

LMC6041

CMOS Single Micropower Operational Amplifier

General Description

Ultra-low power consumption and low input-leakage current are the hallmarks of the LMC6041. Providing input currents of only 2 fA typical, the LMC6041 can operate from a single supply, has output swing extending to each supply rail, and an input voltage range that includes ground.

The LMC6041 is ideal for use in systems requiring ultra-low power consumption. In addition, the insensitivity to latch-up, high output drive, and output swing to ground without requiring external pull-down resistors make it ideal for single-supply battery-powered systems.

Other applications for the LMC6041 include bar code reader amplifiers, magnetic and electric field detectors, and hand-held electrometers.

This device is built with National's advanced Double-Poly Silicon-Gate CMOS process.

See the LMC6042 for a dual, and the LMC6044 for a quad amplifier with these features.

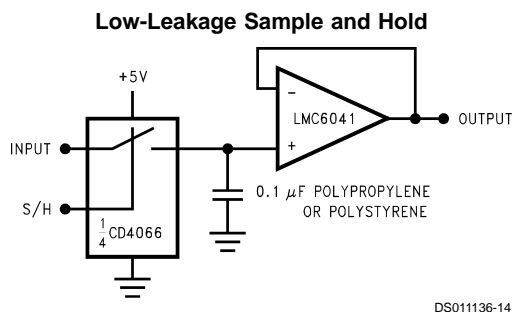
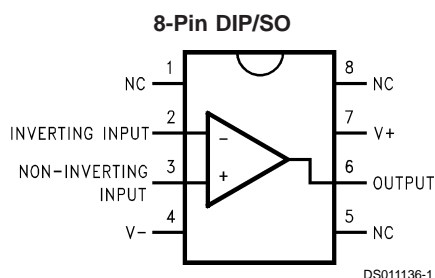
Features

- Low supply current: 14 μ A (Typ)
- Operates from 4.5V to 15.5V single supply
- Ultra low input current: 2 fA (Typ)
- Rail-to-rail output swing
- Input common-mode range includes ground

Applications

- Battery monitoring and power conditioning
- Photodiode and infrared detector preamplifier
- Silicon based transducer systems
- Hand-held analytic instruments
- pH probe buffer amplifier
- Fire and smoke detection systems
- Charge amplifier for piezoelectric transducers

Connection Diagram



Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

| | |
|--|-----------------|
| Differential Input Voltage | ±Supply Voltage |
| Supply Voltage ($V^+ - V^-$) | 16V |
| Output Short Circuit to V^- | (Note 2) |
| Output Short Circuit to V^+ | (Note 11) |
| Lead Temperature (Soldering, 10 sec.) | 260°C |
| Storage Temperature Range | -65°C to +150°C |
| Junction Temperature | 110°C |
| ESD Tolerance (Note 4) | 500V |
| Current at Input Pin | ±5 mA |

| | |
|-----------------------------|------------------------------------|
| Current at Output Pin | ±18 mA |
| Current at Power Supply Pin | 35 mA |
| Voltage at Input/Output Pin | (V^+) + 0.3V, (V^-) - 0.3V |
| Power Dissipation | (Note 3) |

Operating Ratings

| | | |
|--|---------------------|-----------------------|
| Temperature Range | LMC6041AI, LMC6041I | -40°C ≤ T_J ≤ +85°C |
| Supply Voltage | | 4.5V ≤ V^+ ≤ 15.5V |
| Power Dissipation | | (Note 9) |
| Thermal Resistance (θ_{JA}) (Note 10) | | |
| 8-Pin DIP | | 101°C/W |
| 8-Pin SO | | 165°C/W |

Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_A = T_J = 25^\circ\text{C}$. **Boldface** limits apply at the temperature extremes. $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = 1.5\text{V}$, $V_O = V^+/2$, and $R_L > 1\text{M}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Typical (Note 5) | LMC6041AI | LMC6041I | Units (Limit) |
|------------|--|---|---------------------|--|--|------------------------------|
| | | | | Limit (Note 6) | Limit (Note 6) | |
| V_{OS} | Input Offset Voltage | | 1 | 3 3.3 | 6 6.3 | mV max |
| TCV_{OS} | Input Offset Voltage Average Drift | | 1.3 | | | $\mu\text{V}/^\circ\text{C}$ |
| I_B | Input Bias Current | | 0.002 | 4 | 4 | pA max |
| I_{OS} | Input Offset Current | | 0.001 | 2 | 2 | pA max |
| R_{IN} | Input Resistance | | >10 | | | Tera Ω |
| CMRR | Common Mode Rejection Ratio | $0\text{V} \leq V_{CM} \leq 12.0\text{V}$ $V^+ = 15\text{V}$ | 75 | 68 66 | 62 60 | dB min |
| +PSRR | Positive Power Supply Rejection Ratio | $5\text{V} \leq V^+ \leq 15\text{V}$ $V_O = 2.5\text{V}$ | 75 | 68 66 | 62 60 | dB min |
| -PSRR | Negative Power Supply Rejection Ratio | $0\text{V} \leq V^- \leq -10\text{V}$ $V_O = 2.5\text{V}$ | 94 | 84 83 | 74 73 | dB min |
| CMR | Input Common-Mode Voltage Range | $V^+ = 5\text{V}$ and 15V for CMRR ≥ 50 dB | -0.4 | -0.1 0 | -0.1 0 | V max |
| | | | $V^+ - 1.9\text{V}$ | $V^+ - 2.3\text{V}$ $V^+ - 2.5\text{V}$ | $V^+ - 2.3\text{V}$ $V^+ - 2.4\text{V}$ | V min |
| A_V | Large Signal Voltage Gain | $R_L = 100\text{ k}\Omega$ (Note 7) | Sourcing | 1000 300 | 300 200 | V/mV min |
| | | | Sinking | 500 120 | 90 70 | V/mV min |
| | | $R_L = 25\text{ k}\Omega$ (Note 7) | Sourcing | 1000 160 | 100 80 | V/mV min |
| | | | Sinking | 250 60 | 50 40 | V/mV min |

Electrical Characteristics (Continued)

Unless otherwise specified, all limits guaranteed for $T_A = T_J = 25^\circ\text{C}$. **Boldface** limits apply at the temperature extremes. $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = 1.5\text{V}$, $V_O = V^+/2$, and $R_L > 1\text{M}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Typical (Note 5) | LMC6041AI | LMC6041I | Units (Limit) |
|----------|--------------------------------------|---|---------------------|-------------------------|-------------------------|----------------------|
| | | | | Limit (Note 6) | Limit (Note 6) | |
| V_O | Output Swing | $V^+ = 5\text{V}$ $R_L = 100\text{ k}\Omega$ to $V^+/2$ | 4.987 | 4.970 4.950 | 4.940 4.910 | V min |
| | | | 0.004 | 0.030 0.050 | 0.060 0.090 | V max |
| | | $V^+ = 5\text{V}$ $R_L = 25\text{ k}\Omega$ to $V^+/2$ | 4.980 | 4.920 4.870 | 4.870 4.820 | V min |
| | | | 0.010 | 0.080 0.130 | 0.130 0.180 | V max |
| | | $V^+ = 15\text{V}$ $R_L = 100\text{ k}\Omega$ to $V^+/2$ | 14.970 | 14.920 14.880 | 14.880 14.820 | V min |
| | | | 0.007 | 0.030 0.050 | 0.060 0.090 | V max |
| | | $V^+ = 15\text{V}$ $R_L = 25\text{ k}\Omega$ to $V^+/2$ | 14.950 | 14.900 14.850 | 14.850 14.800 | V min |
| | | | 0.022 | 0.100 0.150 | 0.150 0.200 | V max |
| I_{SC} | Output Current $V^+ = 5\text{V}$ | Sourcing, $V_O = 0\text{V}$ | 22 | 16 10 | 13 8 | mA min |
| | | Sinking, $V_O = 5\text{V}$ | 21 | 16 8 | 13 8 | mA min |
| I_{SC} | Output Current $V^+ = 15\text{V}$ | Sourcing, $V_O = 0\text{V}$ | 40 | 15 10 | 15 10 | mA min |
| | | Sinking, $V_O = 13\text{V}$ (Note 11) | 39 | 24 8 | 21 8 | mA min |
| I_S | Supply Current | $V_O = 1.5\text{V}$ | 14 | 20 24 | 26 30 | μA max |
| | | $V^+ = 15\text{V}$ | 18 | 26 31 | 34 39 | μA max |

AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for $T_A = T_J = 25^\circ\text{C}$. **Boldface** limits apply at the temperature extremes. $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{CM} = 1.5\text{V}$, $V_O = V^+/2$, and $R_L > 1\text{M}$ unless otherwise specified.

| Symbol | Parameter | Conditions | Typ (Note 5) | LMC6041AI | LMC6041I | Units (Limit) |
|----------|---------------------------------|---|-----------------|-----------------------|-----------------------|-------------------------|
| | | | | Limit (Note 6) | Limit (Note 6) | |
| SR | Slew Rate | (Note 8) | 0.02 | 0.015 0.010 | 0.010 0.007 | V/ μs min |
| GBW | Gain-Bandwidth Product | | 75 | | | kHz |
| ϕ_m | Phase Margin | | 60 | | | Deg |
| e_n | Input-Referred Voltage Noise | $F = 1\text{ kHz}$ | 83 | | | nV/ $\sqrt{\text{Hz}}$ |
| i_n | Input-Referred Current Noise | $F = 1\text{ kHz}$ | 0.0002 | | | pA/ $\sqrt{\text{Hz}}$ |
| T.H.D. | Total Harmonic Distortion | $F = 1\text{ kHz}$, $A_V = -5$ $R_L = 100\text{ k}\Omega$, $V_O = 2\text{ V}_{pp}$ $\pm 5\text{V}$ Supply | 0.01 | | | % |

AC Electrical Characteristics (Continued)

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating conditions indicate conditions for which the device is intended to be functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only for the test conditions listed.

Note 2: Applies to both single-supply and split-supply operation. Continuous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 110°C. Output currents in excess of ± 30 mA over long term may adversely affect reliability.

Note 3: The maximum power dissipation is a function of $T_{J(max)}$, θ_{JA} , and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(max)} - T_A)/\theta_{JA}$.

Note 4: Human body model, 1.5 k Ω in series with 100 pF.

Note 5: Typical Values represent the most likely parametric norm.

Note 6: All limits are guaranteed at room temperature (standard type face) or at operating temperature extremes (bold face type).

Note 7: $V^+ = 15V$, $V_{CM} = 7.5V$ and R_L connected to 7.5V. For Sourcing tests, $7.5V \leq V_O \leq 11.5V$. For Sinking tests, $2.5V \leq V_O \leq 7.5V$.

Note 8: $V^+ = 15V$. Connected as Voltage Follower with 10V step input. Number specified in the slower of the positive and negative slew rates.

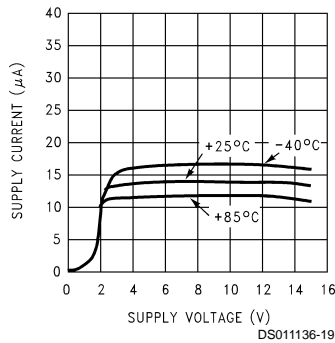
Note 9: For operating at elevated temperatures the device must be derated based on the thermal resistance θ_{JA} with $P_D = (T_J - T_A)/\theta_{JA}$.

Note 10: All numbers apply for packages soldered directly into a PC board.

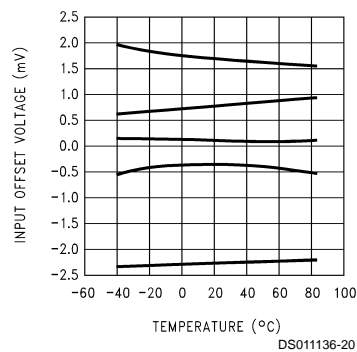
Note 11: Do not connect output to V^+ when V^+ is greater than 13V or reliability may be adversely affected.

Typical Performance Characteristics $V_S = \pm 7.5V$, $T_A = 25^\circ C$ unless otherwise specified

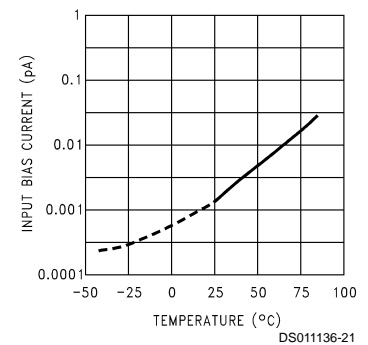
Supply Current vs Supply Voltage



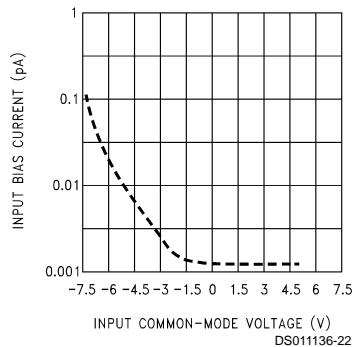
Offset Voltage vs Temperature of Five Representative Units



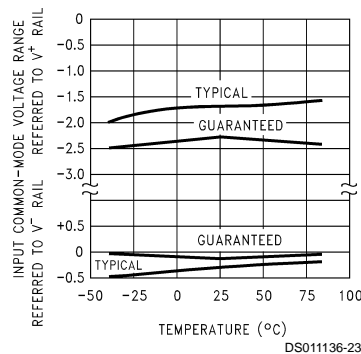
Input Bias Current vs Temperature



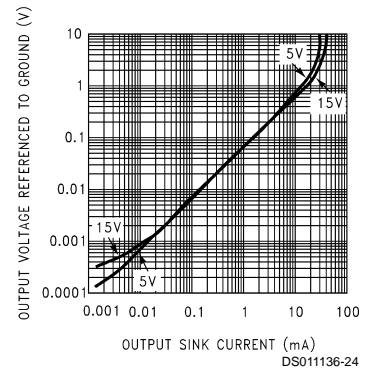
Input Bias Current vs Input Common-Mode Voltage



Input Common-Mode Voltage Range vs Temperature

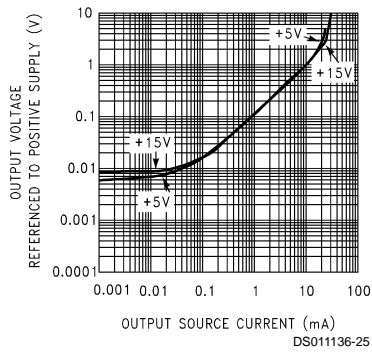


Output Characteristics Current Sinking

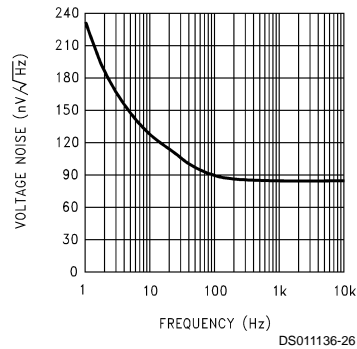


Typical Performance Characteristics $V_S = \pm 7.5V$, $T_A = 25^\circ C$ unless otherwise specified (Continued)

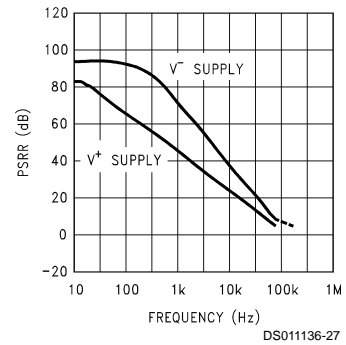
Output Characteristics Current Sourcing



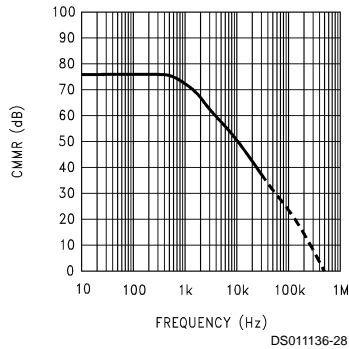
Input Voltage Noise vs Frequency



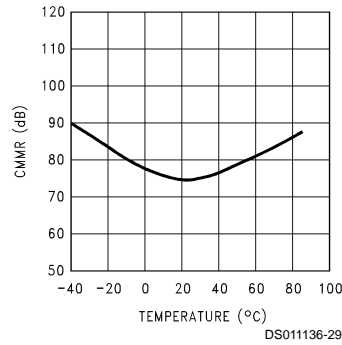
Power Supply Rejection Ratio vs Frequency



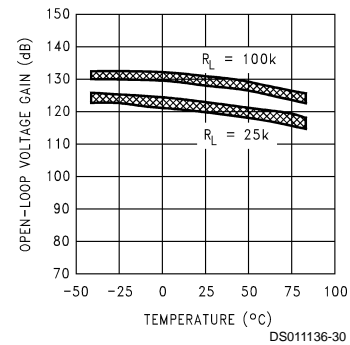
CMRR vs Frequency



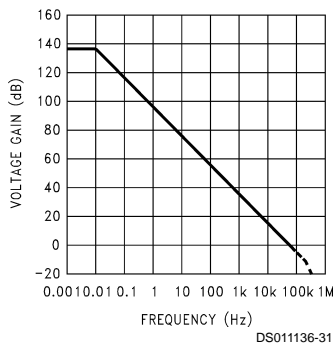
CMRR vs Temperature



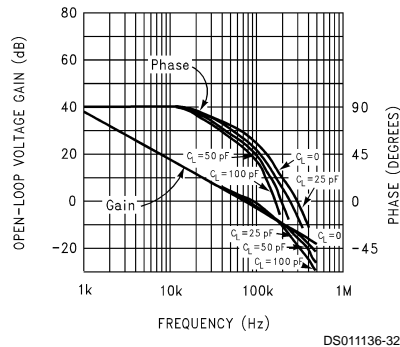
Open-Loop Voltage Gain vs Temperature



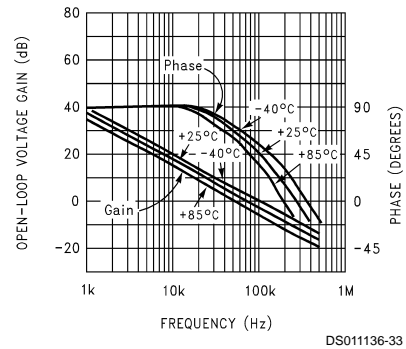
Open-Loop Frequency Response



Gain and Phase Responses vs Load Capacitance

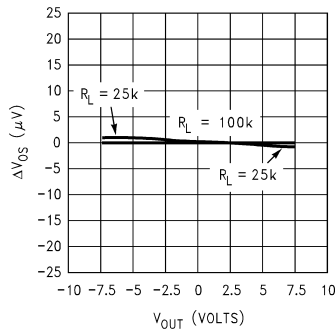


Gain and Phase Responses vs Temperature

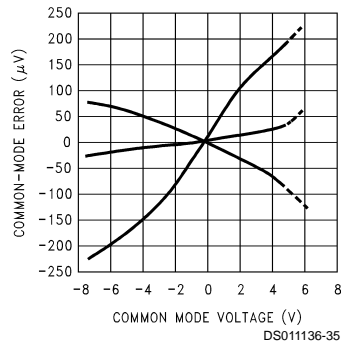


Typical Performance Characteristics $V_S = \pm 7.5V$, $T_A = 25^\circ C$ unless otherwise specified (Continued)

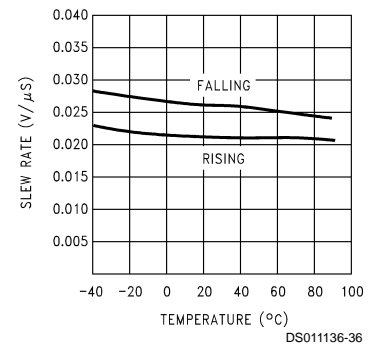
Gain Error (V_{OS} vs V_{OUT})



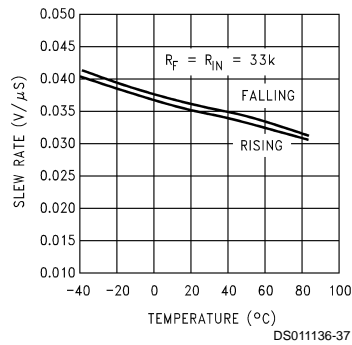
Common-Mode Error vs Common-Mode Voltage of Three Representative Units



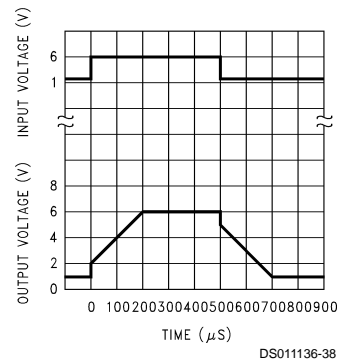
Non-Inverting Slew Rate vs Temperature



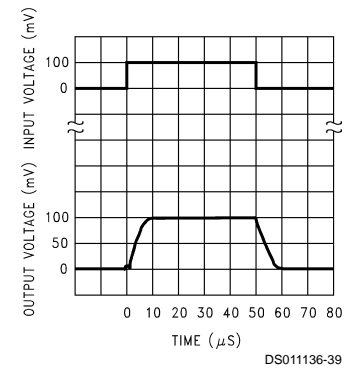
Inverting Slew Rate vs Temperature



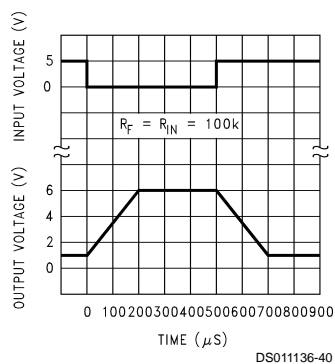
Non-Inverting Large Signal Pulse Response ($A_V = +1$)



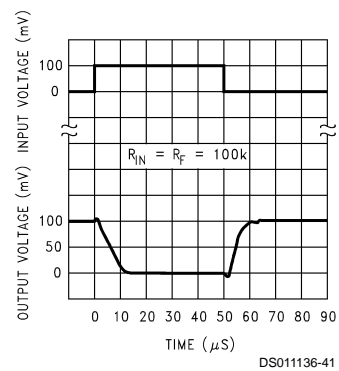
Non-Inverting Small Signal Pulse Response



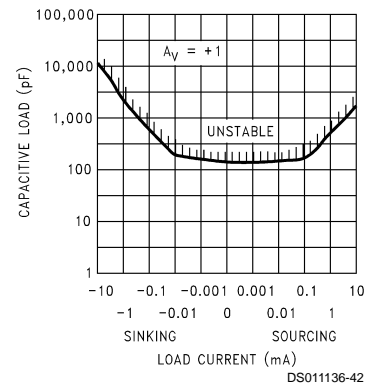
Inverting Large-Signal Pulse Response



Inverting Small Signal Pulse Response



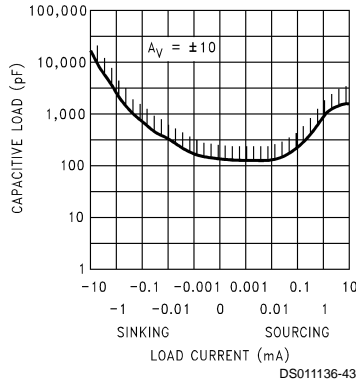
Stability vs Capacitive Load ($A_V = +1$)



Typical Performance

Characteristics $V_S = \pm 7.5V$, $T_A = 25^\circ C$ unless otherwise specified (Continued)

Stability vs Capacitive Load ($A_V = \pm 10$)



Applications Hints

AMPLIFIER TOPOLOGY

The LMC6041 incorporates a novel op-amp design topology that enables it to maintain rail-to-rail output swing even when driving a large load. Instead of relying on a push-pull unity gain output buffer stage, the output stage is taken directly from the internal integrator, which provides both low output impedance and large gain. Special feed-forward compensation design techniques are incorporated to maintain stability over a wider range of operating conditions than traditional micropower op-amps. These features make the LMC6041 both easier to design with, and provide higher speed than products typically found in this ultra-low power class.

COMPENSATING FOR INPUT CAPACITANCE

It is quite common to use large values of feedback resistance with amplifiers with ultra-low input current, like the LMC6041.

Although the LMC6041 is highly stable over a wide range of operating conditions, certain precautions must be met to achieve the desired pulse response when a large feedback resistor is used. Large feedback resistors and even small values of input capacitance, due to transducers, photodiodes, and circuits board parasitics, reduce phase margins.

When high input impedance are demanded, guarding of the LMC6041 is suggested. Guarding input lines will not only reduce leakage, but lowers stray input capacitance as well. (See **Printed-Circuit-Board Layout for High Impedance Work.**)

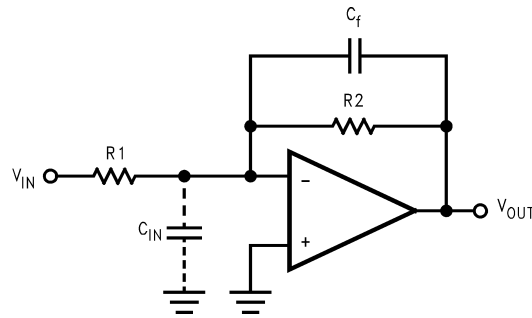


FIGURE 1. Cancelling the Effect of Input Capacitance

The effect of input capacitance can be compensated for by adding a capacitor. Adding a capacitor, C_f , around the feedback resistor (as in *Figure 1*) such that:

$$\frac{1}{2\pi R_1 C_{IN}} \geq \frac{1}{2\pi R_2 C_f}$$

or

$$R_1 C_{IN} \leq R_2 C_f$$

Since it is often difficult to know the exact value of C_{IN} , C_f can be experimentally adjusted so that the desired pulse response is achieved. Refer to the LMC660 and the LMC662 for a more detailed discussion on compensating for input capacitance.

CAPACITIVE LOAD TOLERANCE

Direct capacitive loading will reduce the phase margin of many op-amps. A pole in the feedback loop is created by the combination of the op-amp's output impedance and the capacitive load. This pole induces phase lag at the unity-gain crossover frequency of the amplifier resulting in either an oscillatory or underdamped pulse response. With a few external components, op amps can easily indirectly drive capacitive loads, as shown in *Figure 2*.

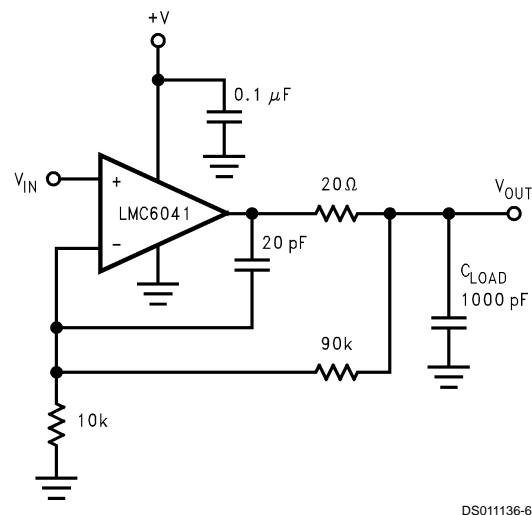


FIGURE 2. LMC6041 Noninverting Gain of 10 Amplifier, Compensated to Handle Capacitive Loads

In the circuit of *Figure 2*, R_1 and C_1 serve to counteract the loss of phase margin by feeding the high frequency compo-

Applications Hints (Continued)

nent of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop.

Capacitive load driving capability is enhanced by using a pull up resistor to V^+ (Figure 3). Typically a pull up resistor conducting 10 μA or more will significantly improve capacitive load responses. The value of the pull up resistor must be determined based on the current sinking capability of the amplifier with respect to the desired output swing. Open loop gain of the amplifier can also be affected by the pull up resistor (see Electrical Characteristics).

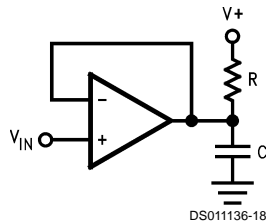


FIGURE 3. Compensating for Large Capacitive Loads with a Pull Up Resistor

PRINTED-CIRCUIT-BOARD LAYOUT FOR HIGH-IMPEDANCE WORK

It is generally recognized that any circuit which must operate with less than 1000 pA of leakage current requires special layout of the PC board. When one wishes to take advantage of the ultra-low bias current of the LMC6041, typically less than 2fA, it is essential to have an excellent layout. Fortunately, the techniques of obtaining low leakages are quite simple. First, the user must not ignore the surface leakage of the PC board, even though it may sometimes appear acceptably low, because under conditions of high humidity or dust or contamination, the surface leakage will be appreciable.

To minimize the effect of any surface leakage, lay out a ring of foil completely surrounding the LMC6041's inputs and the terminals of capacitors, diodes, conductors, resistors, relay terminals, etc. connected to the op-amp's inputs, as in Figure 4. To have a significant effect, guard rings should be placed on both the top and bottom of the PC board. This PC foil must then be connected to a voltage which is at the same voltage as the amplifier inputs, since no leakage current can flow between two points at the same potential. For example, a PC board trace-to-pad resistance of $10^{12}\Omega$, which is normally considered a very large resistance, could leak 5 pA if the trace were a 5V bus adjacent to the pad of the input. This would cause a 100 times degradation from the LMC6041's actual performance. However, if a guard ring is held within 5 mV of the inputs, then even a resistance of $10^{11}\Omega$ would cause only 0.05 pA of leakage current. See Figure 5 for typical connections of guard rings for standard op-amp configurations.

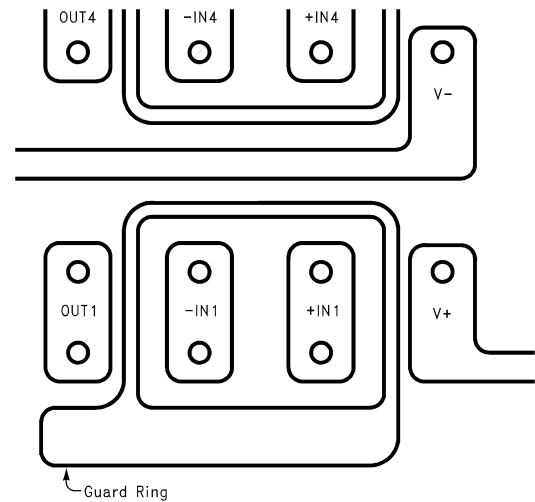
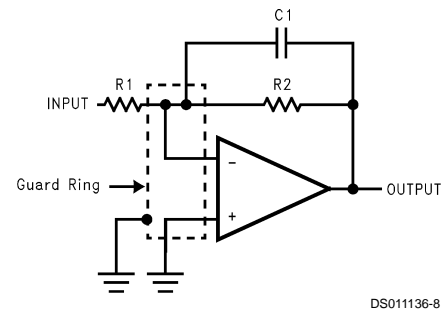
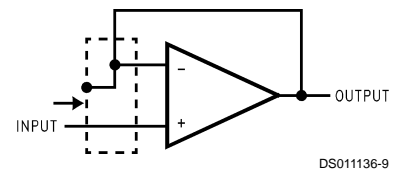


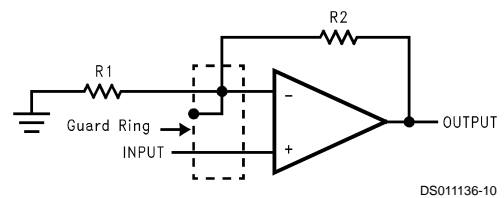
FIGURE 4. Example of Guard Ring in P.C. Board Layout



Inverting Amplifier



Follower

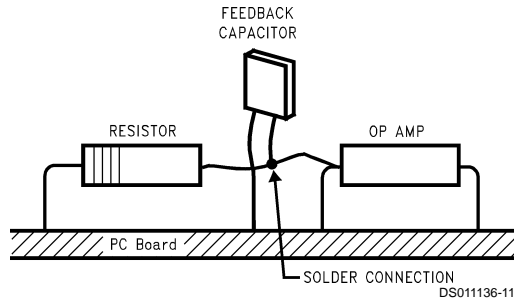


Non-Inverting Amplifier

FIGURE 5. Typical Connections of Guard Rings

The designer should be aware that when it is inappropriate to lay out a PC board for the sake of just a few circuits, there is another technique which is even better than a guard ring on a PC board: Don't insert the amplifier's input pin into the board at all, but bend it up in the air and use only air as an insulator. Air is an excellent insulator. In this case you may have to forego some of the advantages of PC board construction, but the advantages are sometimes well worth the effort of using point-to-point up-in-the-air wiring. See Figure 6.

Applications Hints (Continued)



(Input pins are lifted out of PC board and soldered directly to components. All other pins connected to PC board.)

FIGURE 6. Air Wiring

Typical Single-Supply Applications

($V^+ = 5.0 V_{DC}$)

The extremely high input impedance, and low power consumption, of the LMC6041 make it ideal for applications that require battery-powered instrumentation amplifiers. Examples of these type of applications are hand-held pH probes, analytic medical instruments, magnetic field detectors, gas detectors, and silicon based pressure transducers.

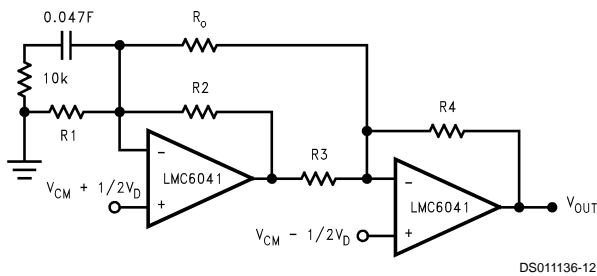


FIGURE 7. Two Op-Amp Instrumentation Amplifier

The circuit in *Figure 7* is recommended for applications where the common-mode input range is relatively low and the differential gain will be in the range of 10 to 1000. This two op-amp instrumentation amplifier features an independent adjustment of the gain and common-mode rejection trim, and a total quiescent supply current of less than 28 μA . To maintain ultra-high input impedance, it is advisable to use ground rings and consider PC board layout an important part of the overall system design (see Printed-Circuit-Board Layout for High Impedance Work). Referring to *Figure 7*, the input voltages are represented as a common-mode input V_{CM} plus a differential input V_D .

Rejection of the common-mode component of the input is accomplished by making the ratio of $R1/R2$ equal to $R3/R4$. So that where,

$$\frac{R3}{R4} = \frac{R2}{R1}$$

$$V_{OUT} = \frac{R4}{R3} \left(1 + \frac{R3}{R4} + \frac{R2 + R3}{R_O} \right) V_D$$

A suggested design guideline is to minimize the difference of value between $R1$ through $R4$. This will often result in improved resistor tempco, amplifier gain, and CMRR over temperature. If $R_N = R1 = R2 = R3 = R4$ then the gain equation can be simplified:

$$V_{OUT} = 2 \left(1 + \frac{R_N}{R_O} \right) V_D$$

Due to the “zero-in, zero-out” performance of the LMC6041, and output swing rail-rail, the dynamic range is only limited to the input common-mode range of 0V to $V_S - 2.3V$, worst case at room temperature. This feature of the LMC6041 makes it an ideal choice for low-power instrumentation systems.

A complete instrumentation amplifier designed for a gain of 100 is shown in *Figure 8*. Provisions have been made for low sensitivity trimming of CMRR and gain.

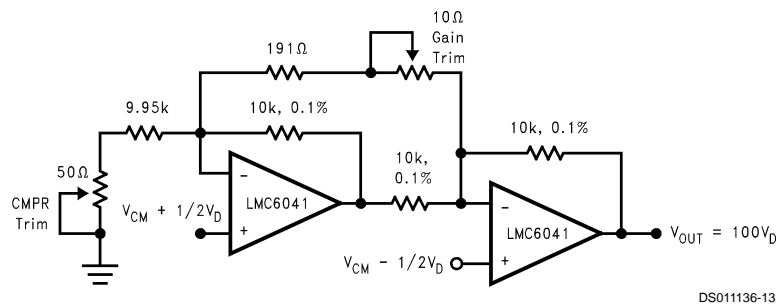


FIGURE 8. Low-Power Two-Op-Amp Instrumentation Amplifier

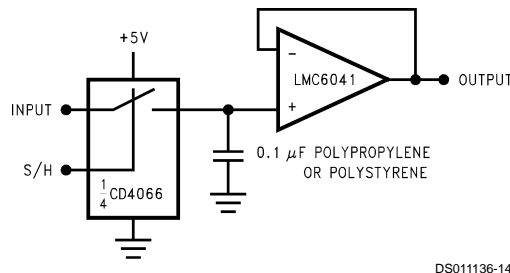


FIGURE 9. Low-Leakage Sample and Hold

Typical Single-Supply Applications ($V^+ = 5.0\text{ V}_{\text{DC}}$) (Continued)

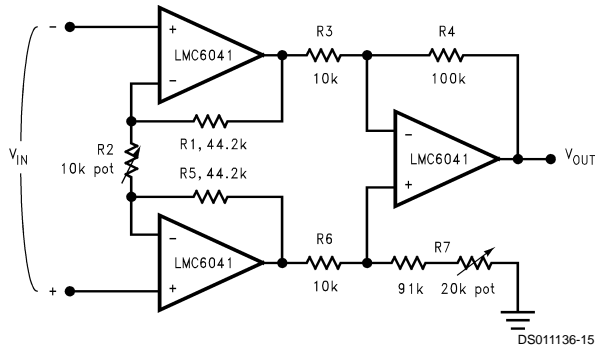


FIGURE 10. Instrumentation Amplifier

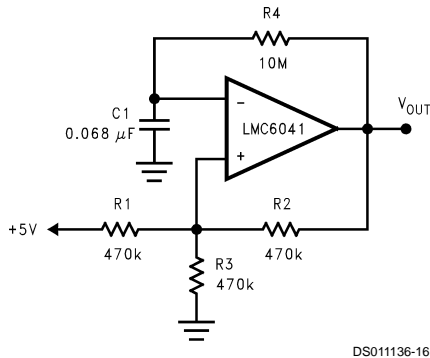


FIGURE 11. 1 Hz Square-Wave Oscillator

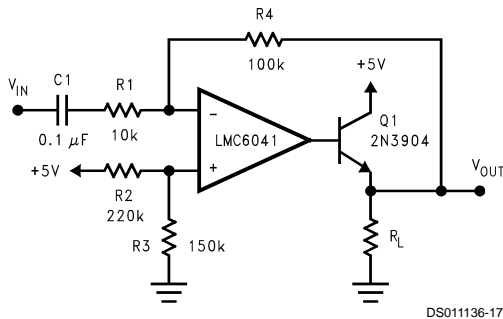
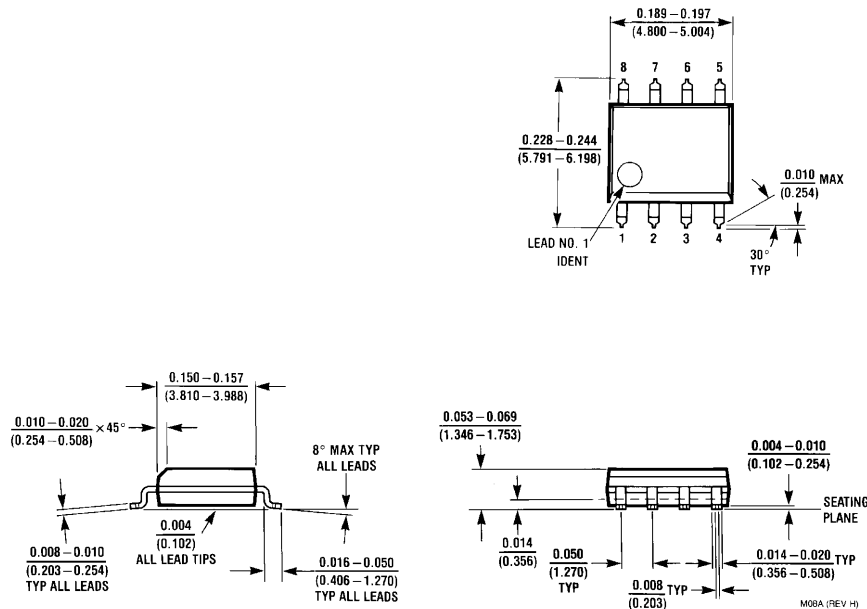


FIGURE 12. AC Coupled Power Amplifier

Ordering Information

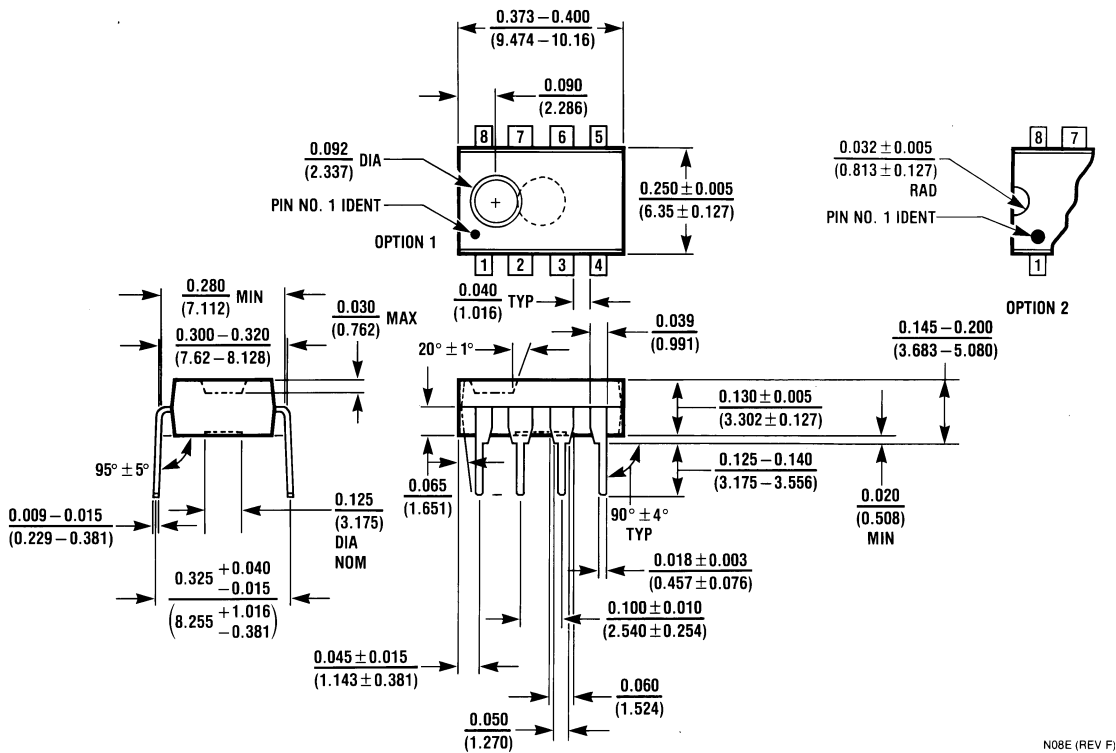
| Package | Temperature Range | NSC Drawing | Transport Media |
|------------------------|--|-------------|---------------------------|
| | Industrial -40°C to +85°C | | |
| 8-Pin Small Outline | LMC6041AIM, LMC6041AIMX LMC6041IM, LMC6041IMX | M08A | Rail Tape and Reel |
| 8-Pin Molded DIP | LMC6041AIN LM6041IN | N08E | Rail |

Physical Dimensions inches (millimeters) unless otherwise noted



8-Pin Small Outline

Order Number LMC6041AIM, LMC6041AIMX, LMC6041IM or LMC6041IMX
NS Package Number M08A



8-Pin Molded DIP

Order Number LMC6041AIN or LMC6041IN
NS Package Number N08E

Notes

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