

INTRODUCTION

The KA22136/D is a monolithic integrated circuit designed for use in low voltage and low power applications. It has functions including dual audio pre-power amplifier, electronic volume controller and DC motor speed controller in a single chip. It is suitable for portable tape recorders headphone cassette tape recorders or radios that are battery-operated.

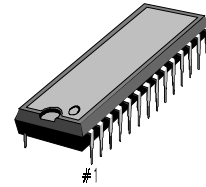
FEATURES

- Low current consumption in an operating voltage range
- Operating supply voltage range: $V_{CC} = 2.1V \sim 5V$
- Only a few components in composing a headphone cassette tape recorder
- Dual audio pre-power amplifier, electronic volume controller and DC motor speed controller in a single chip
- Reduced input and output coupling capacitors because of 1/2 V_{CC} AMP adoption on chip as AC GND

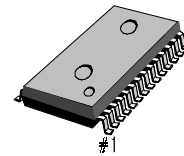
ORDERING INFORMATION

Device	Package	Operating Temperature
KA22136	28-SDIP	$-20^{\circ}C \sim +65^{\circ}C$
KA22136D	28-SOP	

28-SDIP



28-SOP



BLOCK DIAGRAM

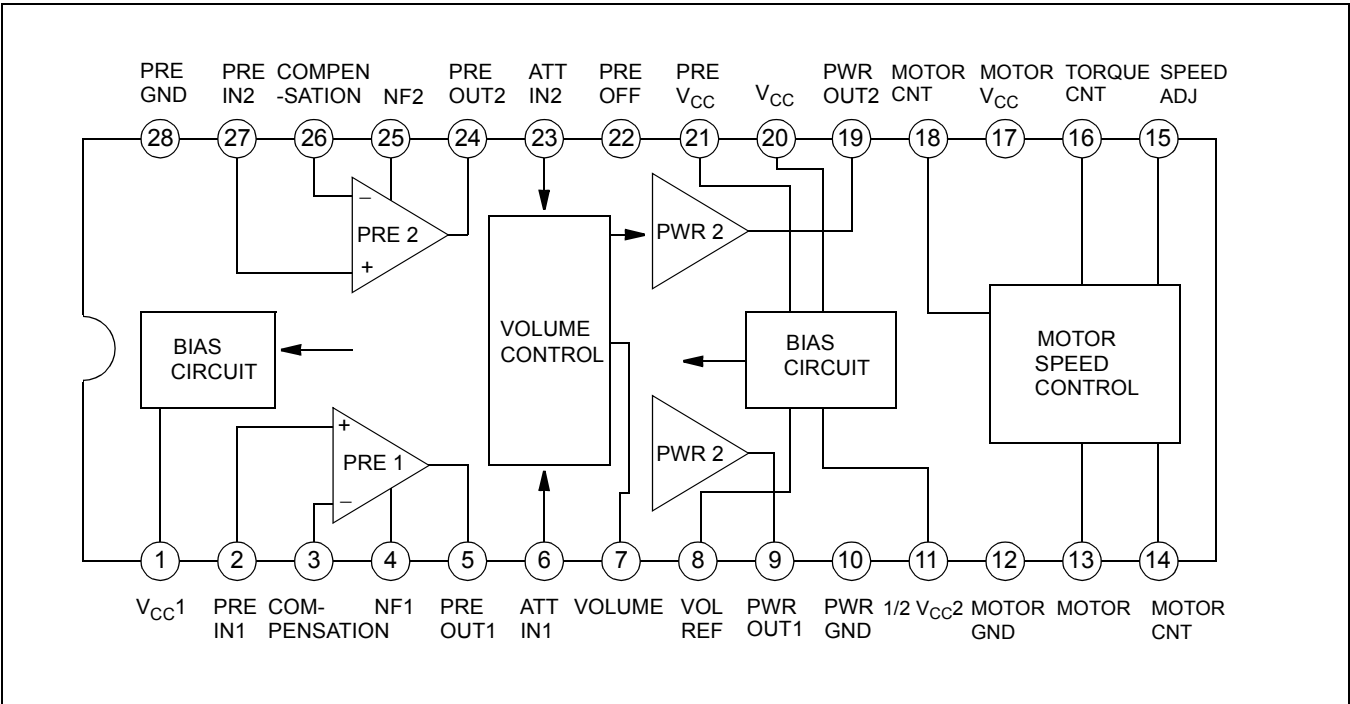


Figure 1.

ABSOLUTE MAXIMUM RATINGS (Ta = 25°C)

Characteristic	Symbol	Value	Unit
Supply Voltage	V _{CC}	7.5	V
Power Dissipation	P _O	450	mW
Operating Temperature	T _{OPR}	-20 ~ +70	°C
Storage Temperature	T _{STG}	- 40 ~ +125	°C

ELECTRICAL CHARACTERISTICS(Ta = 25°C, V_{CC} = 3V, unless otherwise specified)

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Unit
Quiescent Circuit Current	I _{CCQ}	V _{CC} = 3V, V _I = 0, I _M = 0	–	18	25	mA

PRE AMPLIFIER SECTION(V_{CC} = 3V, f = 1kHz, R_{L1} = 10kΩ, unless otherwise specified)

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Unit
Open Loop Voltage Gain	G _{VO}	V _O = –10dBm, R _L = ∞	–	70	–	dB
Closed Loop Voltage Gain	G _{VC1}	V _O = –10dBm	40	42	44	dB
Output Voltage	V _O	THD = 1%	0.45	0.6	–	V
Total Harmonic Distortion	THD	V _O = 0.2V	–	0.05	0.5	%
Output Noise Voltage	V _{NO1}	V _I = 0, R _g = 2.2kΩ, BPF(30 ~ 20kHz)	–	150	300	μV
Input Resistance	R _I	V _O = 10dBm	18	22	–	kΩ
Cross Talk	CT ₁	R _G = 2.2kΩ, V _O = –10dBm	30	–	–	dB
Output Voltage In Pre OFF	V _{O (OFF)}	V _I = 100mV Pre OFF (pin 22) = V _{CC}	–	–	–50	dB

POWER AMPLIFIER SECTION(Ta = 25°C, V_{CC} = 3V, unless otherwise specified)

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Unit
Closed Loop Voltage Gain	G _{VC2}	P _O = 5mW	26	28	30	dB
Voltage Gain Difference	ΔG _V	V _{CONT} = Max	–	0	3	dB
Output Power 1	P _{O1}	THD = 10%, R _L = 32Ω	20	28	–	mW
Output Power 2	P _{O2}	THD = 10%, R _L = 16Ω	30	–	–	mW
Total Harmonic Distortion	THD ₂	P _O = 5mW	–	0.2	2.0	%
Pre+ Power Output Noise Voltage	V _{NO2I}	V _I = 0, R _G = 2.2kΩ, V _{CONT} = Max	–	6	10	mV
Output Noise Voltage	V _{NO3I}	R _G = 2.2 kΩ, V _{CONT} = Min	–	0.25	1.0	mV
Cross Talk	CT ₂	R _O = 5mW	20	30	–	dB
Ripple Rejection Ratio	RR	V _{CC} = 3V, 100Hz, 100mVp-p	34	40	–	dB

ATTENUATOR SECTION

($T_a = 25^\circ\text{C}$, $V_{CC} = 3\text{V}$, $f = 1\text{kHz}$, unless otherwise specified)

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Unit
Maximum Input Voltage	$V_{I(\text{MAX})}$	–	0.2	–	–	V
Maximum Attenuation	$V_{\text{ATT}(\text{MAX})}$	$V_{\text{CONT}} = \text{Min}$	66	–	–	dB
Attenuation Error	$V_{\text{ATT}(\text{ERR})}$	$V_{\text{CONT}} = \text{Max}$	–	0	–	dB
Input Impedance	Z_I	–	15	20	–	$\text{K}\Omega$

MOTOR SPEED CONTROLLER

($T_a = 25^\circ\text{C}$, $V_{CC} = 3\text{V}$, $I_M = 100\text{mA}$, unless otherwise specified)

Characteristic	Symbol	Test Conditions	Min.	Typ.	Max.	Unit
Circuit Current	I_{MC}	–	–	3.0	5.0	mA
Starting Current	I_{MS}	–	500	–	–	mA
Reference Voltage	V_{REF}	V(pin 15, 16)	0.72	0.80	0.87	V
Reference Voltage Regulation 1	$\Delta V_{\text{REF}1}$	$V_{CC} = 2.1 \sim 5.0 \text{ V}$	–	0.05	–	%/V
Reference Voltage Regulation 2	$\Delta V_{\text{REF}2}$	$I_M = 25 \sim 250 \text{ mA}$	–	0.01	–	%/mA
Reference Voltage Regulation 3	$\Delta V_{\text{REF}3}$	$T_a = -10 \sim 50^\circ\text{C}$	–	0.01	–	%/ $^\circ\text{C}$
Current Coefficient	K	–	32	38	43	–
Current Coefficient Regulation 1	$\Delta K1$	$V_{CC} = 2.1 \sim 5.0 \text{ V}$	–	0.50	–	%/V
Current Coefficient Regulation 2	$\Delta K2$	$I_M = 25 \sim 250 \text{ mA}$	–	0.05	–	%/mA
Current Coefficient Regulation 3	$\Delta K3$	$T_a = -10 \sim 50^\circ\text{C}$	–	0.02	–	%/ $^\circ\text{C}$
Saturation Voltage	V_{SAT}	$I_M = 200\text{mA}$, Pin14 = V_{CC}	–	–	0.6	V
Leakage Current	I_{LKG}	Pin 18 = V_{CC}	–	50	200	μV

* Voltage across Pin 13, 17

TEST CIRCUIT

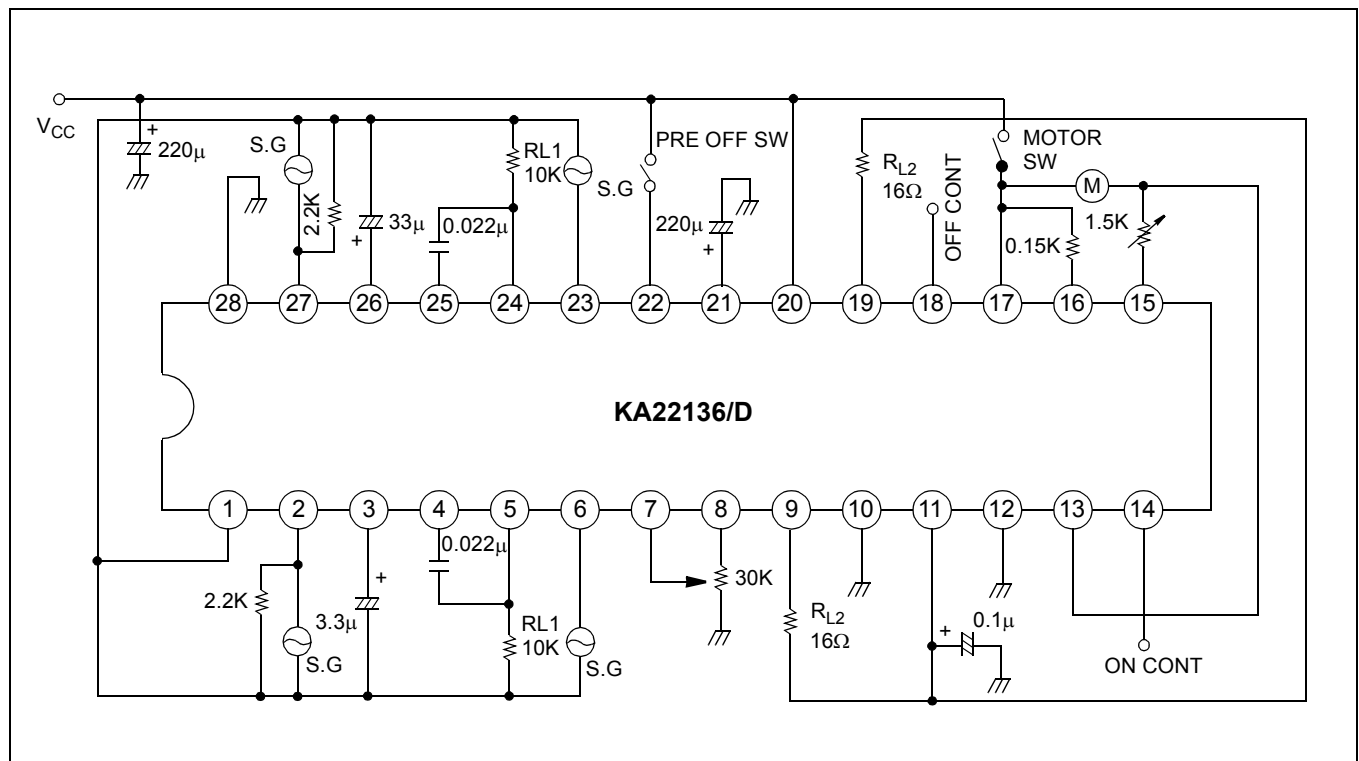


Figure 2.

APPLICATION CIRCUIT

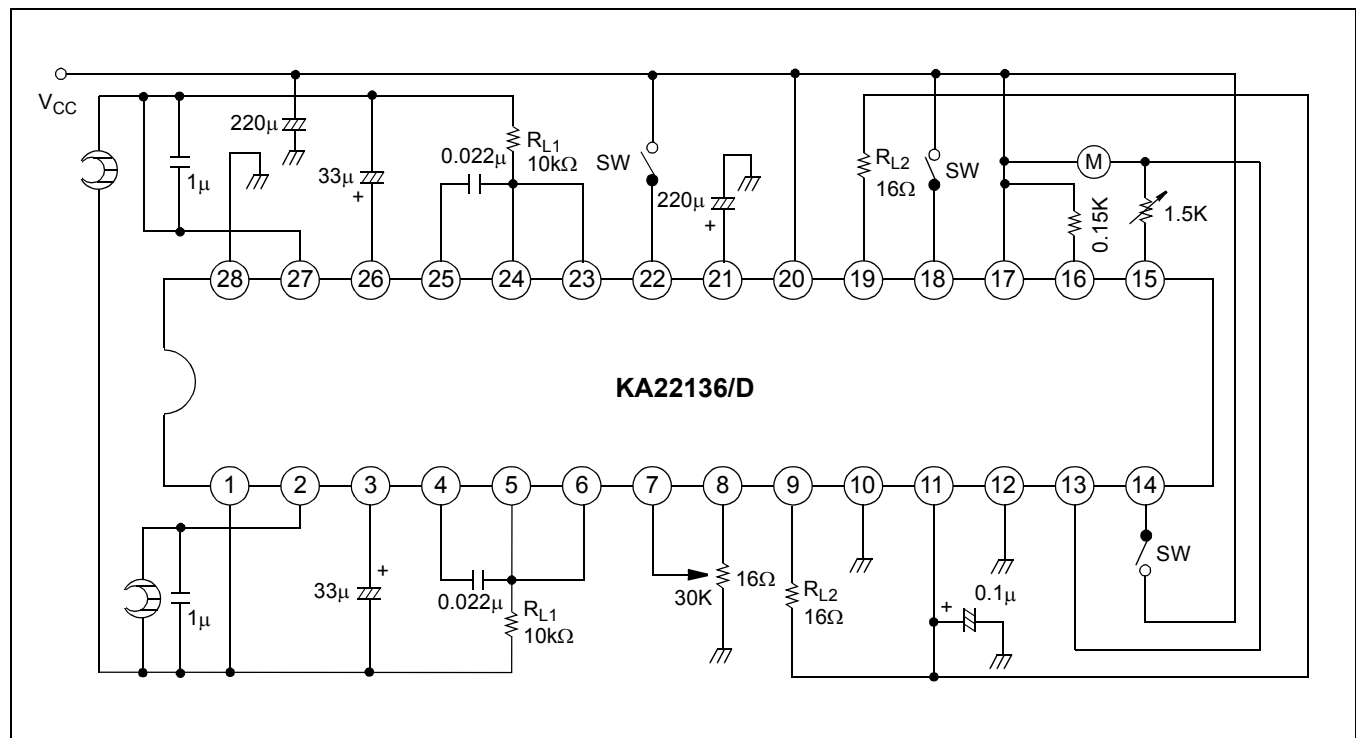


Figure 3.