

**LB1995**

## Three-Phase Brushless Motor Driver for CD-ROM Spindle Drive

### Overview

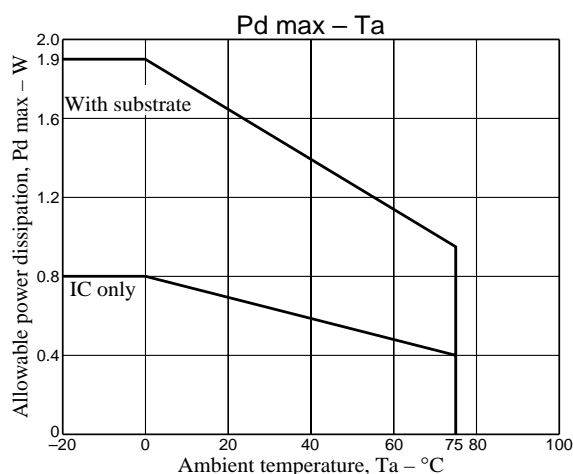
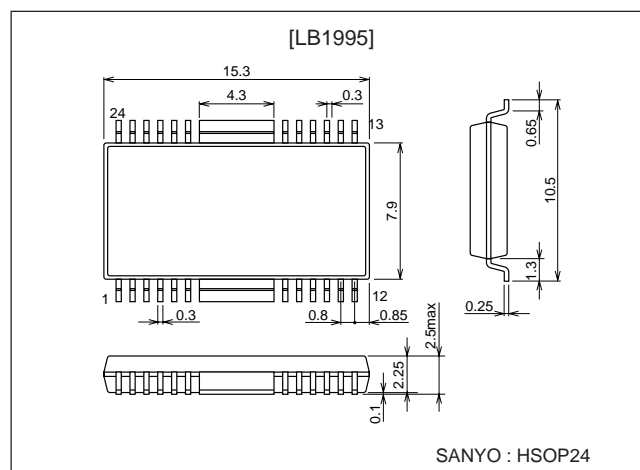
The LB1995 is a three-phase brushless motor driver especially suited for CD-ROM spindle motor drives.

### Functions

- Current linear drive
- Control V type amplifier with single side control switching pin
- Separate power supply for output upper side bias circuit allows low output saturation by boosting this power supply only (useful for 5V power supply types).
- Upper side current detection technique reduces loss voltage of current detection resistor. Voltage effect of this resistor reduces internal current drain of IC.
- Built-in short braking circuit
- Built-in reverse blocking circuit
- Hall FG output
- Built-in S/S function
- Built-in current limiter circuit
- Built-in Hall power supply
- Built-in thermal shutdown circuit

### Package Dimensions

unit: mm

**3227-HSOP24**

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## Specifications

### Maximum Ratings at $T_a = 25^{\circ}\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	$V_{CC1}$ max		7.0	V
	$V_{CC2}$ max		14.4	V
	$V_{CC3}$ max		14.4	V
Applied output voltage	$V_O$ max		14.4	V
Applied input voltage	$V_{IN}$ max		$V_{CC1}$	V
Output current	$I_O$ max		1.3	A
Allowable power dissipation	$P_d$ max	IC only	0.8	W
		with substrate ( $114.3 \times 76.1 \times 1.6 \text{ mm}^3$ , glass epoxy)	1.9	W
Operating temperature	$T_{opr}$		$-20$ to $+75$	$^{\circ}\text{C}$
Storage temperature	$T_{stg}$		$-55$ to $+150$	$^{\circ}\text{C}$

### Operating Conditions at $T_a = 25^{\circ}\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	$V_{CC1}$		4 to 6	V
	$V_{CC2}$	$\geq V_{CC1}$	4 to 13.6	V
	$V_{CC3}$		4 to 13.6	V

### Sample Application at $T_a = 25^{\circ}\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
12V type	$V_{CC1}$	Regulated voltage	4 to 6	V
	$V_{CC2} = V_{CC3}$	Unregulated voltage	4 to 13.6	V
5V type	$V_{CC1} = V_{CC3}$	Regulated voltage	4 to 6	V
	$V_{CC2}$	Boost-up voltage or regulated voltage (Note)	4 to 13.6	V

Note: When boost-up voltage is used at  $V_{CC2}$ , output can be set to low-saturation.

**Electrical Characteristics at Ta = 25°C, V<sub>CC1</sub> = 5V, V<sub>CC2</sub> = V<sub>CC3</sub> = 12V**

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
[Power supply current]						
Power supply current	I <sub>CC1</sub>	V <sub>C</sub> = V <sub>CREF</sub>		8		mA
	I <sub>CC2</sub>	V <sub>C</sub> = V <sub>CREF</sub>		0		mA
	I <sub>CC3</sub>	V <sub>C</sub> = V <sub>CREF</sub>		150	250	μA
Output idle current	I <sub>CC1OQ</sub>	V <sub>S/S</sub> = 0V			200	μA
	I <sub>CC2OQ</sub>	V <sub>S/S</sub> = 0V			30	μA
	I <sub>CC3OQ</sub>	V <sub>S/S</sub> = 0V			30	μA
[Output]						
Saturation voltage, upper side 1 lower side 1	V <sub>OU1</sub>	I <sub>O</sub> = −0.5A, V <sub>CC1</sub> = 5V, V <sub>CC2</sub> = V <sub>CC3</sub> = 12V		1.0		V
	V <sub>OD1</sub>	I <sub>O</sub> = 0.5A, V <sub>CC1</sub> = 5V, V <sub>CC2</sub> = V <sub>CC3</sub> = 12V		0.3		V
Saturation voltage, upper side 2 lower side 2	V <sub>OU2</sub>	I <sub>O</sub> = −0.5A, V <sub>CC1</sub> = V <sub>CC3</sub> = 5V, V <sub>CC2</sub> = 12V		0.3		V
	V <sub>OD2</sub>	I <sub>O</sub> = 0.5A, V <sub>CC1</sub> = V <sub>CC3</sub> = 5V, V <sub>CC2</sub> = 12V		0.3		V
Current limiter setting voltage	V <sub>CL</sub>	R <sub>RF</sub> = 0.43Ω		0.37		V
[Hall amplifier]						
Common mode input voltage range	V <sub>HCOM</sub>		1.2		V <sub>CC</sub> −1.0	V
Input bias current	I <sub>HIB</sub>			1		μA
Minimum Hall input level	V <sub>HIN</sub>		60			mV <sub>P-P</sub>
[S/S pin]						
High level voltage	V <sub>S/SH</sub>		2.0		V <sub>CC1</sub>	V
Low level voltage	V <sub>S/SL</sub>				0.7	V
Input current	I <sub>S/SI</sub>	V <sub>S/S</sub> = 5V			200	μA
Leak current	I <sub>S/SL</sub>	V <sub>S/S</sub> = 0V	−30			μA
[Control]						
V <sub>C</sub> pin input current	I <sub>VC</sub>	V <sub>C</sub> = V <sub>CREF</sub> = 2.5V		1		μA
V <sub>CREF</sub> pin input current	I <sub>VCREF</sub>	V <sub>C</sub> = V <sub>CREF</sub> = 2.5V		1		μA
Voltage gain	GV <sub>CO</sub>	ΔV <sub>RF</sub> /ΔV <sub>C</sub>		0.25		times
Startup voltage	V <sub>CTH</sub>	V <sub>CREF</sub> = 2.5V	2.35		2.65	V
Startup voltage width	ΔV <sub>CTH</sub>	V <sub>CREF</sub> = 2.5V	50		150	mV
[Hall power supply]						
Hall power supply voltage	V <sub>H</sub>	I <sub>H</sub> = 5 mA		0.8		V
Allowable current	I <sub>H</sub>		20			mA
[Thermal shutdown]						
Operating temperature	T <sub>TSD</sub>	Design target value	150	180	210	°C
Hysteresis	ΔT <sub>TSD</sub>	Design target value		15		°C
[Short braking]						
Brake pin at High level	V <sub>BRH</sub>		4		5	V
Brake pin at Low level	V <sub>BRL</sub>		0		1	V
[Control switching]						
CC pin at High level	V <sub>CCH</sub>		4		5	V
CC pin at Low level	V <sub>CCL</sub>		0		1	V

Note:

- During S/S OFF (standby), the Hall comparator is at High.
- Design target values are not measured.

## Truth Table

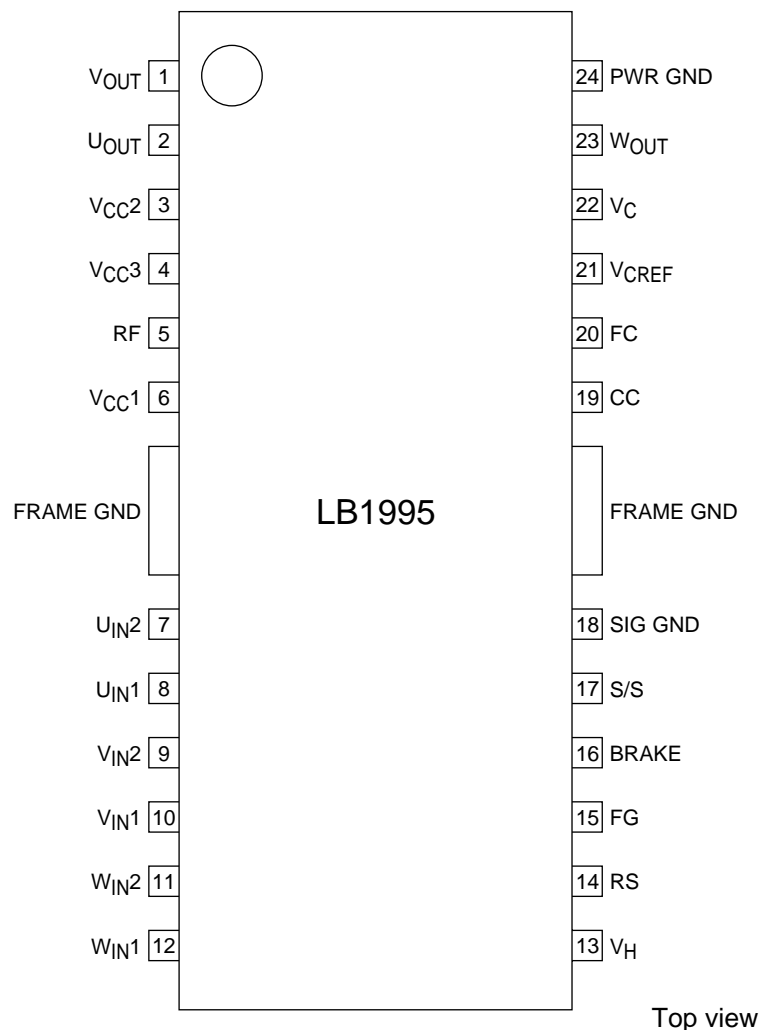
	Source → Sink	Hall input			Control $V_C$
		U	V	W	
1	Phase W → Phase V	H	H	L	H
	Phase V → Phase W				L
2	Phase W → Phase U	H	L	L	H
	Phase U → Phase W				L
3	Phase V → Phase W	L	L	H	H
	Phase W → Phase V				L
4	Phase U → Phase V	L	H	L	H
	Phase V → Phase U				L
5	Phase V → Phase U	H	L	H	H
	Phase U → Phase V				L
6	Phase U → Phase W	L	H	H	H
	Phase W → Phase U				L

Input:

H: Input 1 is higher in potential than input 2 by at least 0.2V.

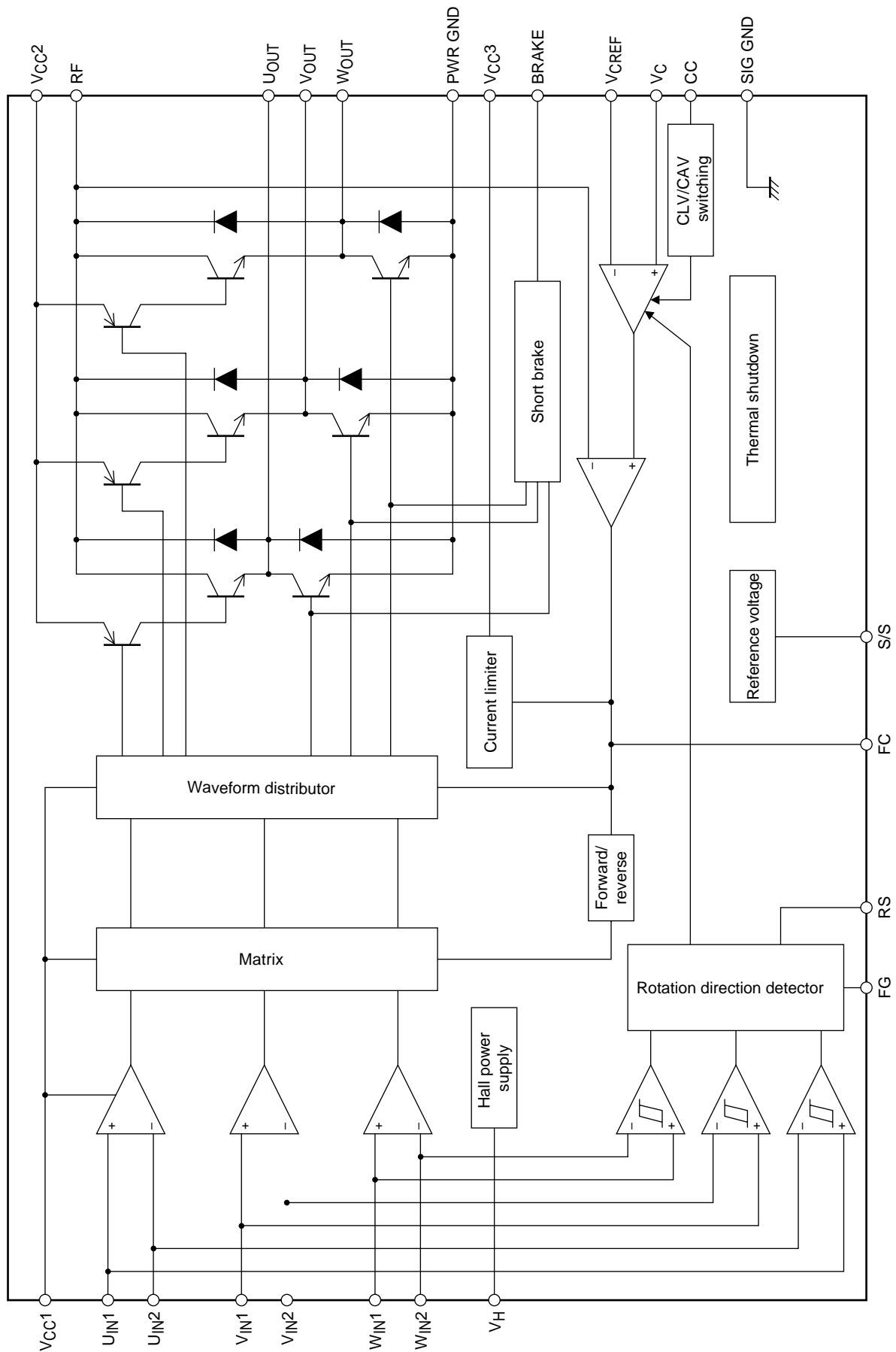
L: Input 1 is lower in potential than input 2 by at least 0.2V.

## Pin Assignment



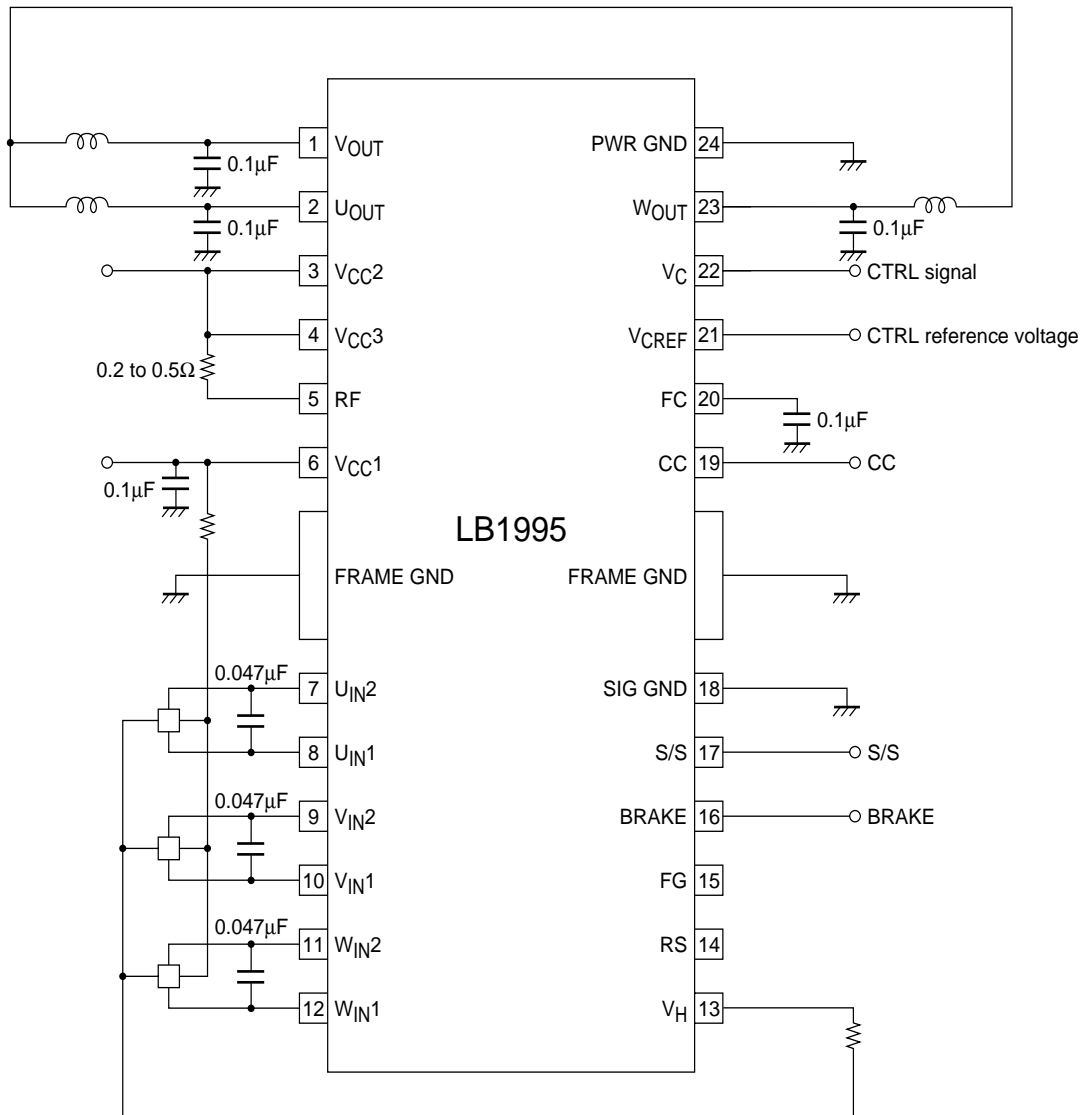
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## Block Diagram



A11124

## Sample Application Circuit

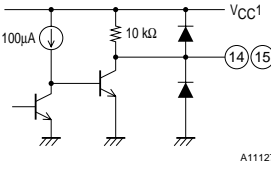
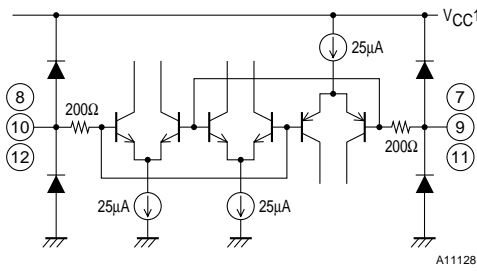
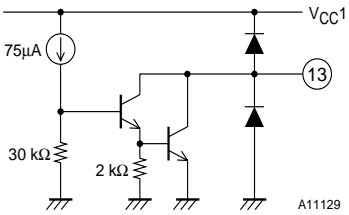
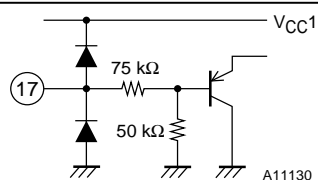
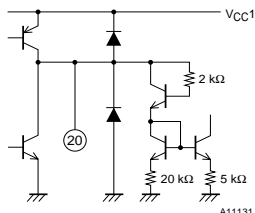


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Power supply - GND  
Output - GND  
Between Hall inputs

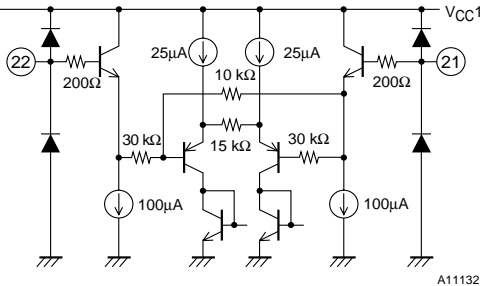
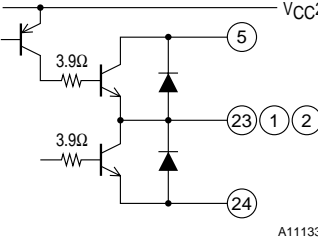
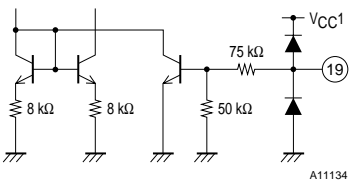
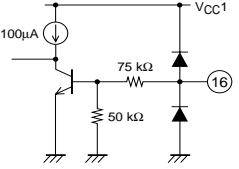
Capacitor requirements may change depending on motor.  
For some motors, capacitor between Hall inputs may not be needed.

## Pin Descriptions

Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
3	$V_{CC2}$	4V to 13.6V		Source side predrive voltage supply pin
4	$V_{CC3}$	4V to 13.6V		Constant current control amplifier voltage supply pin
6	$V_{CC1}$	4V to 6V		Power supply pin for all circuits except output transistors, source predriver, and low current control amplifier
14	RS			Reverse detector pin Forward rotation: High Reverse rotation: Low
15	FG			1 Hall element waveform Schmitt comparator composite output
8 7	$U_{IN1}$ $U_{IN2}$	1.2V to $V_{CC1}-1V$		U phase Hall element input and reverse detector U phase Schmitt comparator input pin Logic High indicates $U_{IN1} > U_{IN2}$ .
10 9	$V_{IN1}$ $V_{IN2}$			V phase Hall element input and reverse detector V phase Schmitt comparator input pin Logic High indicates $V_{IN1} > V_{IN2}$ .
12 11	$W_{IN1}$ $W_{IN2}$			W phase Hall element input and reverse detector W phase Schmitt comparator input pin Logic High indicates $W_{IN1} > W_{IN2}$ .
13	$V_H$			Hall element lower side bias voltage supply pin
17	S/S	0V to $V_{CC1}$		When this pin is at 0.7V or lower, or when it is open, all circuits are inactive. When driving motor, set this pin to 2V or higher.
18	SIG GND			GND pin for all circuits except output
20	FC			Control loop frequency compensator pin. Connecting a capacitor between this pin and GND prevents closed loop oscillation in current limiting circuitry.

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Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
21	$V_{CREF}$	2V to 3V		Control reference voltage supply pin. Determines control start voltage.
22	$V_C$	0V to $V_{CC1}$		Speed control voltage supply pin V type control technique $V_C > V_{CREF}$ : Forward $V_C < V_{CREF}$ : Slowdown (Reverse-blocking circuit prevents reverse rotation.)
23	$W_{OUT}$			W phase output
24	PWR GND			Output transistor GND
1	$V_{OUT}$			V phase output
2	$U_{OUT}$			U phase output
5	RF			Upper side output PNP transistor collector pin (common for all 3 phases). For current detection, connect resistor between $V_{CC3}$ pin and RF pin. Constant current control and current limiter works by detecting this voltage.
19	CC			V type control/single-side control switching pin CC: High → Single-side control Low/Open → V type control
16	BRAKE			Short brake pin BRAKE: High → Short brake operation Low/Open → Motor drive operation



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