

## Features

- Zarlink ST-BUS compatible
- 4-line x 32-channel inputs
- 4-line x 32-channel outputs
- 128 ports non-blocking switch
- Single power supply (+5 V)
- Low power consumption: 30 mW Typ.
- Microprocessor-control interface
- Three-state serial outputs

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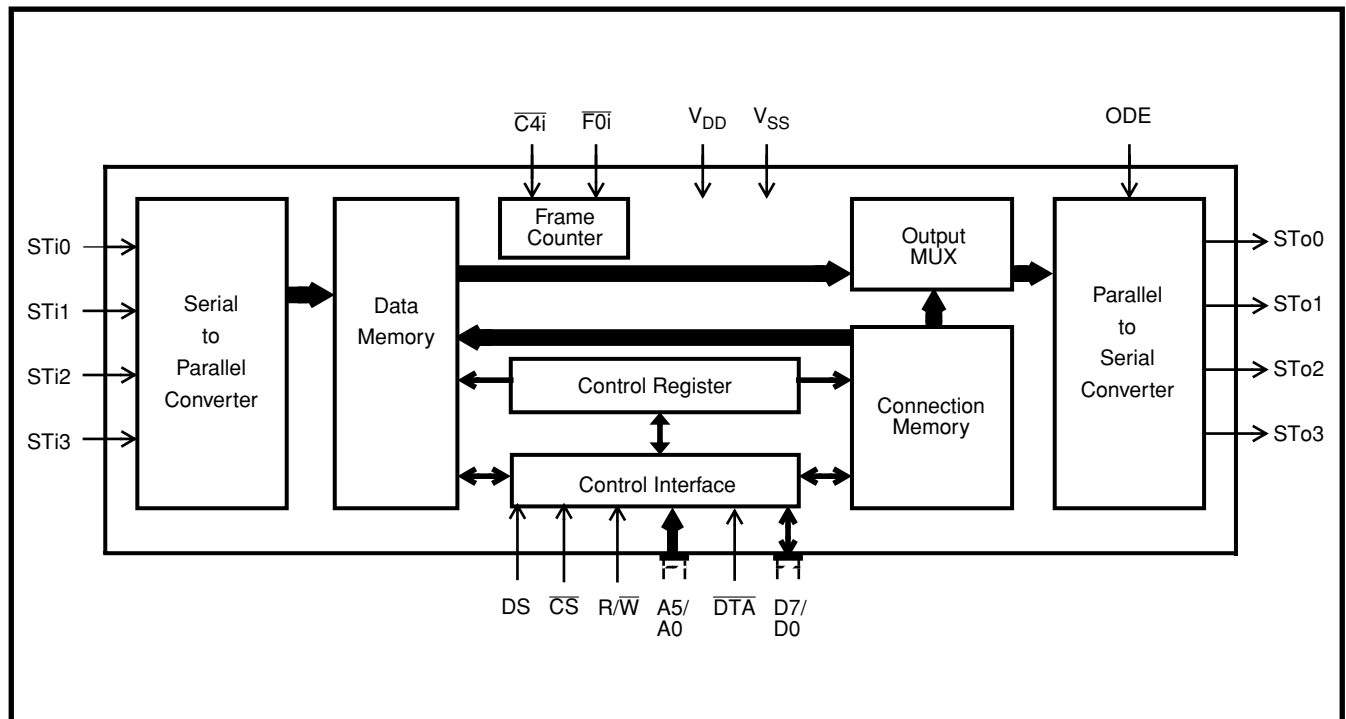
## Ordering Information

MT8981DE	40 Pin Plastic DIP
MT8981DP	44 PLCC

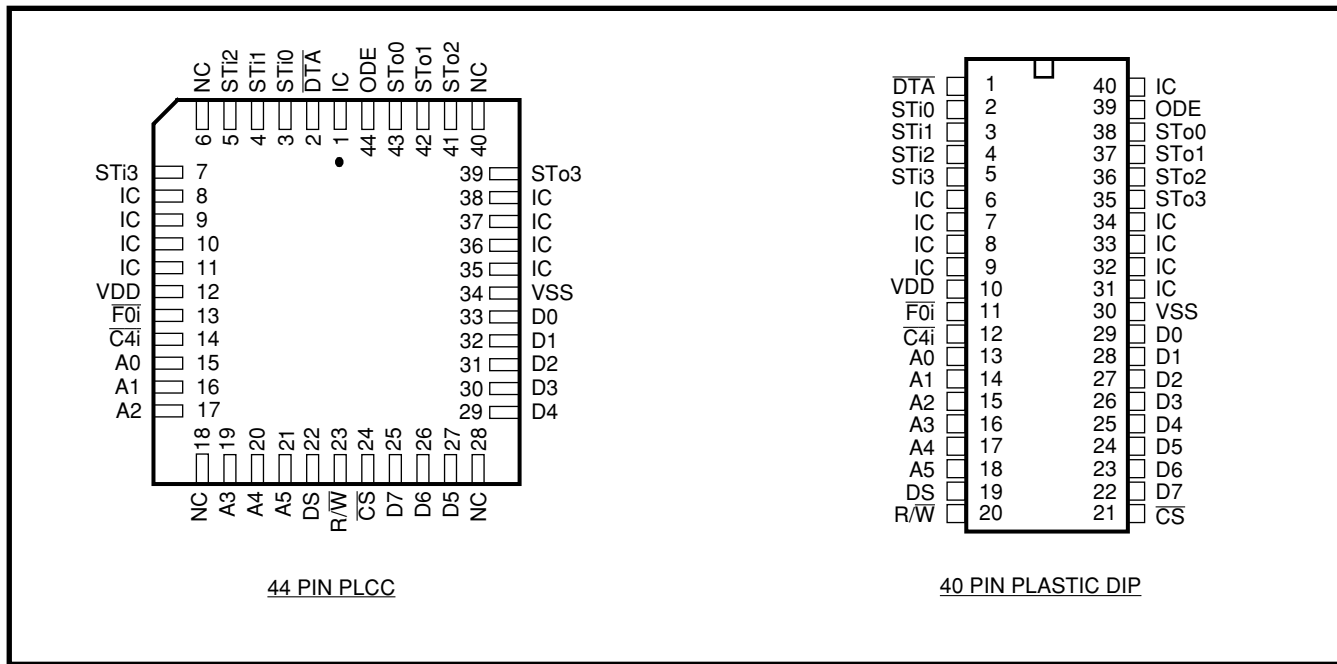
**-40°C to +85°C**

### Description

This VLSI ISO-CMOS device is designed for switching PCM-encoded voice or data, under microprocessor control, in a modern digital exchange, PBX or Central Office. It provides simultaneous connections for up to 128 64 kbit/s channels. Each of the four serial inputs and outputs consist of 32 64 kbit/s channels multiplexed to form a 2048 kbit/s ST-BUS stream. In addition, the MT8981 provides microprocessor read and write access to individual ST-BUS channels.



### Figure 1 - Functional Block Diagram


**Figure 2 - Pin Connections**

## Pin Description

Pin #		Name	Description
40 DIP	44 PLCC		
1	2	DTA	<b>Data Acknowledgement (Open Drain Output).</b> This is the data acknowledgement on the microprocessor interface. This pin is pulled low to signal that the chip has processed the data. A 909 $\Omega$ , 1/4W, resistor is recommended to be used as a pullup.
2-4	3-5	STi0-STi2	<b>ST-BUS Input 0 to 2 (Inputs).</b> These are the inputs for the 2048 kbit/s ST-BUS input streams.
5	7	STi3	<b>ST-BUS Input 3 (Input).</b> These are the inputs for the 2048 kbit/s ST-BUS input streams.
6-9	8-11	IC	<b>Internal Connections.</b> Must be connected to $V_{DD}$ .
10	12	$V_{DD}$	<b>Power Input.</b> Positive Supply.
11	13	$\overline{FOi}$	<b>Framing 0-Type (Input).</b> This is the input for the frame synchronization pulse for the 2048 kbit/s ST-BUS streams. A low on this input causes the internal counter to reset on the next negative transition of $\overline{C4i}$ .
12	14	$\overline{C4i}$	<b>4.096 MHz Clock (Input).</b> ST-BUS bit cell boundaries lie on the alternate falling edges of this clock.
13-15	15-17	A0-A2	<b>Address 0 to 2 (Inputs).</b> These are the inputs for the address lines on the microprocessor interface.
16-18	19-21	A3-A5	<b>Address 3 to 5 (Inputs).</b> These are the inputs for the address lines on the microprocessor interface.
19	22	DS	<b>Data Strobe (Input).</b> This is the input for the active high data strobe on the microprocessor interface.
20	23	R/W	<b>Read or Write (Input).</b> This is the input for the read/write signal on the microprocessor interface - high for read, low for write.
21	24	$\overline{CS}$	<b>Chip Select (Input).</b> This is the input for the active low chip select on the microprocessor interface.

**Pin Description (continued)**

Pin #		Name	Description
40 DIP	44 PLCC		
22- 24	25- 27	D7-D5	<b>Data 7 to 5 (Three-state I/O Pins).</b> These are the bidirectional data pins on the microprocessor interface.
25- 29	29- 33	D4-D0	<b>Data 4 to 0 (Three-state I/O Pins).</b> These are the bidirectional data pins on the microprocessor interface.
30	34	V <sub>SS</sub>	<b>Power Input.</b> Negative Supply (Ground).
31- 34	35- 38	IC	<b>Internal Connections.</b> Leave pins disconnected.
35	39	STo3	<b>ST-BUS Output 3 (Three-state Outputs).</b> These are the pins for the four 2048 kbit/s ST-BUS output streams.
36- 38	41- 43	STo2- STo0	<b>ST-BUS Output 2 to 0 (Three-state Outputs).</b> These are the pins for the four 2048 kbit/s ST-BUS output streams.
39	44	ODE	<b>Output Drive Enable (Input).</b> If this input is held high, the STo0-STo3 output drivers function normally. If this input is low, the STo0-STo3 output drivers go into their high impedance state. <b>NB:</b> Even when ODE is high, channels on the STo0-STo3 outputs can go high impedance under software control.
40	1	IC	<b>Internal Connection.</b> Leave pin disconnected.

## Functional Description

In recent years, there has been a trend in telephony towards digital switching, particularly in association with software control. Simultaneously, there has been a trend in system architectures towards distributed processing or multi-processor systems.

In accordance with these trends, Zarlink has devised the ST-BUS (Serial Telecom Bus). This bus architecture can be used both in software-controlled digital voice and data switching, and for interprocessor communications. The uses in switching and in interprocessor communications are completely integrated to allow for a simple general purpose architecture appropriate for the systems of the future.

The serial streams of the ST-BUS operate continuously at 2048 kbit/s and are arranged in 125  $\mu$ s wide frames which contain 32 8-bit channels. Zarlink manufactures a number of devices which interface to the ST-BUS; a key device being the MT8981 chip.

The MT8981 can switch data from channels on ST-BUS inputs to channels on ST-BUS outputs, and simultaneously allows its controlling microprocessor to read channels on ST-BUS inputs or write to channels on ST-BUS outputs (Message Mode). To the microprocessor, the MT8981 looks like a memory peripheral. The microprocessor can write to the MT8981 to establish switched connections between input ST-BUS channels and output ST-BUS channels, or to transmit messages on output ST-BUS channels. By reading from the MT8981, the microprocessor can receive messages from ST-BUS input channels or check which switched connections have already been established.

By integrating both switching and interprocessor communications, the MT8981 allows systems to use distributed processing and to switch voice or data in an ST-BUS architecture.

## Hardware Description

Serial data at 2048 kbit/s is received at the four ST-BUS inputs (STi0 to STi3), and serial data is transmitted at the four ST-BUS outputs (STo0 to STo3). Each serial input accepts 32 channels of digital data, each channel containing an 8-bit word which may represent a PCM-encoded analog/voice sample as provided by a codec (e.g., Zarlink's MT8964).

This serial input word is converted into parallel data and stored in the 128 X 8 Data Memory. Locations in the Data Memory are associated with particular channels on particular ST-BUS input streams. These locations can be read by the microprocessor which controls the chip.

Locations in the Connection Memory, which is split into high and low parts, are associated with particular ST-BUS output streams. When a channel is due to be transmitted on an ST-BUS output, the data for the channel can either be switched from an ST-BUS input or it can originate from the microprocessor. If the data is switched from an input, then the contents of the Connection Memory Low location associated with the output channel is used to address the Data Memory. This Data Memory address corresponds to the channel on the input ST-BUS stream on which the data for switching arrived. If the data for the output channel originates from the microprocessor (Message Mode), then the contents of the Connection Memory Low location associated with the output channel are output directly, and this data is output repetitively on the channel once every frame until the microprocessor intervenes.

The Connection Memory data is received, via the Control Interface, at D7 to D0. The Control Interface also receives address information at A5 to A0 and handles the microprocessor control signals  $\overline{CS}$ ,  $\overline{DTA}$ , R/W and DS. There are two parts to any address in the Data Memory or Connection Memory. The higher order bits come from the

A5	A4	A3	A2	A1	A0	HEX ADDRESS	LOCATION
0	X	X	X	X	X	00 - 1F	Control Register *
1	0	0	0	0	0	20	Channel 0 <sup>†</sup>
1	0	0	0	0	1	21	Channel 1 <sup>†</sup>
.	.	.	.	.	.	.	.
.	.	.	.	.	.	.	.
.	.	.	.	.	.	.	.
1	1	1	1	1	1	3F	Channel 31 <sup>†</sup>

\* Writing to the Control Register is the only fast transaction.  
<sup>†</sup> Memory and stream are specified by the contents of the Control Register.

**Figure 3 - Address Memory Map**

Control Register, which may be written to or read from via the Control Interface. The lower order bits come from the address lines directly.

The Control Register also allows the chip to broadcast messages on all ST-BUS outputs (i.e., to put every channel into Message Mode), or to split the memory so that reads are from the Data Memory and writes are to the Connection Memory Low. The Connection Memory High determines whether individual output channels are in Message Mode, and allows individual output channels to go into a high-impedance state, which enables arrays of MT8981s to be constructed. It also controls the CSto pin.

All ST-BUS timing is derived from the two signals  $\overline{C4i}$  and  $\overline{F0i}$ .

### Software Control

The address lines on the Control Interface give access to the Control Register directly or, depending on the contents of the Control Register, to the High or Low sections of the Connection Memory or to the Data Memory.

If address line A5 is low, then the Control Register is addressed regardless of the other address lines (see Fig. 3). If A5 is high, then the address lines A4-A0 select the memory location corresponding to channel 0-31 for the memory and stream selected in the Control Register.

The data in the Control Register consists of mode control bits, memory select bits, and stream address bits (see Fig. 4). The memory select bits allow the Connection Memory High or Low or the Data Memory to be chosen, and the stream address bits define one of the ST-BUS input or output streams.

Bit 7 of the Control Register allows split memory operation - reads are from the Data Memory and writes are to the Connection Memory Low.

The other mode control bit, bit 6, puts every output channel on every output stream into active Message Mode; i.e., the contents of the Connection Memory Low are output on the ST-BUS output streams once every frame unless the ODE pin is low. In this mode the chip behaves as if bits 2 and 0 of every Connection Memory High location were 1, regardless of the actual values.

BIT	NAME	DESCRIPTION
7	<b>Split Memory</b>	When 1, all subsequent reads are from the Data Memory and writes are to the Connection Memory Low, except when the Control Register is accessed again. When 0, the Memory Select bits specify the memory for subsequent operations. In either case, the Stream Address Bits select the subsection of the memory which is made available.
6	<b>Message Mode</b>	When 1, the contents of the Connection Memory Low are output on the Serial Output streams except when the ODE pin is low. When 0, the Connection Memory bits for each channel determine what is output.
5	<b>(unused)</b>	
4-3	<b>Memory Select Bits</b>	0-0 - Not to be used 0-1 - Data Memory (read only from the microprocessor port) 1-0 - Connection Memory Low 1-1 - Connection Memory High
2	<b>(unused)</b>	Must be a 0.
1-0	<b>Stream Address Bits</b>	The number expressed in binary notation on these bits refers to the input or output ST-BUS stream which corresponds to the subsection of memory made accessible for subsequent operations.

**Figure 4 - Control Register Bits**

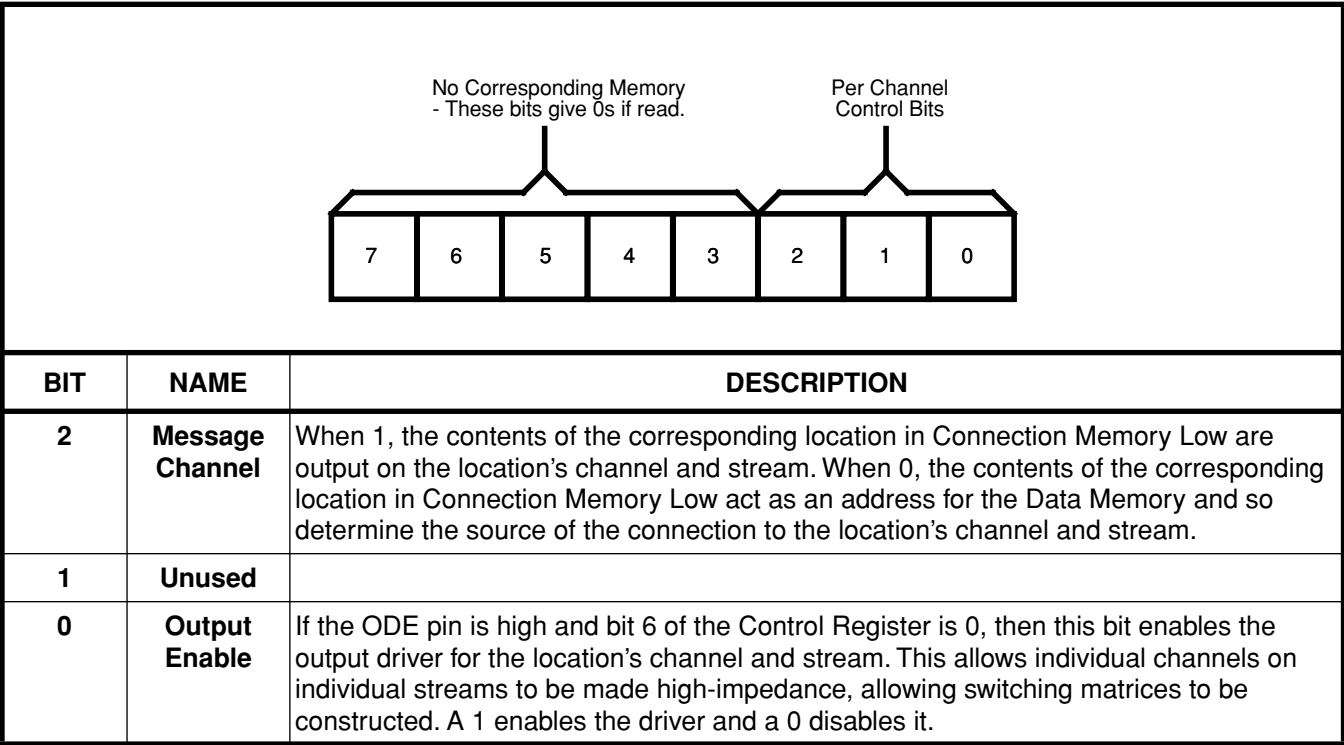


Figure 5 - Connection Memory High Bits

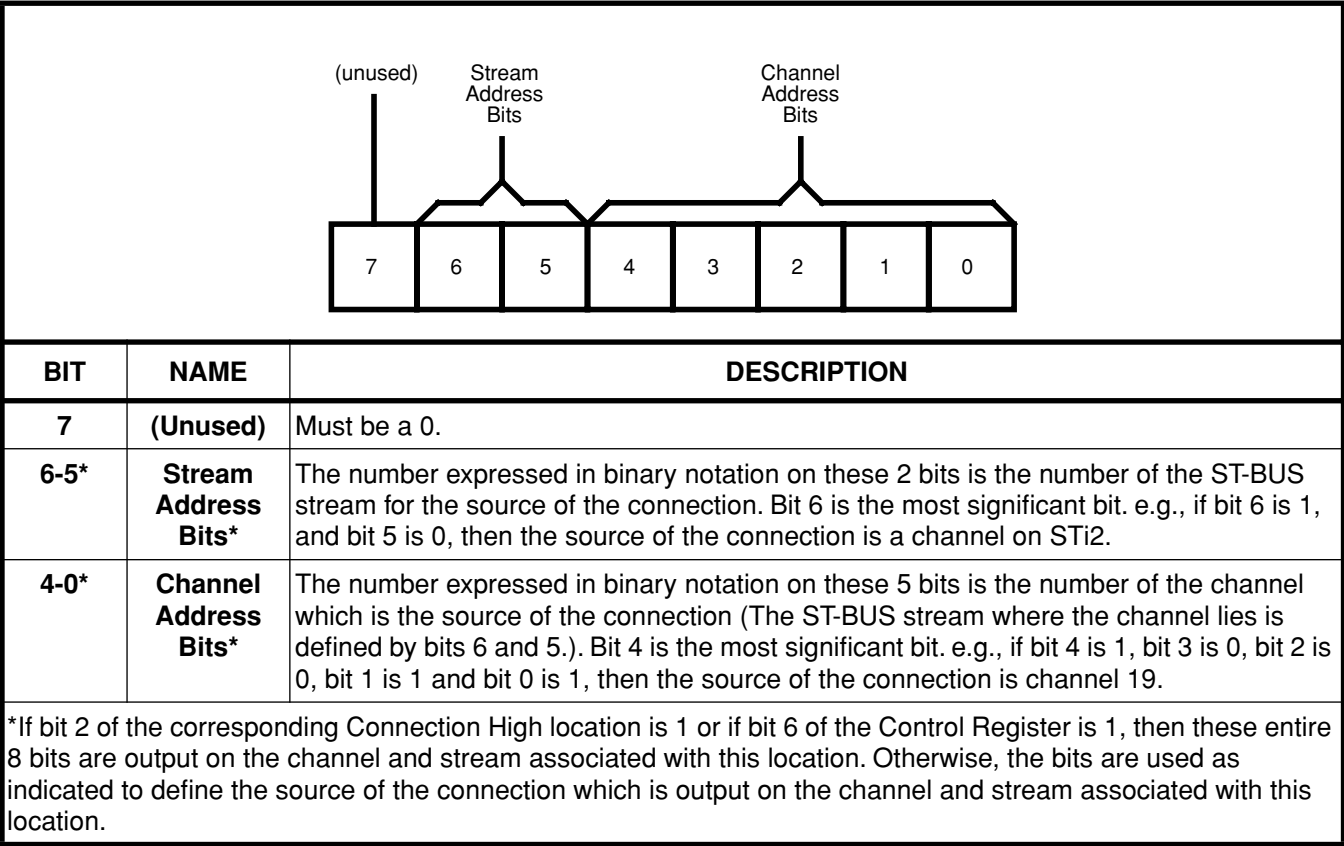


Figure 6 - Connection Memory Low Bits

If bit 6 of the Control Register is 0, then bits 2 and 0 of each Connection Memory High location function normally (see Fig. 5). If bit 2 is 1, the associated ST-BUS output channel is in Message Mode; i.e., the byte in the corresponding Connection Memory Low location is transmitted on the stream at that channel. Otherwise, one of the bytes received on the serial inputs is transmitted and the contents of the Connection Memory Low define the ST-BUS input stream and channel where the byte is to be found (see Fig. 6).

If the ODE pin is low, then all serial outputs are high-impedance. If it is high and bit 6 in the Control Register is 1, then all outputs are active. If the ODE pin is high and bit 6 in the Control Register is 0, then the bit 0 in the Connection Memory High location enables the output drivers for the corresponding individual ST-BUS output stream and channel. Bit 0=1 enables the driver and bit 0=0 disables it (see Fig. 5).

## Applications

### Use in a Simple Digital Switching System

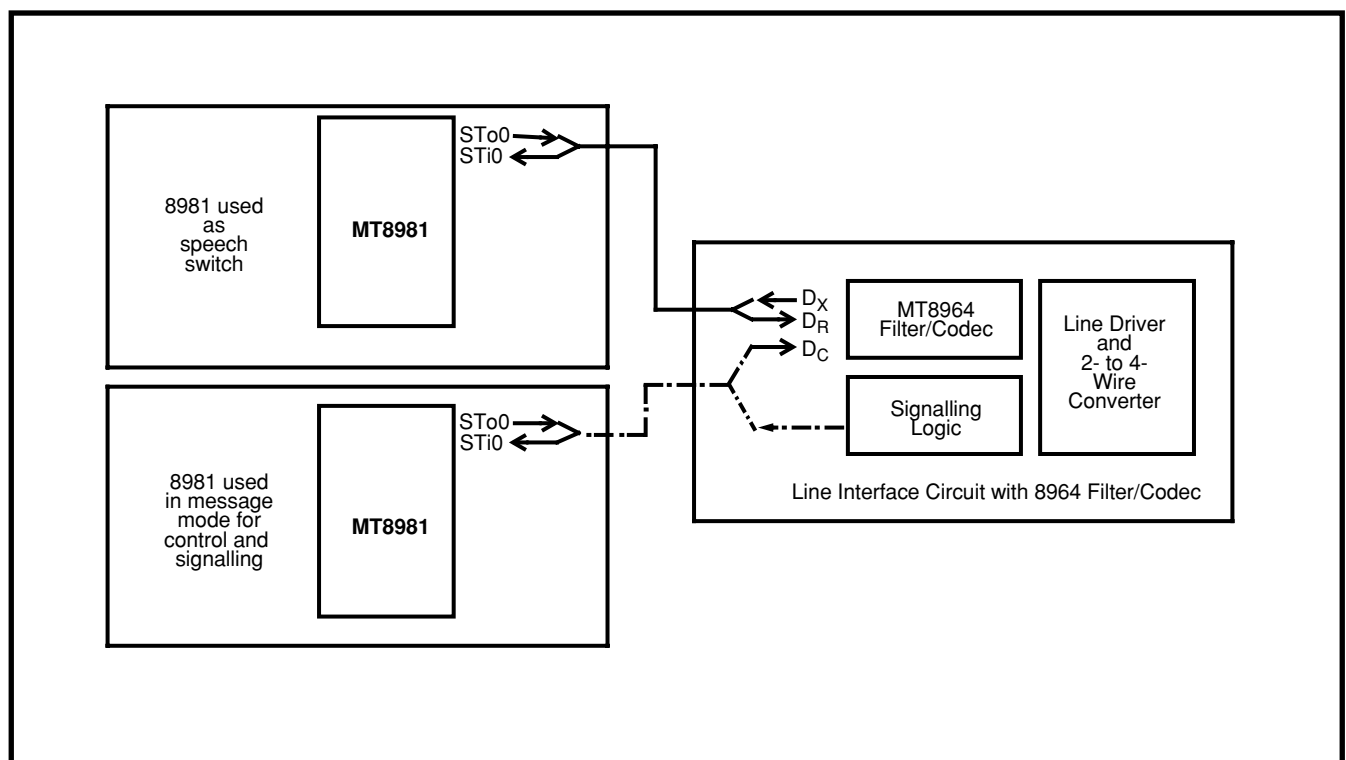
Fig. 7 and 8 show how MT8981s can be used with MT8964s to form a simple digital switching system. Fig. 7 shows the interface between the MT8981s and the filter/codecs. Fig. 8 shows the position of these components in an example architecture.

The MT8964 filter/codec in Fig. 7 receives and transmits digitised voice signals on the ST-BUS input  $D_R$ , and ST-BUS output  $D_X$ , respectively. These signals are routed to the ST-BUS inputs and outputs on the top MT8981, which is used as a digital speech switch.

The MT8964 is controlled by the ST-BUS input  $D_C$  originating from the bottom MT8981, which generates the appropriate signals from an output channel in Message Mode. This architecture optimises the messaging capability of the line circuit by building signalling logic, e.g., for on-off hook detection, which communicates on an ST-BUS output. This signalling ST-BUS output is monitored by a microprocessor (not shown) through an ST-BUS input on the bottom MT8981.

Fig. 8 shows how a simple digital switching system may be designed using the ST-BUS architecture. This is a private telephone network with 128 extensions which uses a single MT8981 as a speech switch and a second MT8981 for communication with the line interface circuits.

A larger digital switching system may be designed by cascading a number of MT8981s. Fig. 9 shows how four MT8981s may be arranged in a non-blocking configuration which can switch any channel on any of the ST-BUS inputs to any channel on the ST-BUS outputs.



**Figure 7 - Example of Typical Interface between 8981s and 8964s for Simple Digital Switching System**

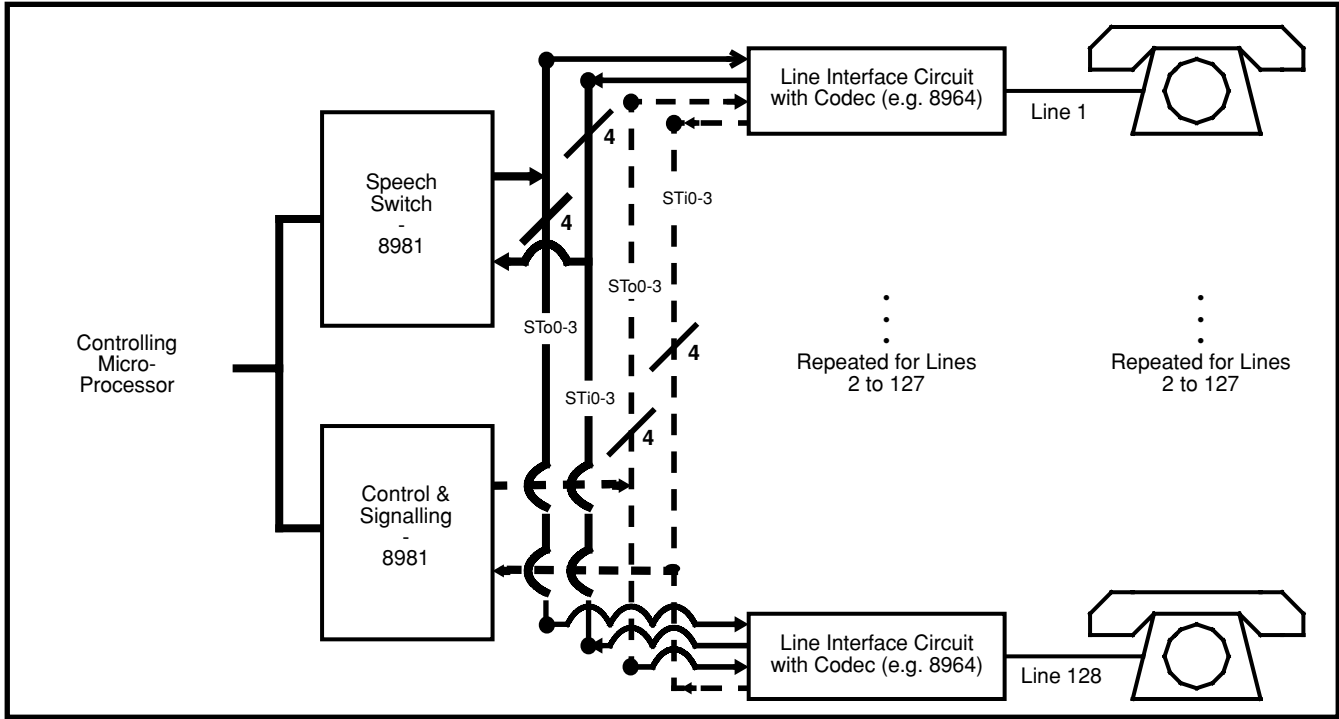


Figure 8 - Example Architecture of a Simple Digital Switching System

Application Circuit with 6802 Processor

Fig. 10 shows an example of a complete circuit which may be used to evaluate the chip.

For convenience, a 4 MHz crystal oscillator has been used rather than a 4.096 MHz clock, as both are within the limits of the chip's specifications. The RC delay used with the 393 counters ensures a sufficient hold time for the  $\overline{FP}$  signal, but the values used may have to be changed if faster 393 counters become available.

The chip is shown as memory mapped into the MEK6802D3 system. Chip addresses 00-3F correspond to processor addresses 2000-203F. Delay through the address decoder requires the VMA signal to be used twice to remove glitches. The MEK6802D3 board uses a 10K $\Omega$  pullup on the MR pin, which would have to be incorporated into the circuit if the board was replaced by a processor.

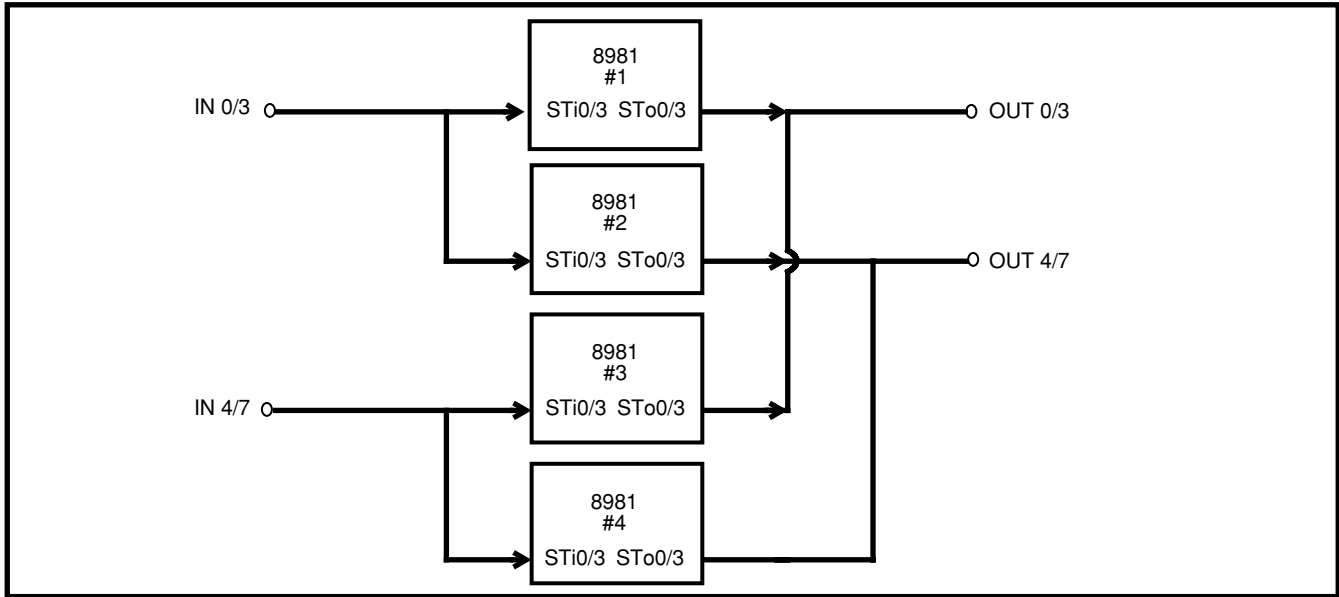


Figure 9 - Four 8981s Arranged in a Non-Blocking 8 x 8 Configuration



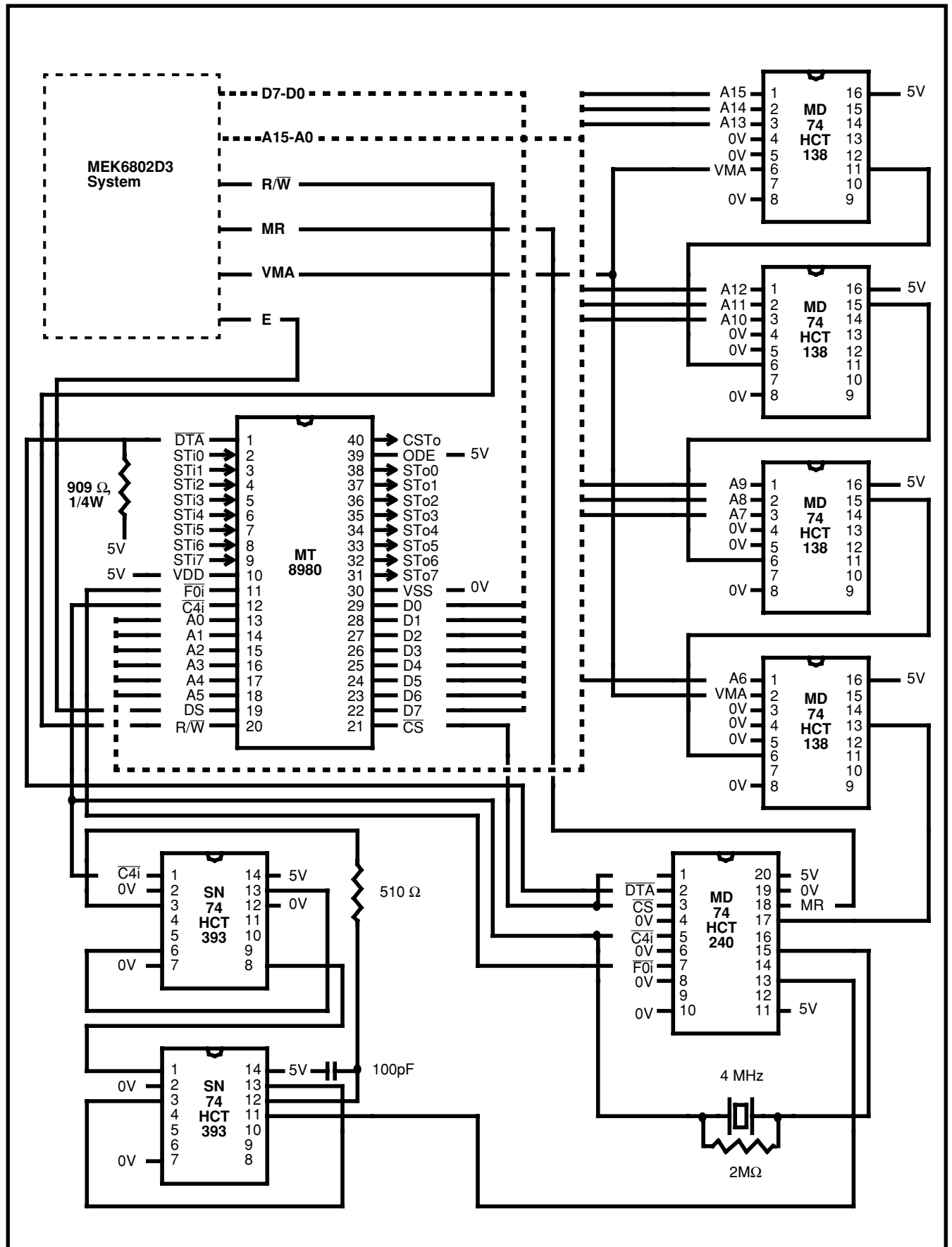


Figure 10 - Application Circuit with 6802

## Absolute Maximum Ratings\*

	Parameter	Symbol	Min	Max	Units
1	$V_{DD} - V_{SS}$		-0.3	7	V
2	Voltage on Digital Inputs	$V_I$	$V_{SS}-0.3$	$V_{DD}+0.3$	V
3	Voltage on Digital Outputs	$V_O$	$V_{SS}-0.3$	$V_{DD}+0.3$	V
4	Current at Digital Outputs	$I_O$		40	mA
5	Storage Temperature	$T_S$	-65	+150	°C
6	Package Power Dissipation	$P_D$		2	W

\* Exceeding these values may cause permanent damage. Functional operation under these conditions is not implied.

## Recommended Operating Conditions - Voltages are with respect to ground ( $V_{SS}$ ) unless otherwise stated.

	Characteristics	Sym	Min	Typ <sup>‡</sup>	Max	Units	Test Conditions
1	Operating Temperature	$T_{OP}$	-40		+85	°C	
2	Positive Supply	$V_{DD}$	4.75		5.25	V	
3	Input Voltage	$V_I$	0		$V_{DD}$	V	

‡ Typical figures are at 25°C and are for design aid only: not guaranteed and not subject to production testing.

## DC Electrical Characteristics - Voltages are with respect to ground ( $V_{SS}$ ) unless otherwise stated.

	Characteristics	Sym	Min	Typ <sup>‡</sup>	Max	Units	Test Conditions
1	INPUTS	Supply Current	$I_{DD}$	6	10	mA	Outputs unloaded
2		Input High Voltage	$V_{IH}$	2.0		V	
3		Input Low Voltage	$V_{IL}$		0.8	V	
4		Input Leakage	$I_{IL}$		5	μA	$V_I$ between $V_{SS}$ and $V_{DD}$
5		Input Pin Capacitance	$C_I$	8		pF	
6	OUTPUTS	Output High Voltage	$V_{OH}$	2.4		V	$I_{OH} = 10$ mA
7		Output High Current	$I_{OH}$	10	15	mA	Sourcing. $V_{OH}=2.4$ V
8		Output Low Voltage	$V_{OL}$		0.4	V	$I_{OL} = 5$ mA
9		Output Low Current	$I_{OL}$	5	10	mA	Sinking. $V_{OL} = 0.4$ V
10		High Impedance Leakage	$I_{OZ}$		5	μA	$V_O$ between $V_{SS}$ and $V_{DD}$
11		Output Pin Capacitance	$C_O$	8		pF	

‡ Typical figures are at 25°C and are for design aid only: not guaranteed and not subject to production testing.

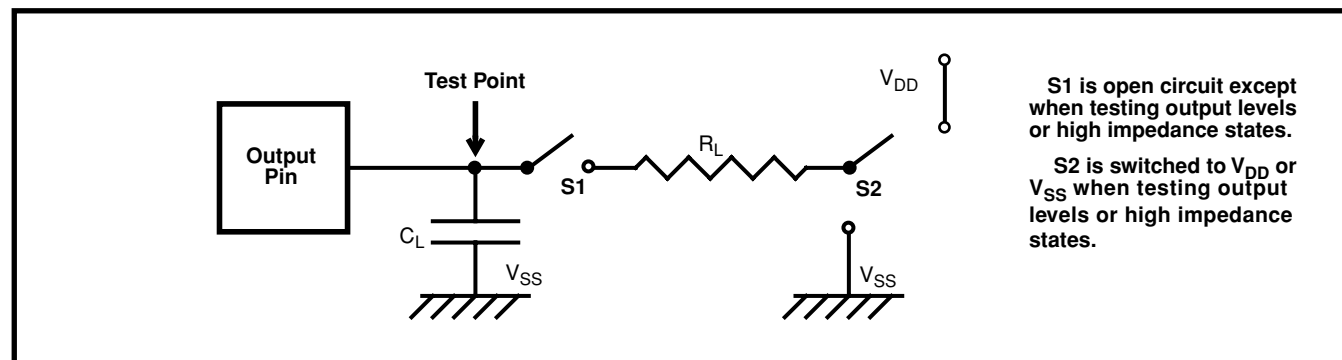


Figure 11 - Output Test Load

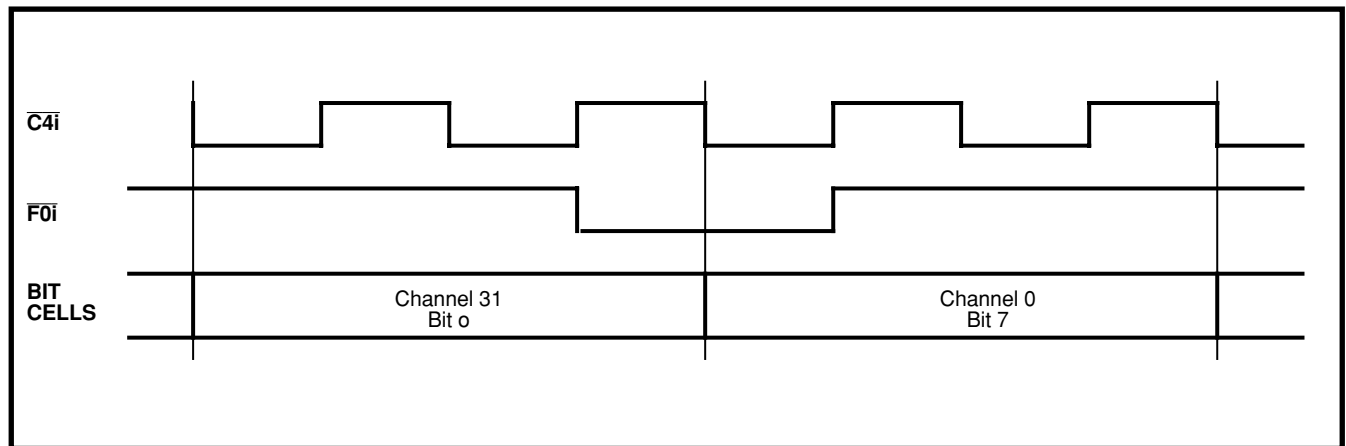
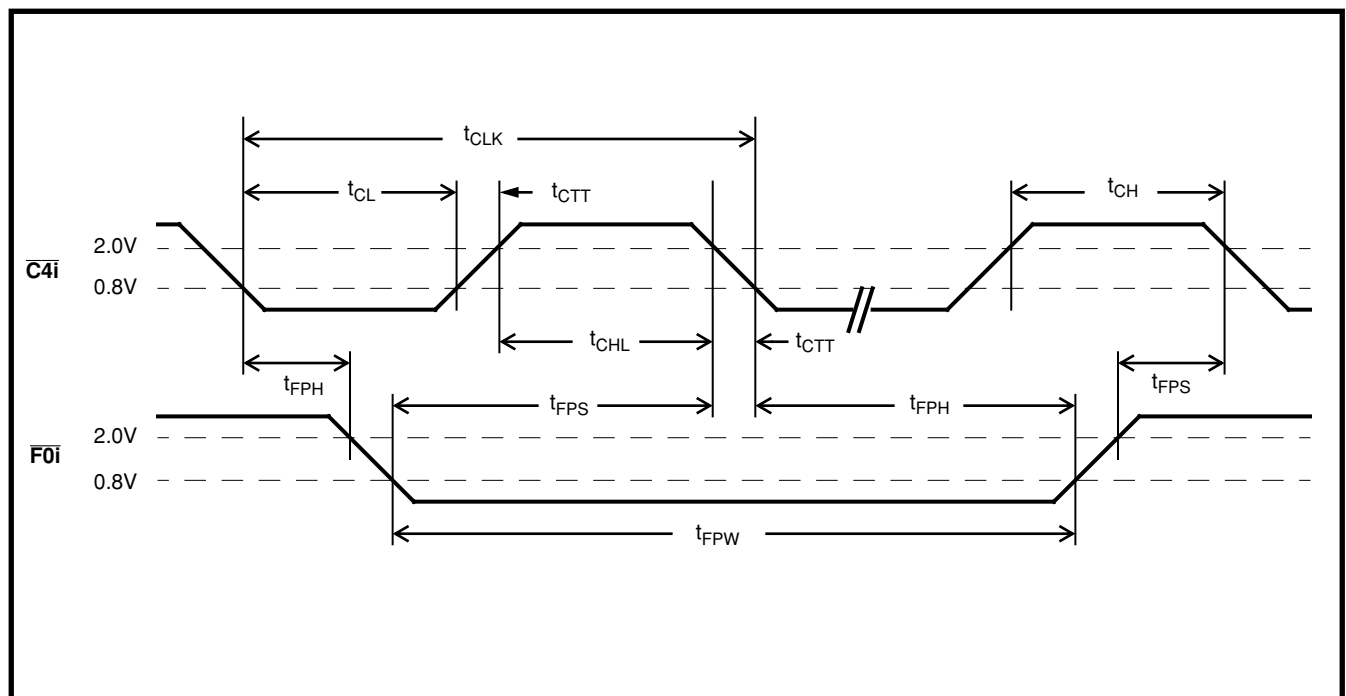
**AC Electrical Characteristics† - Clock Timing (Figures 12 and 13)**

		Characteristics	Sym	Min	Typ‡	Max	Units	Test Conditions
1	I N P U T S	Clock Period*	$t_{CLK}$	220	244	300	ns	
2		Clock Width High	$t_{CH}$	95	122	150	ns	
3		Clock Width Low	$t_{CL}$	110	122	150	ns	
4		Clock Transition Time	$t_{CTT}$		20		ns	
5		Frame Pulse SetupTime	$t_{FPS}$	20		200	ns	
6		Frame Pulse Hold Time	$t_{FPH}$	0.020		50	$\mu s$	
7		Frame Pulse Width	$t_{FPW}$		244		ns	

† Timing is over recommended temperature &amp; power supply voltages

‡ Typical figures are at 25°C and are for design aid only: not guaranteed and not subject to production testing.

\* Contents of Connection Memory are not lost if the clock stops, however, ST-BUS outputs go into the high impedance state.

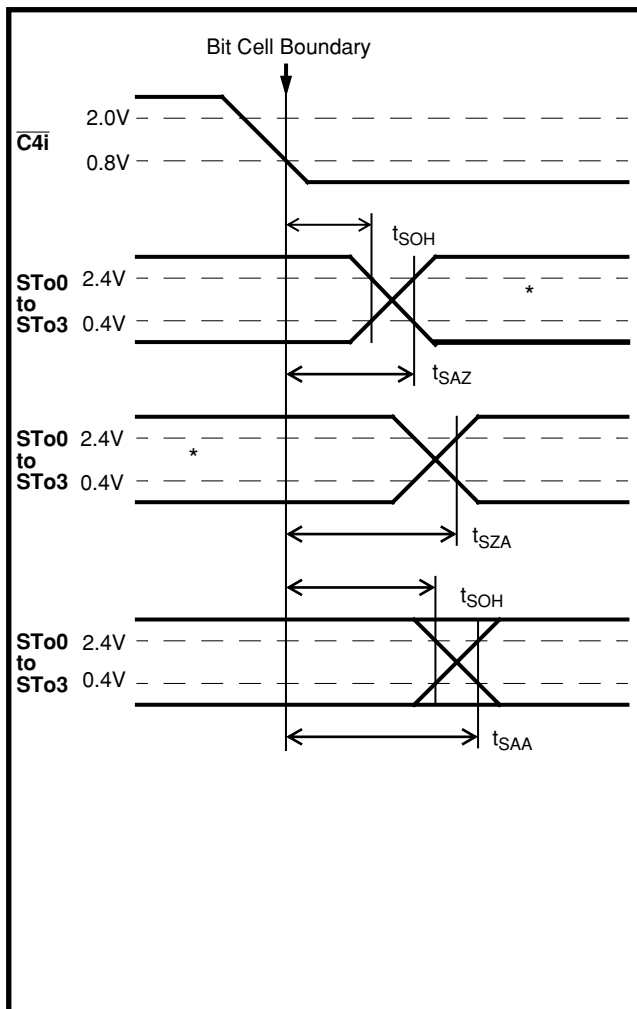
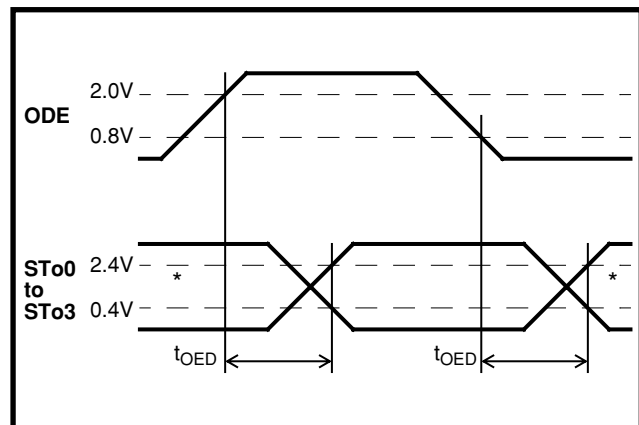
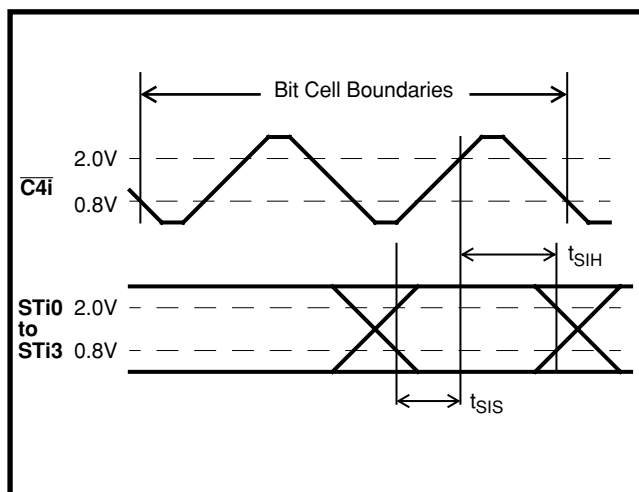
**NB:** Frame Pulse is repeated every 512 cycles of  $\overline{C4i}$ .**Figure 12 - Frame Alignment****Figure 13 - Clock Timing**

**AC Electrical Characteristics<sup>†</sup> - Serial Streams (Figures 11, 14, 15 and 16)**

		Characteristics	Sym	Min	Typ <sup>‡</sup>	Max	Units	Test Conditions
1	O U T P U T S	STo0/3 Delay - Active to High Z	$t_{SAZ}$	20	50	80	ns	$R_L=1\text{ K}\Omega^*$ , $C_L=150\text{ pF}$
2		STo0/3 Delay - High Z to Active	$t_{SZA}$	25	60	125	ns	$C_L=150\text{ pF}$
3		STo0/3 Delay - Active to Active	$t_{SAA}$	30	65	125	ns	$C_L=150\text{ pF}$
4		STo0/3 Hold Time	$t_{SOH}$	25	45		ns	$C_L=150\text{ pF}$
5		Output Driver Enable Delay	$t_{OED}$		45	125	ns	$R_L=1\text{ K}\Omega^*$ , $C_L=150\text{ pF}$
6		External Control Hold Time	$t_{XCH}$	0	50		ns	$C_L=150\text{ pF}$
7		External Control Delay	$t_{XCD}$		75	110	ns	$C_L=150\text{ pF}$
8	I N	Serial Input Setup Time	$t_{SIS}$		-40	-20	ns	
9		Serial Input Hold Time	$t_{SIH}$	90			ns	

<sup>†</sup> Timing is over recommended temperature & power supply voltages

<sup>‡</sup> Typical figures are at 25°C and are for design aid only: not guaranteed and not subject to production testing.

<sup>\*</sup> High Impedance is measured by pulling to the appropriate rail with  $R_L$ , with timing corrected to cancel time taken to discharge  $C_L$ .

**Figure 14 - Serial Outputs and External Control**

**Figure 15 - Output Driver Enable**

**Figure 16 - Serial Inputs**

**AC Electrical Characteristics<sup>†</sup> - Processor Bus (Figures 11 and 17)**

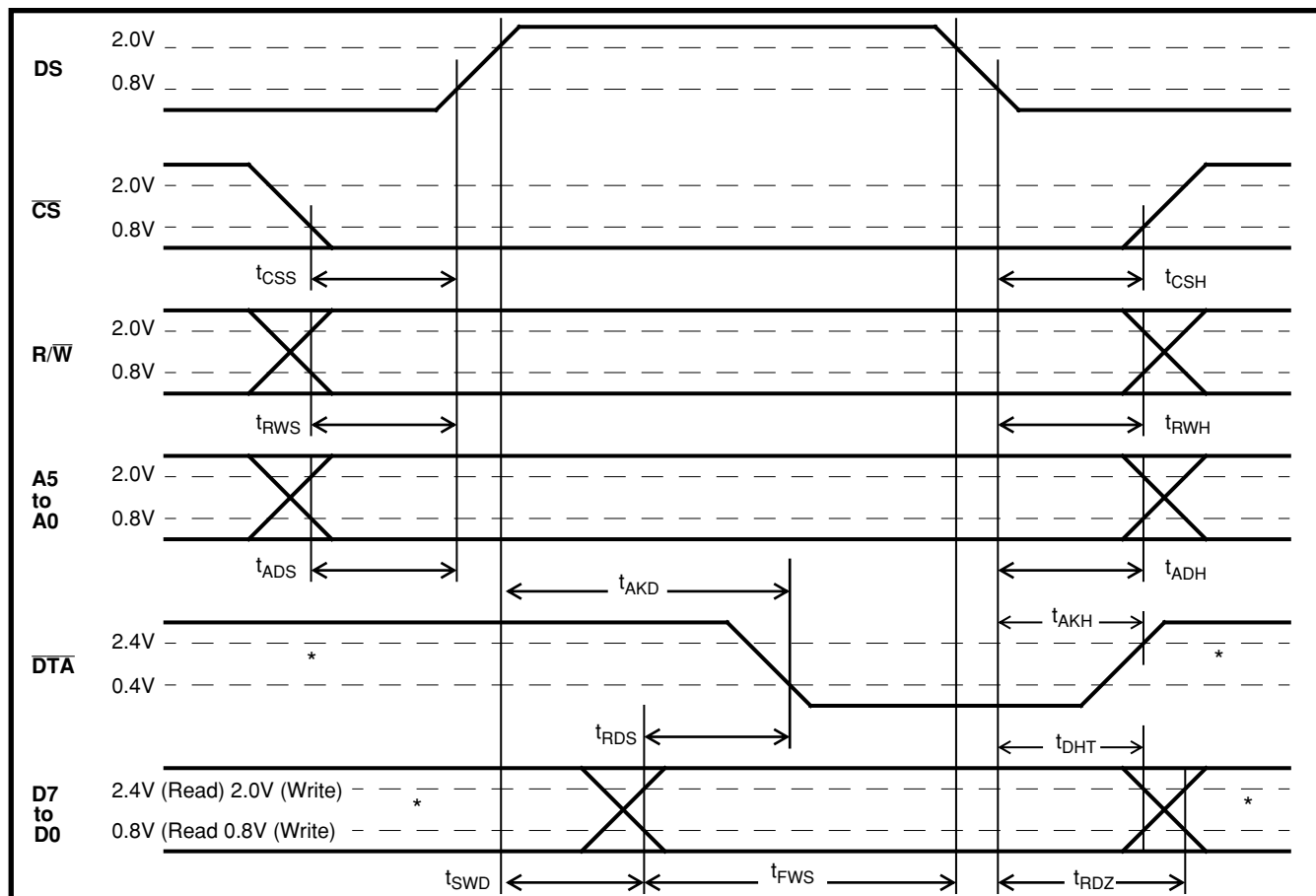
	Characteristics	Sym	Min	Typ <sup>‡</sup>	Max	Units	Test Conditions
1	Chip Select Setup Time	$t_{CSS}$	20	0		ns	
2	Read/Write Setup Time	$t_{RWS}$	25	5		ns	
3	Address Setup Time	$t_{ADS}$	25	5		ns	
4	Acknowledgement Delay Fast Slow	$t_{AKD}$		40	100	ns	$C_L=150$ pF
		$t_{AKD}$	2.7		7.2	cycles	$\overline{C4i}$ cycles <sup>①</sup>
5	Fast Write Data Setup Time	$t_{FWS}$	20			ns	
6	Slow Write Data Delay	$t_{SWD}$		2.0	1.7	cycles	$\overline{C4i}$ cycles <sup>①</sup>
7	Read Data Setup Time	$t_{RDS}$			0.5	cycles	$\overline{C4i}$ cycles <sup>①</sup> , $C_L=150$ pF
8	Data Hold Time Read Write	$t_{DHT}$	20			ns	$R_L=1$ K $\Omega^*$ , $C_L=150$ pF
		$t_{DHT}$	20	10		ns	
9	Read Data To High Impedance	$t_{RDZ}$		50	90	ns	$R_L=1$ K $\Omega^*$ , $C_L=150$ pF
10	Chip Select Hold Time	$t_{CSH}$	0			ns	
11	Read/Write Hold Time	$t_{RWH}$	0			ns	
12	Address Hold Time	$t_{ADH}$	0			ns	
13	Acknowledgement Hold Time	$t_{AKH}$	10	60	80	ns	$R_L=1$ K $\Omega^*$ , $C_L=150$ pF

<sup>†</sup> Timing is over recommended temperature & power supply voltages.

<sup>‡</sup> Typical figures are at 25°C and are for design aid only: not guaranteed and not subject to production testing.

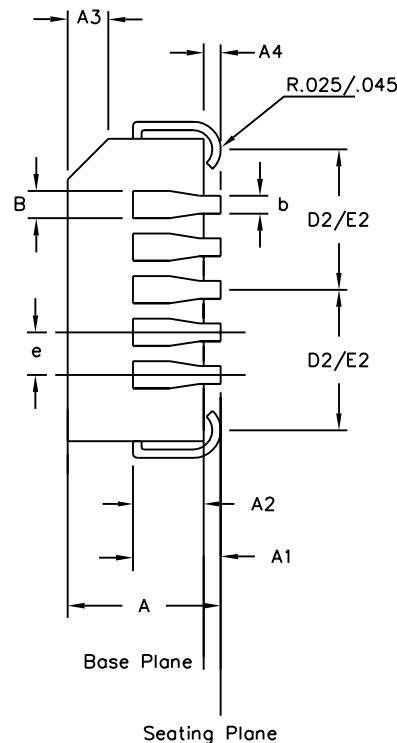
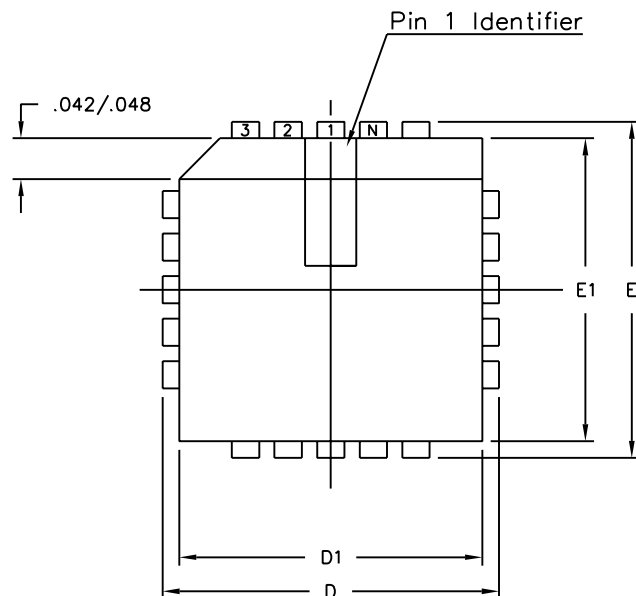
\* High Impedance is measured by pulling to the appropriate rail with  $R_L$ , with timing corrected to cancel time taken to discharge  $C_L$ .

① Processor accesses are dependent on the  $\overline{C4i}$  clock, and so some timings are expressed as multiples of the  $\overline{C4i}$  clock period.



**Figure 17 - Processor Bus**

**Notes:**



Symbol	Control Dimensions in inches		Altern. Dimensions in millimetres	
	MIN	MAX	MIN	MAX
A	0.165	0.180	4.19	4.57
A1	0.090	0.120	2.29	3.05
A2	0.062	0.083	1.57	2.11
A3	0.042	0.056	1.07	1.42
A4	0.020	—	0.51	—
D	0.685	0.695	17.40	17.65
D1	0.650	0.656	16.51	16.66
D2	0.291	0.319	7.39	8.10
E	0.685	0.695	17.40	17.65
E1	0.650	0.656	16.51	16.66
E2	0.291	0.319	7.39	8.10
B	0.026	0.032	0.66	0.81
b	0.013	0.021	0.33	0.53
e	0.050	BSC	1.27	BSC
	Pin features			
ND	11			
NE	11			
N	44			
Note	Square			
Conforms to JEDEC MS-018AC Iss. A				

#### Notes:

1. All dimensions and tolerances conform to ANSI Y14.5M-1982
2. Dimensions D1 and E1 do not include mould protrusions. Allowable mould protrusion is 0.010" per side. Dimensions D1 and E1 include mould protrusion mismatch and are determined at the parting line, that is D1 and E1 are measured at the extreme material condition at the upper or lower parting line.
3. Controlling dimensions in Inches.
4. "N" is the number of terminals.
5. Not To Scale
6. Dimension R required for 120° minimum bend.

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DATE	15Aug94	10Sep99	15Jul02	
APPRD.				



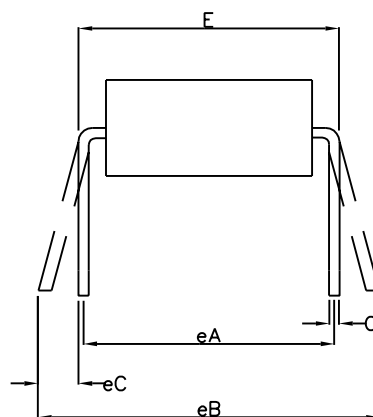
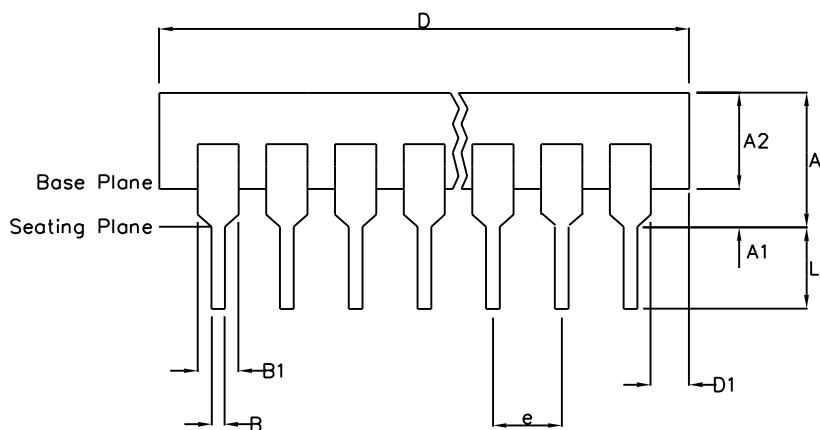
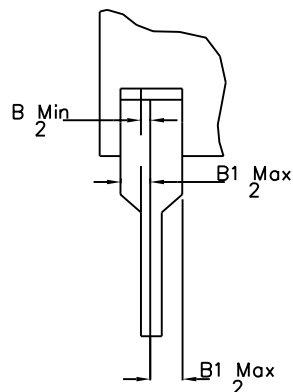
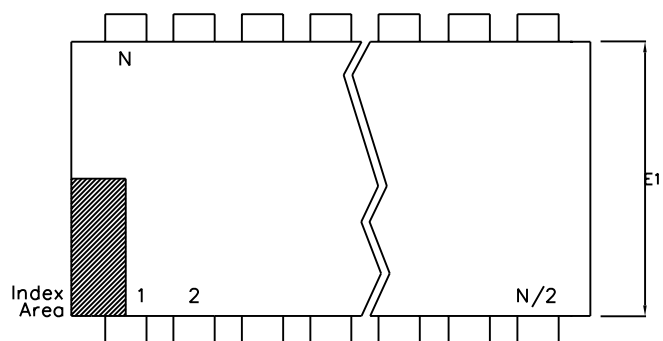
Previous package codes

HP / P

Package Code QA

Package Outline for  
44 lead PLCC


GPD000003



	Min mm	Max mm	Min Inches	Max Inches
A		6.35		0.250
A1	0.38		0.015	
A2	3.18	4.95	0.125	0.195
B	0.36	0.56	0.014	0.022
B1	0.76	1.78	0.030	0.070
C	0.20	0.38	0.008	0.015
D	50.29	53.21	1.980	2.095
D1	0.13		0.005	
E	15.24	15.88	0.600	0.625
E1	12.32	14.73	0.485	0.580
e	2.54 BSC		0.100 BSC	
eA	15.24 BSC		0.600 BSC	
eB		17.78		0.700
L	2.92	5.08	0.115	0.200
N	40		40	
Conforms to Jedec MS-011AC ISS.B				

#### Notes:

1. Controlling Dimensions are in inches
2. Dimension A, A1 and L are measured with the package seated in the Seating Plane
3. Dimensions D & E1 do not include mould flash or protrusions. Mould flash or protrusion shall not exceed 0.010 inch.
4. Dimensions E & eA are measured with leads constrained to be perpendicular to plane T.
5. Dimensions eB & eC are measured at the lead tips with the leads unconstrained; eC must be zero or greater.

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ISSUE	1	2	3		Previous package codes	Package Outline for 40 lead PDIP
ACN	7010	203533	213103		DP / E	
DATE	20Apr95	25Nov97	15Jul02			GPD000073
APPRD.						





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