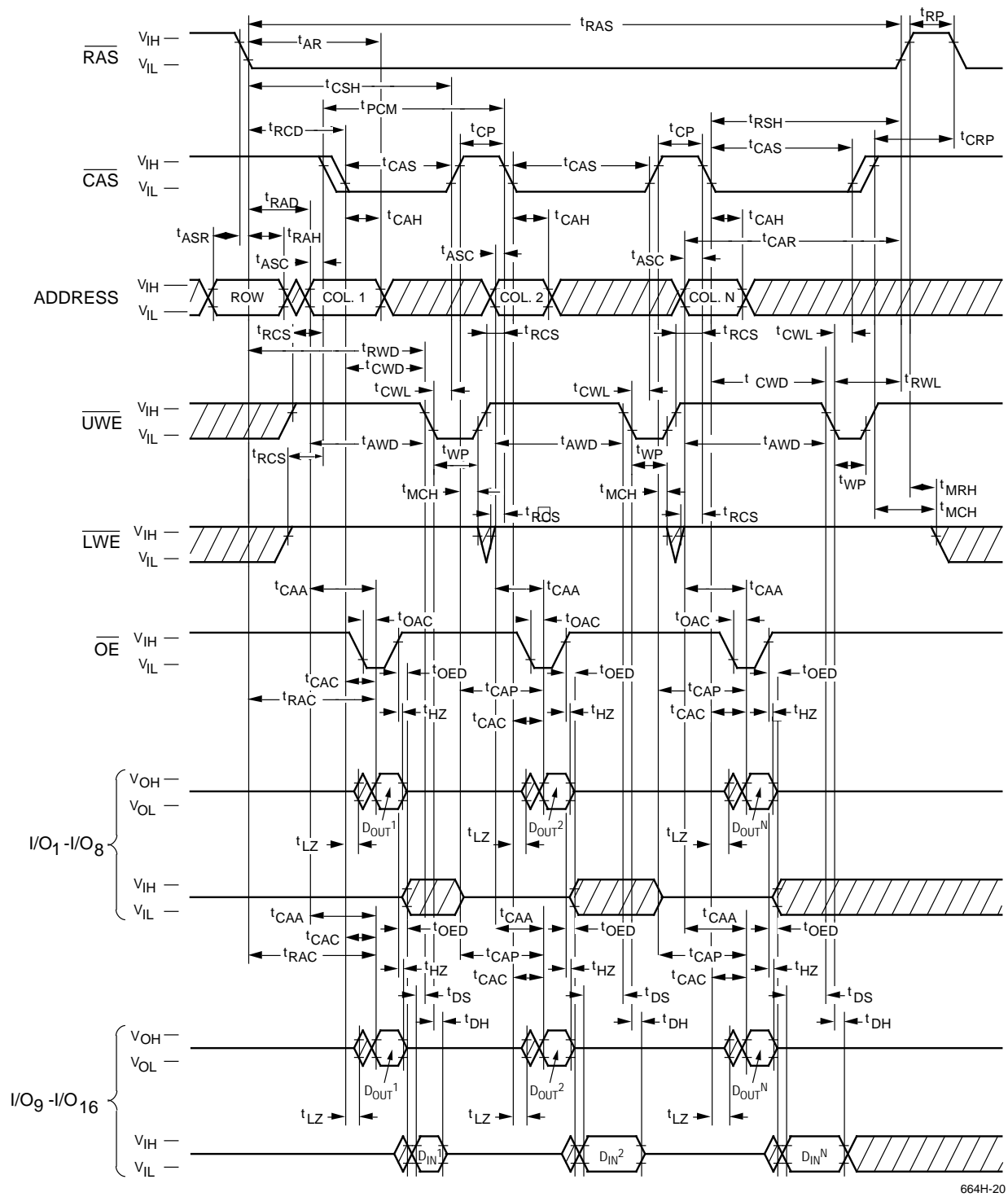
664H-17

Waveforms of Fast Page Mode Lower Byte Write Cycle

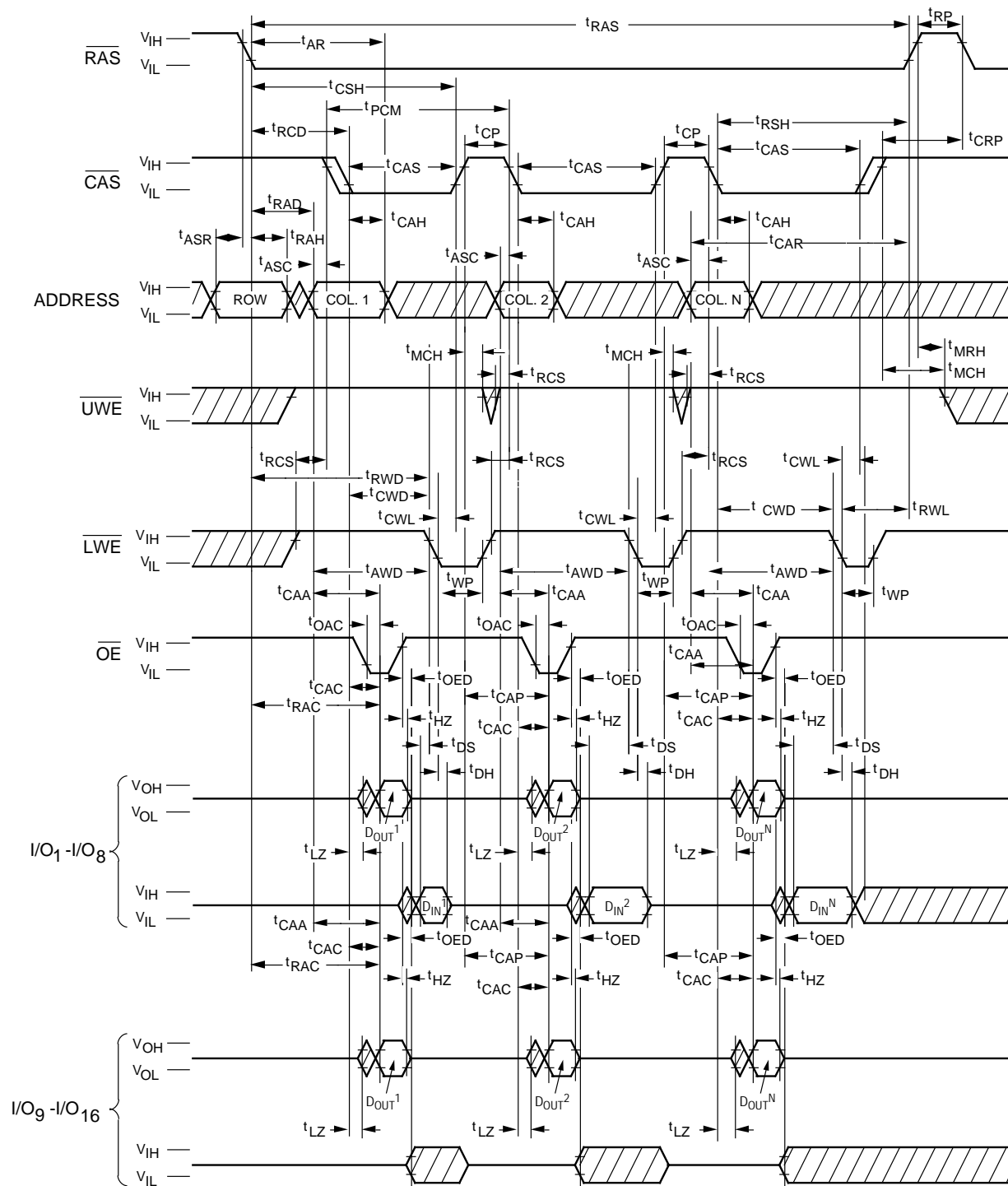
664H-18

Waveforms of Fast Page Read-Modify-Write Cycle

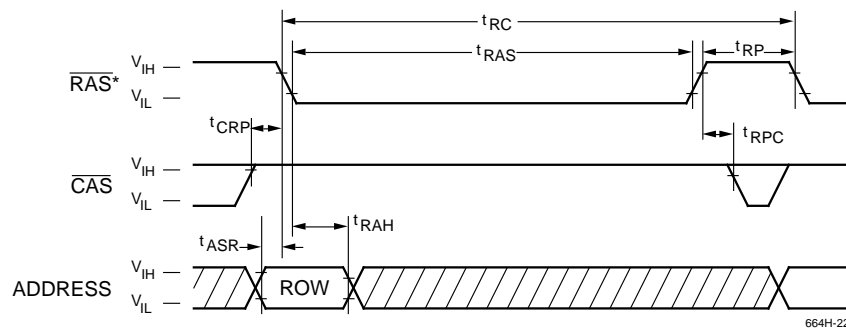
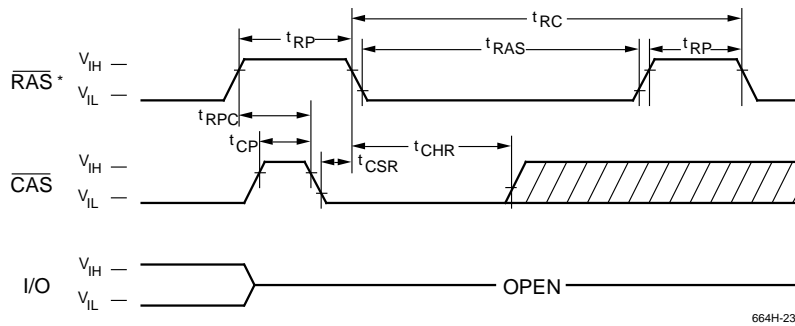
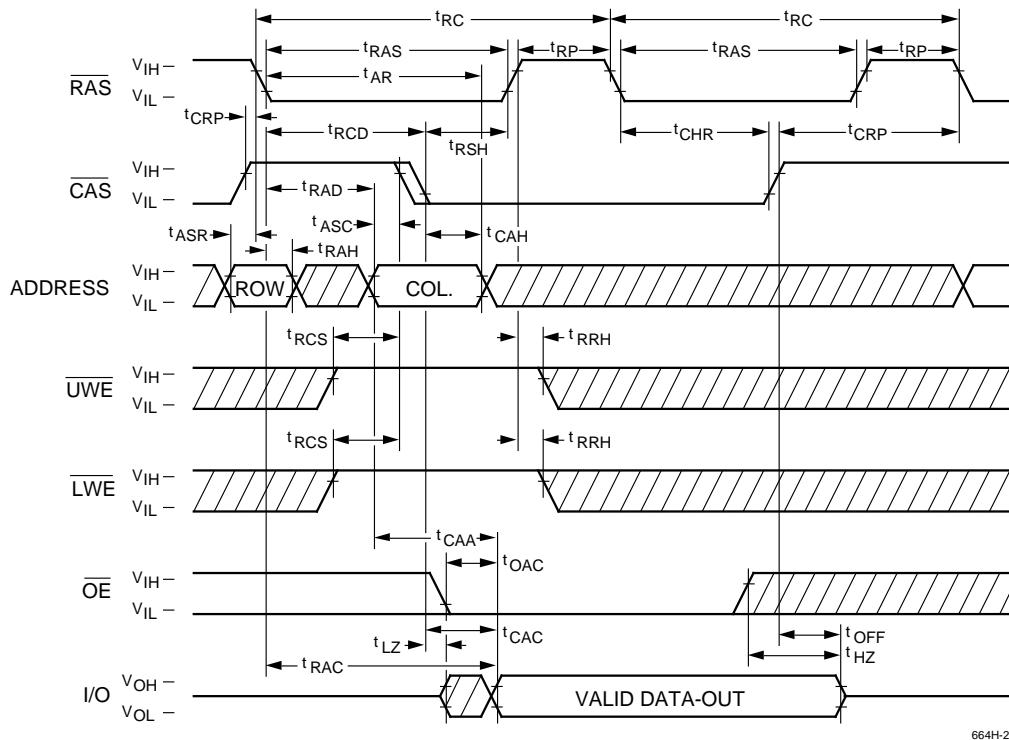
664H-19

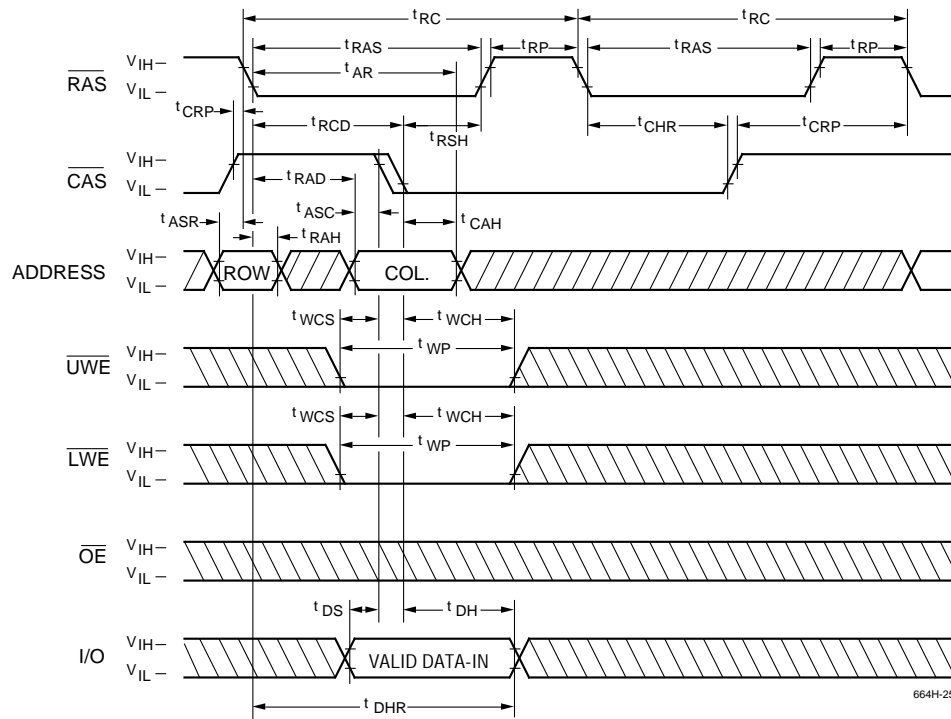
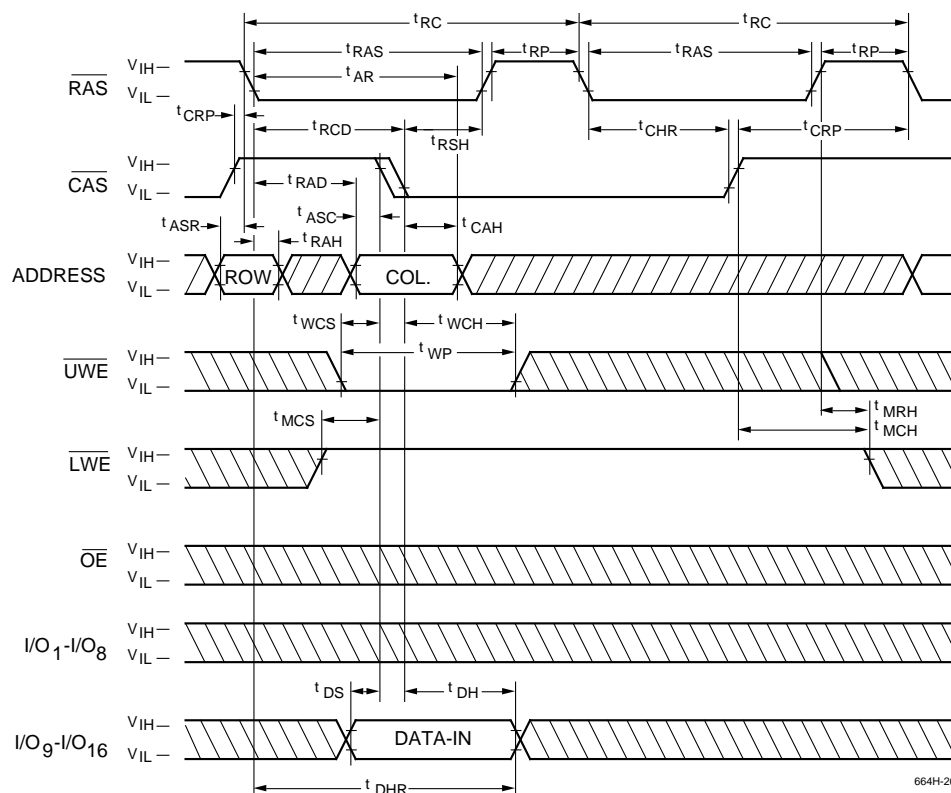
Waveforms of Fast Page Mode Read-Modify-Upper-Byte-Write Cycle

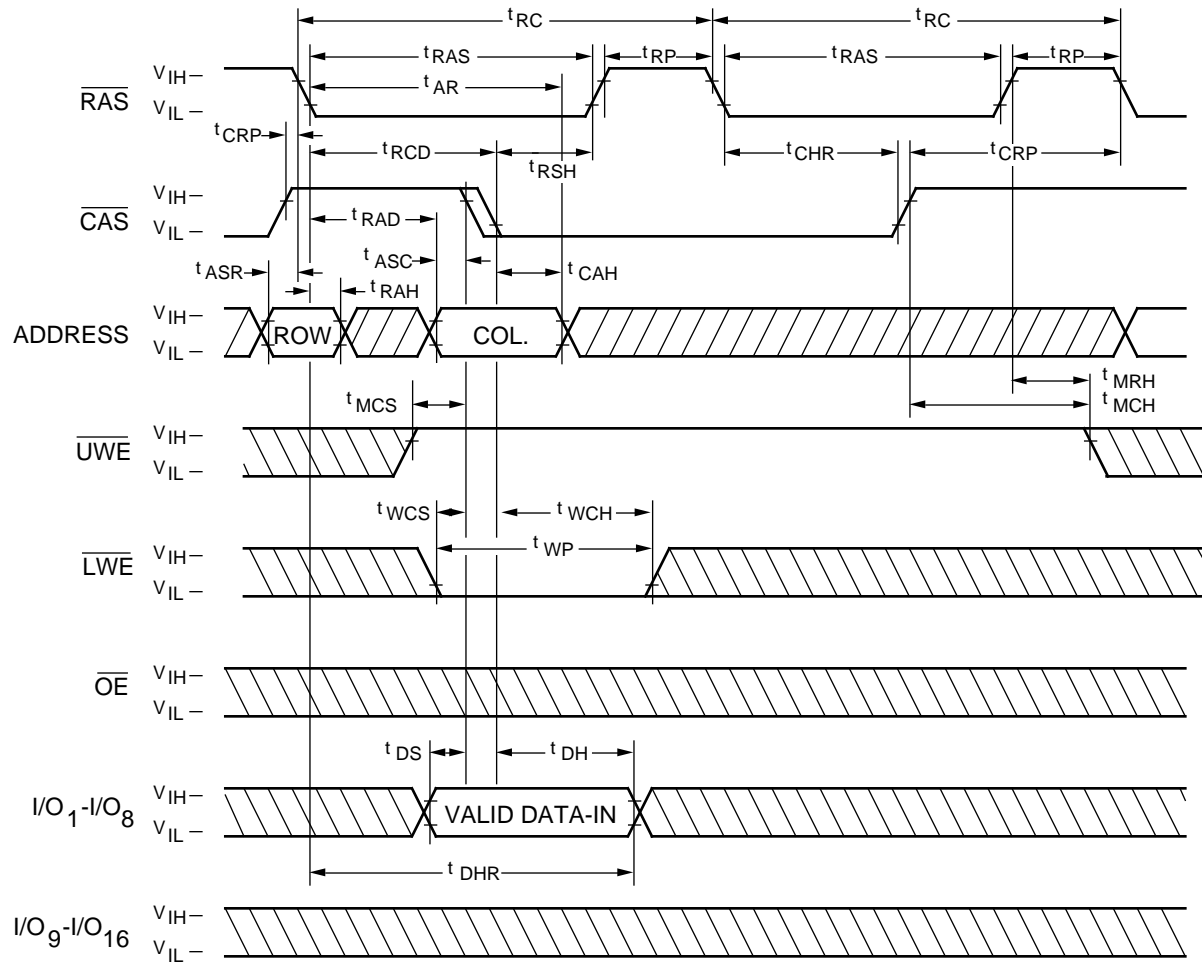
664H-20

Waveforms of Fast Page Mode Read-Modify-Lower-Byte-Write Cycle

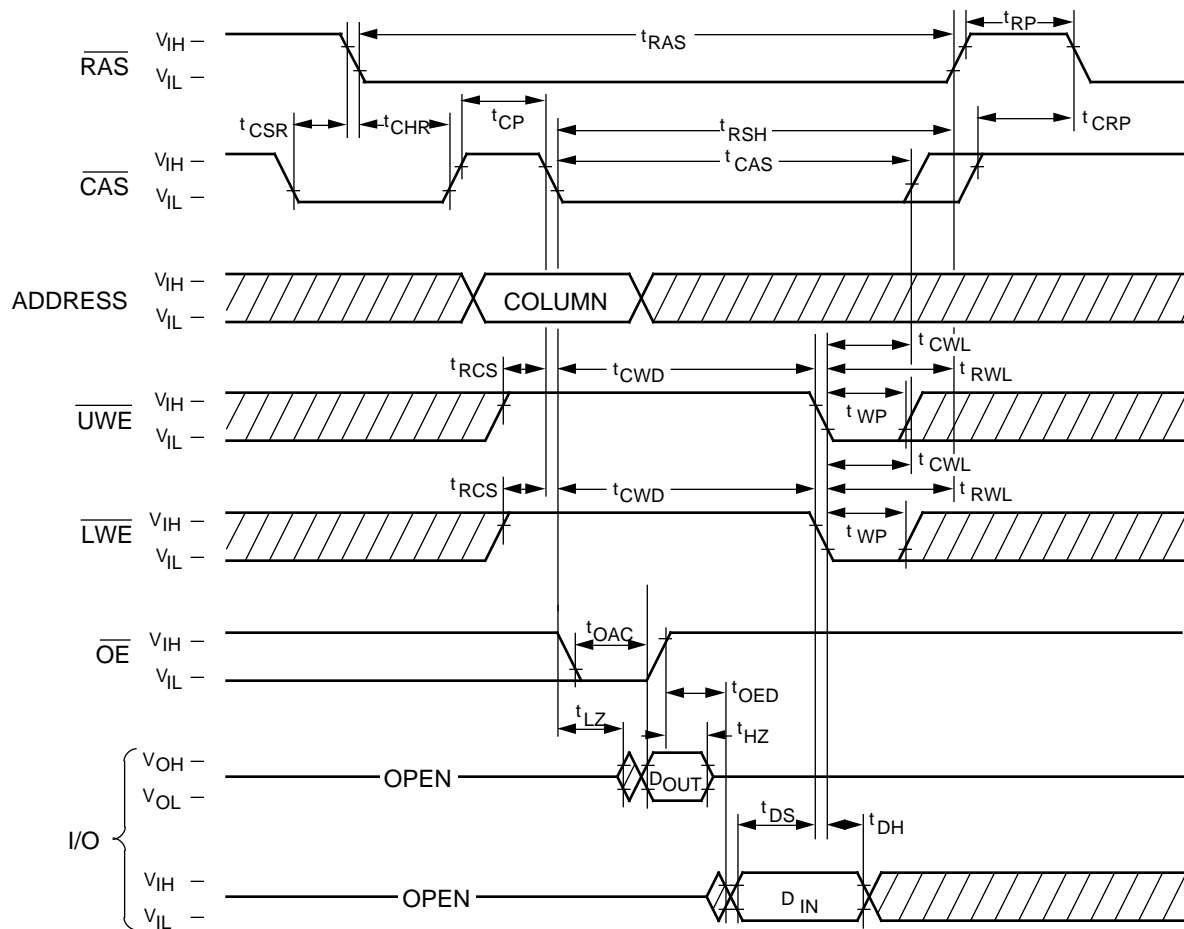
664H-21

Waveforms of $\overline{\text{RAS}}$ -Only Refresh Cycle**Waveforms of $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh Cycle****Waveforms of Hidden Refresh Cycle (Read)**

Waveforms of Hidden Refresh Cycle (Write)**Waveforms of Hidden Refresh Cycle (Upper Byte Write)**

Waveforms of Hidden Refresh Cycle (Lower Byte Write)

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Waveforms of $\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh Counter Test Read-Modify-Write Cycle

664H-28

Functional Description

The V53C664H is a CMOS dynamic RAM optimized for high data bandwidth, low power applications. It is functionally similar to a traditional dynamic RAM. The V53C664H reads and writes data by multiplexing an 16-bit address into a 8-bit row and an 8-bit column address. The row address is latched by the Row Address Strobe (\overline{RAS}). The column address “flows through” an internal address buffer and is latched by the Column Address Strobe (\overline{CAS}). Because access time is primarily dependent on a valid column address rather than the precise time that the \overline{CAS} edge occurs, the delay time from \overline{RAS} to \overline{CAS} has little effect on the access time.

Memory Cycle

A memory cycle is initiated by bringing \overline{RAS} low. Any memory cycle, once initiated, must not be ended or aborted before the minimum t_{RAS} time has expired. This ensures proper device operation and data integrity. A new cycle must not be initiated until the minimum precharge time t_{RP}/t_{CP} has elapsed.

Read Cycle

A Read cycle is performed by holding the Write Enable (\overline{WE}) signal High during a $\overline{RAS}/\overline{CAS}$ operation. The column address must be held for a minimum specified by t_{AR} . Data Out becomes valid only when t_{OAC} , t_{RAC} , t_{CAA} and t_{CAC} are all satisfied. As a result, the access time is dependent on the timing relationships between these parameters. For example, the access time is limited by t_{CAA} when t_{RAC} , t_{CAC} and t_{OAC} are all satisfied.

Write Cycle

A Write Cycle is performed by taking \overline{WE} and \overline{CAS} low during a \overline{RAS} operation. The column address is latched by \overline{CAS} . The Write Cycle can be \overline{WE} controlled or \overline{CAS} controlled depending on whether \overline{WE} or \overline{CAS} falls later. Consequently, the input data must be valid at or before the falling edge of \overline{WE} or \overline{CAS} , whichever occurs last. In the \overline{CAS} -controlled Write Cycle, when the leading edge of \overline{WE} occurs prior to the \overline{CAS} low transition, the I/O data pins will be in the High-Z state at the beginning of the Write function. Ending the Write with \overline{RAS} or \overline{CAS} will maintain the output in the High-Z state.

In the \overline{WE} controlled Write Cycle, \overline{OE} must be in the high state and t_{OED} must be satisfied.

Refresh Cycle

To retain data, 256 Refresh Cycles are required in each 4 ms period. There are two ways to refresh the memory:

1. By clocking each of the 256 row addresses (A_0 through A_7) with \overline{RAS} at least once every 4 ms. Any Read, Write, Read-Modify-Write or \overline{RAS} -only cycle refreshes the addressed row.
2. Using a \overline{CAS} -before- \overline{RAS} Refresh Cycle. If \overline{CAS} makes a transition from low to high to low after the previous cycle and before \overline{RAS} falls, \overline{CAS} -before- \overline{RAS} refresh is activated. The V53C664H uses the output of an internal 9-bit counter as the source of row addresses and ignore external address inputs.

\overline{CAS} -before- \overline{RAS} is a “refresh-only” mode and no data access or device selection is allowed. Thus, the output remains in the High-Z state during the cycle. A \overline{CAS} -before- \overline{RAS} counter test mode is provided to ensure reliable operation of the internal refresh counter.

Fast Page Mode Operation

Fast Page Mode operation permits all 256 columns within a selected row of the device to be randomly accessed at a high data rate. Maintaining \overline{RAS} low while performing successive \overline{CAS} cycles retains the row address internally and eliminates the need to reapply it for each cycle. The column address buffer acts as a transparent or flow-through latch while \overline{CAS} is high. Thus, access begins from the occurrence of a valid column address rather than from the falling edge of \overline{CAS} , eliminating t_{ASC} and t_T from the critical timing path. \overline{CAS} latches the address into the column address buffer and acts as an output enable. During Fast Page Mode operation, Read, Write, Read-Modify-Write or Read-Write-Read cycles are possible at random addresses within a row. Following the initial entry cycle into Fast Page Mode, access is t_{CAA} or t_{CAP} controlled. If the column address is valid prior to the rising edge of \overline{CAS} , the access time is referenced to the \overline{CAS} rising edge and is specified by t_{CAP} . If the column address is valid after the rising \overline{CAS} edge, access is timed from the occurrence of a valid address and is specified by t_{CAA} . In both cases, the falling edge of \overline{CAS} latches the address and enables the output.

Fast Page Mode provides a sustained data rate of 53 MHz for applications that require high data rates such as bit-mapped graphics or high-speed

signal processing. The following equation can be used to calculate the maximum data rate:

$$\text{Data Rate} = \frac{256}{t_{RC} + 255 \times t_{PC}}$$

Data Output Operation

The V53C664H Input/Output is controlled by \overline{OE} , \overline{CAS} , \overline{WE} and \overline{RAS} . A \overline{RAS} low transition enables the transfer of data to and from the selected row address in the Memory Array. A \overline{RAS} high transition disables data transfer and latches the output data if the output is enabled. After a memory cycle is initiated with a \overline{RAS} low transition, a \overline{CAS} low transition or \overline{CAS} low level enables the internal I/O path. A \overline{CAS} high transition or a \overline{CAS} high level disables the I/O path and the output driver if it is enabled. A \overline{CAS} low transition while \overline{RAS} is high has no effect on the I/O data path or on the output drivers. The output drivers, when otherwise enabled, can be disabled by holding \overline{OE} high. The \overline{OE} signal has no effect on any data stored in the output latches. A \overline{WE} low level can also disable the output drivers when \overline{CAS} is low. During a Write cycle, if \overline{WE} goes low at a time in relationship to \overline{CAS} that would normally cause the outputs to be active, it is necessary to use \overline{OE} to disable the output drivers prior to the \overline{WE} low transition to allow Data In Setup Time (t_{DS}) to be satisfied.

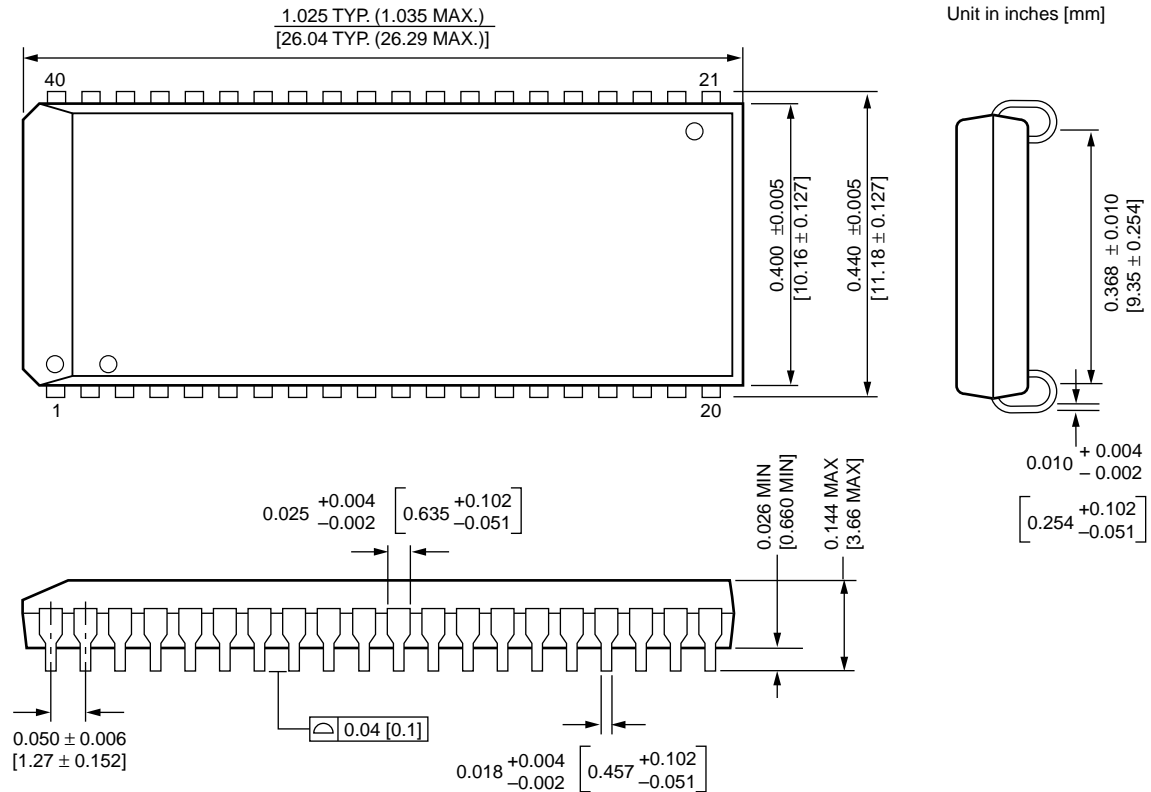
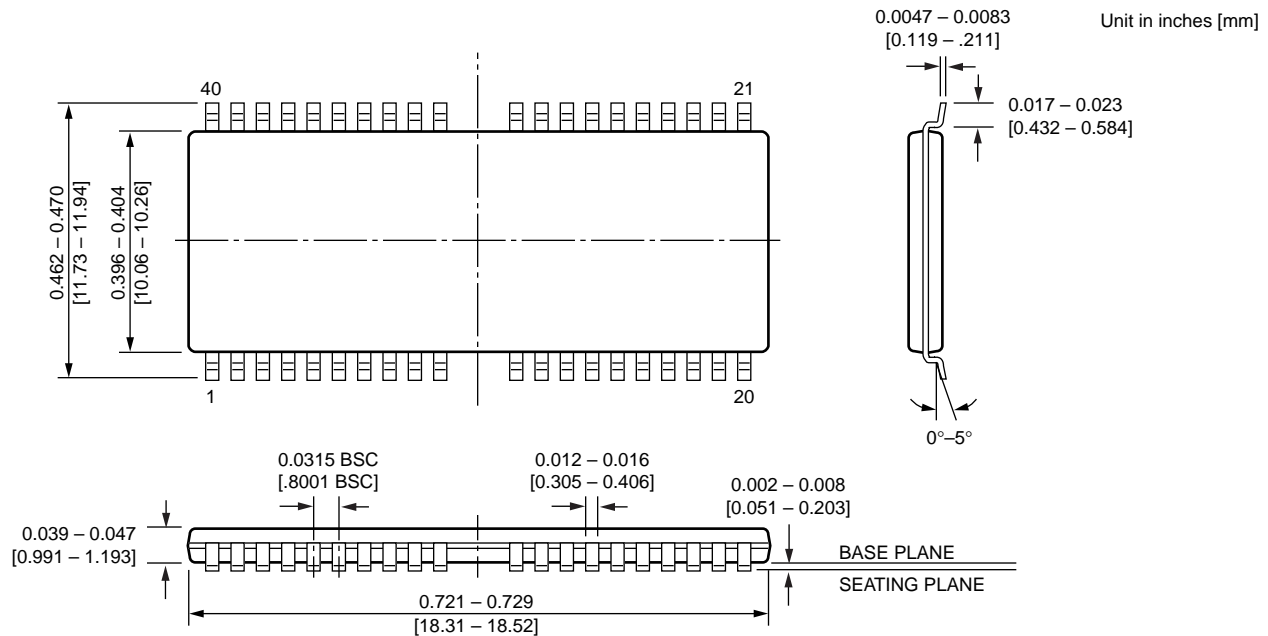
Power-On

After application of the V_{CC} supply, an initial pause of 200 μs is required followed by a minimum of 8 initialization cycles (any combination of cycles containing a \overline{RAS} clock). Eight initialization cycles are required after extended periods of bias without clocks (greater than the Refresh Interval).

During Power-On, the V_{CC} current requirement of the V53C664H is dependent on the input levels of \overline{RAS} and \overline{CAS} . If \overline{RAS} is low during Power-On, the device will go into an active cycle and I_{CC} will exhibit current transients. It is recommended that \overline{RAS} and \overline{CAS} track with V_{CC} or be held at a valid V_{IH} during Power-On to avoid current surges.

Table 1. V53C664H Data Output Operation for Various Cycle Types

Cycle Type	I/O State
Read Cycles	Data from Addressed Memory Cell
\overline{CAS} -Controlled Write Cycle (Early Write)	High-Z
\overline{WE} -Controlled Write Cycle (Late Write)	\overline{OE} Controlled. High \overline{OE} = High-Z I/Os
Read-Modify-Write Cycles	Data from Addressed Memory Cell
Fast Page Mode Read	Data from Addressed Memory Cell
Fast Page Mode Write Cycle (Early Write)	High-Z
Fast Page Mode Read-Modify-Write Cycle	Data from Addressed Memory Cell
\overline{RAS} -only Refresh	High-Z
\overline{CAS} -before- \overline{RAS} Refresh Cycle	Data remains as in previous cycle
\overline{CAS} -only Cycles	High-Z

Package Diagrams**40-Pin SOJ****40/44L-Pin TSOP-II**

Notes

Notes

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